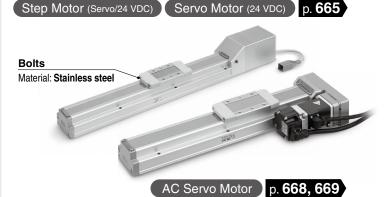
## Environment Secondary Battery Compatible

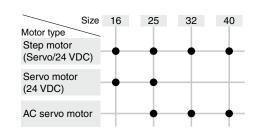
- Copper (Cu) and zinc (Zn) free\*1
  \*1 Excludes motors, cables, controllers/drivers
- Compatible with dew points as low as -70°C

Uses grease compatible with low dew points

#### Slider Type

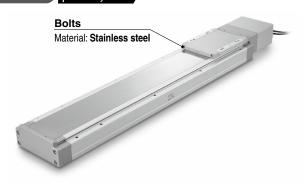
#### **Ball Screw Drive/25A-LEFS**

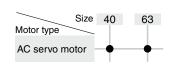




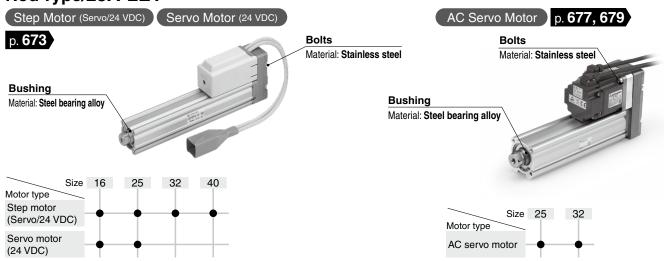
### **High Rigidity Slider Type Ball Screw Drive/25A-LEJS**

AC Servo Motor p. **671, 672** 





### Rod Type/25A-LEY



\* Copper and zinc materials are used for the motors, cables, controllers/drivers.



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LEY-X5 11-LEFS

11-LEJS

Motorless | LECY□ | LECS□-T

LAT3

## **Electric Actuator/Slider Type**

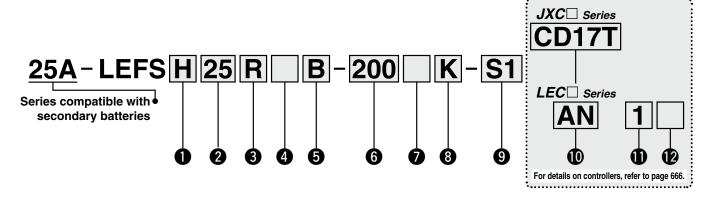
Ball Screw Drive Secondary Battery Compatible

**25A-LEFS Series** LEFS16, 25, 32, 40

(RoHS)

Refer to page 31 for model selection.

**How to Order** 



#### Accuracy

	•
Nil	Basic type
Н	High-precision type

#### 2 Size 16 32

40

#### 3 Motor mounting position

Nil	In-line
R	Right side parallel
L	Left side parallel

#### 4 Motor type

Cumbal	Timo	Applicable size				Compatible	
Symbol	Туре	LEFS16	LEFS25	LEFS32	LEFS40	controlle	rs/drivers
Nil	Step motor (Servo/24 VDC)	•	•	•	•	JXCE1 JXC91 JXCP1 JXCD1 JXCL1 JXCM1 JXC51 JXC61	LECP1 LECPA
A	Servo motor (24 VDC)	•	•	_	_	LEC	CA6

#### A Lead [mm]

Caa [min]							
Symbol	LEFS16	LEFS25	LEFS32	LEFS40			
Α	10	12	16	20			
В		6	0	10			

#### 6 Stroke\*1 [mm]

Stroke		Note
Stroke	Size	Applicable stroke
50 to 500	16	50, 100, 150, 200, 250, 300, 350, 400, 450, 500
50 to 600	25	50, 100, 150, 200, 250, 300, 350, 400, 450, 500, 550, 600
50 to 800	32	50, 100, 150, 200, 250, 300, 350, 400, 450, 500, 550, 600, 650, 700, 750, 800
150 to 1000	40	150, 200, 250, 300, 350, 400, 450, 500, 550, 600, 650, 700, 750, 800, 850, 900, 950, 1000

#### **Motor option**

_	
Nil	Without option
В	With lock

#### Positioning pin hole

• · · · · · · · · · · · · · · · · · · ·						
Nil	Housing B bottom* <sup>2</sup>	Housing B bottom				
K	Body bottom 2 locations	Body bottom				

#### Actuator cable type/length\*4

•	• riotaator camie typeriong							
Standard of	cable [m]		Roboti	c cable	!	[m]		
Nil	None		<b>R1</b> 1.5 <b>R</b> 4			10*3		
S1	1.5*6		R3	3	RB	15* <sup>3</sup>		
S3	3*6		R5	5	RC	20*3		
S5	5* <sup>6</sup>		R8	8*3				

#### Support Guide/LEFG Series

The support guide was designed to support workpieces with significant overhang.



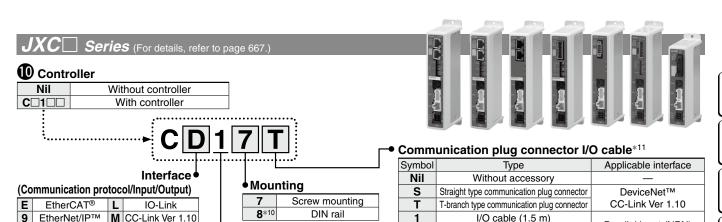
For auto switches, refer to pages 161 to 164.

I/O cable (3 m)

I/O cable (5 m)

Parallel input (NPN)

Parallel input (PNP)



1

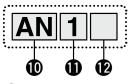
3

5

**Series** (For details, refer to page 667.)

5 Parallel input (NPN)

6 Parallel input (PNP)



**PROFINET** 

DeviceNet™

#### Controller/Driver type\*5

<u> </u>					
Nil	Without controller/driver				
6N	LECA6	NPN			
6P	(Step data input type)	PNP			
1N	LECP1*6	NPN			
1P	(Programless type)	PNP			
AN	LECPA*6 *7	NPN			
AP	(Pulse input type)	PNP			

#### I/O cable length\*8

For single axis

Nil	Without cable (Without communication plug connector)					
1	1.5 m					
3	3 m* <sup>9</sup>					
5	5 m* <sup>9</sup>					

#### (2) Controller/Driver mounting

Nil	Screw mounting
D	DIN rail*10

- \*1 Please consult with SMC for non-standard strokes as they are produced as special orders.
- \*2 Refer to the body mounting example on page 166 for the mounting method.
- \*3 Produced upon receipt of order (Robotic cable only)
- \*4 The standard cable should only be used on fixed parts. For use on moving parts, select the robotic cable. Refer to pages 758 and 759 if only the actuator cable is required.
- \*5 For details on controllers/drivers and compatible motors, refer to the compatible controllers/drivers on the next page.
- \*6 Only available for the motor type "Step motor"
- \*7 When pulse signals are open collector, order the current limiting resistor (LEC-PA-R-□) on page 736 separately.
- \*8 When "Without controller/driver" is selected for controller/driver types. I/O cable cannot be selected. Refer to page 713 (For LECA6), page 724 (For LECP1), or page 736 (For LECPA) if I/O cable is required.
- \*9 When "Pulse input type" is selected for controller/driver types, pulse input usable only with differential. Only 1.5 m cables usable with open collector
- \*10 The DIN rail is not included. It must be ordered separately.
- \*11 Select "Nil" for anything other than DeviceNet™, CC-Link, or parallel input.
  - Select "Nil," "S," or "T" for DeviceNet™ or CC-Link. Select "Nil," "1," "3," or "5" for parallel input.

#### **⚠** Caution

#### [CE-compliant products]

- 1) EMC compliance was tested by combining the electric actuator LEF series and the controller LEC/JXC series.
  - The EMC depends on the configuration of the customer's control panel and the relationship with other electrical equipment and wiring. Therefore, compliance with the EMC directive cannot be certified for SMC components incorporated into the customer's equipment under actual operating conditions. As a result, it is necessary for the customer to verify compliance with the EMC directive for the machinery and equipment as a whole.
- 2 For the servo motor (24 VDC) specification, EMC compliance was tested by installing a noise filter set (LEC-NFA). Refer to page 713 for the noise filter set. Refer to the LECA series Operation Manual for installation.

#### [UL-compliant products (For the LEC series)]

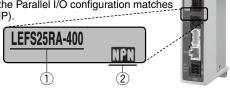
When compliance with UL is required, the electric actuator and controller/ driver should be used with a UL1310 Class 2 power supply.

#### The actuator and controller/driver are sold as a package.

Confirm that the combination of the controller/driver and actuator is correct.

#### <Check the following before use.>

- 1) Check the actuator label for the model number (after "25A-"). This number should match that of the controller/driver.
- 2 Check that the Parallel I/O configuration matches (NPN or PNP).



Refer to the Operation Manual for using the products. Please download it via our website: https://www.smcworld.com

LEJB LEJB

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LEPY LEPS

LEB

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LEY-X5 11-LEFS

11-LEJS 25A-

CXC

Motorless

LAT3

#### **Compatible Controllers/Drivers**

Туре	EtherCAT® direct input type	EtherNet/IP™ direct input type	PROFINET direct input type	DeviceNet™ direct input type	IO-Link direct input type	CC-Link direct input type	
Series	JXCE1	JXC91	JXCP1	JXCD1	JXCL1	JXCM1	
Features	EtherCAT® direct input	EtherNet/IP™ direct input	PROFINET direct input	DeviceNet™ direct input	IO-Link direct input	CC-Link direct input	
Compatible motor	Step motor (Servo/24 VDC)						
Max. number of step data			64 p	oints			
Power supply voltage		24 VDC					
Reference page		741					

Type		Step data input type	Programless type	Pulse input type
		O MO STATE OF THE PARTY OF THE		
Series	JXC51 JXC61	LECA6	LECP1	LECPA
Features	Parallel I/O	Value (Step data) input Standard controller	Capable of setting up operation (step data) without using a PC or teaching box	Operation by pulse signals
Compatible motor	Step motor (Servo/24 VDC)	Servo motor (24 VDC)	Step motor (Servo/24 VDC)	
Max. number of step data	64 p	oints	14 points	_
Power supply voltage		24 \	/DC	
Reference page	706-1	707	719	731

## **Electric Actuator/Slider Type**

Ball Screw Drive Secondary Battery Compatible

25A-LEFS Series LEFS25, 32, 40

Refer to page 39 for model selection.

LECY□ Series p. 669

**How to Order** 



LEFS LEFB

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EB

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LEY-X5

11-LEFS

11-LEJS

LECY

25A-LEFS	H	32	R	<b>S</b> 3	B-	200	K	2	<b>A2</b>	
Series compatible with										

secondary batteries

Basic type
gh-precision type

<b>2</b> Si	ze
25	
32	
40	

	otor mounting
Nii	In line

Nil	In-line
R	Right side parallel
L	Left side parallel

nm]

Symbol	25A- LEFS25	25A- LEFS32	25A- LEFS40
Α	12	16	20
В	6	8	10

Otroke [mm]				U IVIO	toi op			
	<b>50</b> 50			Nil	Withou			
	to to			В	With			
	1000	1000						
	* For details, refer to the applicable stroke table below.							

Motor option					
Nil	Without option				
В	With lock				

Motor type

U IVI	otor type				
Symbol	Type	Output [W]	Actuator size	Compatible drivers	UL-compliant
S2*1	AC servo motor	100	25	LECSA□-S1	
S3	(Incremental	200	32	LECSA□-S3	•
S4	encoder)	400	40	LECSA2-S4	•
<b>S6</b> *1		100	25	LECSB□-S5 LECSC□-S5 LECSS□-S5	
<b>S7</b>	AC servo motor (Absolute encoder)	200	32	LECSB□-S7 LECSC□-S7 LECSS□-S7	
S8		400	40	LECSB2-S8 LECSC2-S8 LECSS2-S8	_
<b>T6</b> *2		100	25	LECSB2-T5 LECSC2-T5 LECSN2-T5-□	_
				LECSS2-T5	•
<b>T</b> 7		200	32	LECSB2-T7 LECSC2-T7 LECSN2-T7-□	_
	encoder)			LECSS2-T7	
Т8		400	40	LECSB2-T8 LECSC2-T8 LECSN2-T8-□	_
				LECSS2-T8	

\*1 For motor type S2 and S6, the compatible driver part number suffixes are S1 and S5 respectively.

\*2 For motor type T6, the compatible driver part number is LECS□2-T5.

Positioning pin hole

0 1 0	O i dollidining pini noic							
Nil	Housing B bottom*1	Housing B bottom						
К	Body bottom 2 locations	Body bottom						
*1 Pefer to the body mounting example on								

Refer to the body mounting example on page 166 for the mounting method.

Nil	Without cable		
S	Standard cable		
	Robotic cable		
R	(Flexible cable)		

9 Cable type\*1 \*2

- The motor and encoder cables are included. (The lock cable is also included when the motor with lock option is selected.)
- \*2 Standard cable entry direction is Parallel: (A) Axis side
   In-line: (B) Counter axis side

#### Cable length\*1 [m]

Nil	Nil Without cable							
2	2							
5	5							
Α	10							

\*1 The length of the encoder, motor, and lock cables are the same.

### I/O cable length [m]\*3

Nil Without cable							
Н	Without cable (Connector only)						
1	1.5						

When "Without driver" is selected for driver type, only "Nil: Without cable" can be selected. Réfer to page 797 if I/O cable is required. (Options are shown on page 797.)

### **1** Driver type

	Compatible	Power supply		UL-			
	drivers	voltage [V]	25	32	40	compliant	
Nil	Without driver	_				_	
A1	LECSA1-S□	100 to 120			_	•	
A2	LECSA2-S□	200 to 230					
B1	LECSB1-S□	100 to 120			_	_	
B2	LECSB2-S□	200 to 230				_	
DZ	LECSB2-T□	200 to 240					
C1	LECSC1-S□	100 to 120			_	_	
C2	LECSC2-S□	200 to 230				_	
CZ	LECSC2-T□	200 10 230					
S1	LECSS1-S□	100 to 120			_	_	
S2	LECSS2-S□	200 to 230				_	
32	LECSS2-T□	200 to 240					
N2	LECSN2-T□	200 to 240					
92	LECSN2-T□-9	200 to 240				_	
E2	LECSN2-T□-E	200 to 240				_	
P2	LECSN2-T□-P	200 to 240				_	
* Wh							

included. Select the cable type and cable length. Example) S2S2: Standard cable (2 m) + Driver (LECSS2) S2: Standard cable (2 m)

Nil: Without cable and driver

The 25A- series specifications and dimensions

#### Applicable Stroke Table

Applicab	ile s	Juo	NE.	ıab	ie															•	Standard
Stroke																					Manufacturable
[mm]	50	100	150	200	250	300	350	400	450	500	550	600	650	700	750	800	850	900	950	1000	stroke range
Model																					[mm]
25A-LEFS25		•	•	•		•	•	•	•			•	_	_	<b>—</b>	_	_	—	_	_	50 to 600
25A-LEFS32		•	•				•	•				•	•				_	_	_		50 to 800
25A-LEFS40	_	_																			150 to 1000

Please consult with SMC for non-standard strokes as they are produced as special orders.

<b>Compatible Dr</b>	compatible Drivers*1 are the same as those of the standard model.							
Driver type	Pulse input type/ Positioning type	Pulse input type	CC-Link direct input type	SSCNETIII type	Pulse input type	CC-Link direct input type	type The state of	Network card type
Series	LECSA	LECSB	LECSC	LECSS	LECSB-T	LECSC-T	LECSS-T	LECSN-T
Number of point tables*2	Up to 7	_	Up to 255 (2 stations occupied)	_	Up to 255	Up to 255 (2 stations occupied)	_	Up to 255
Pulse input	0	0	_	_	0	_	_	_
Applicable network	_	_	CC-Link	SSCNET	_	CC-Link	SSCNET II/H	PROFINET EtherCAT® EtherNet/IP™
Control encoder	Incremental 17-bit encoder	Absolute 18-bit encoder	Absolute 18-bit encoder	Absolute 18-bit encoder	Absolute 22-bit encoder	Absolute 18-bit encoder	Absolute 22-bit encoder	Absolute 22-bit encoder
Communication function	USB communication	USB communication,	RS422 communication	USB communication	USB communication,	RS422 communication	USB communication	USB communication
Power supply voltage [V]	100 to 120	VAC (50/60 Hz)	, 200 to 230 VAC	(50/60 Hz)	200 to 240 VAC (50/60 Hz)	200 to 230 VAC (50/60 Hz)	200 to 240 VAC (50/60 Hz)	200 to 240 VAC (50/60 Hz)
Reference page		•		7	77			

\*1 Copper and zinc materials are used for the motors, cables, controllers/drivers. \*2 The LECSN-T only supports PROFINET and EtherCAT®.



## **Electric Actuator/Slider Type**

Ball Screw Drive Secondary Battery Compatible

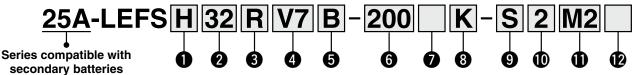
**25A-LEFS Series** LEFS25, 32, 40

Refer to page 47 for model selection.

RoHS

LECS□ Series ▶ p. 668

#### **How to Order**



Accuracy

Nil Basic type High-precision type

32

40

2 Size 3 Motor mounting position

Nil	In-line					
R	Right side parallel					
L	Left side parallel					

ย	Lead	[mm]

Symbol	LEFS25	LEFS32	LEFS40		
Α	12	16	20		
В	6	8	10		

6 Stroke [mm]

50	50
to	to
1000	1000

Motor option Nil Without option With lock

\* For details, refer to the applicable stroke table below

4 Motor type

Symbol	Type	Output [W]	Size	Compatible drivers
V6*1	AC servo motor	100	25	LECYM2-V5/LECYU2-V5
V7	(Absolute encoder)	200	32	LECYM2-V7/LECYU2-V7
V8		400	40	LECYM2-V8/LECYU2-V8

\*1 For motor type V6, the compatible driver part number suffix is V5.

#### I/O cable length [m]\*3

Nil Without cable					
Н	Without cable (Connector only)				
1	1.5				

\*3 When "Without driver" is selected for driver type, only "Nil: Without cable" can be selected. Refer to page 808 if I/O cable is required. (Options are shown on page 808.)

#### 8 Positioning pin hole

Nil	Housing B bottom*1	Housing B bottom
К	Body bottom 2 locations	Body bottom

\*1 Refer to the body mounting example on page 166 for the mounting method.

the encoder,

motor, and lock

cables are the same.

: Standard

Nil	Without cable
3	3
5	5
Α	10
С	20

9 Cable type\*1 \*2

Nil	Without cable
S	Standard cable
R	Robotic cable
	(Flexible cable)

- \*1 The motor and encoder cables are included. (The lock cable is also included when the motor with lock option is selected.)
- \*2 Standard cable entry direction is
  - · Parallel: (A) Axis side
  - · In-line: (B) Counter axis side

#### Cable length\*1 [m] \*1 The length of

Nil	Without cable						
3	3						
5	5						
Α	10						
С	20						

### **1** Driver type

	Compatible drivers	Power supply voltage [V]				
Nil	Without driver	_				
M2	LECYM2-V□	200 to 230				
U2	LECYU2-V□	200 to 230				

Stroke [mm] Model	50	100	150	200	250	300	350	400	450	500	550	600	650	700	750	800	850	900	950		Manufacturable stroke range [mm]
25A-LEFS25	•	•	•	•	•	•	•	•	•	•	•	•	_	_	_	_	_	_	_	_	50 to 600
25A-LEFS32	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	_	_	_	_	50 to 800
25A-LEFS40	_	_	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	150 to 1000

\* Please consult with SMC for non-standard strokes as they are produced as special orders.

The 25A- series specifications and dimensions are the same as those of the standard model.

#### **Compatible Drivers**

Applicable Stroke Table

Driver type	MECHATROLINK-II type	MECHATROLINK-III type						
Series	LECYM	LECYU						
Applicable network	MECHATROLINK-II	MECHATROLINK-Ⅲ						
Control encoder		olute encoder						
Communication device	USB communication, I	USB communication, RS-422 communication						
Power supply voltage [V]	200 to 230 VAC (50/60 Hz)							
Reference page	8	801						

Copper and zinc materials are used for the motors, cables, controllers/drivers.

## **Electric Actuator/High Rigidity Slider Type**

Ball Screw Drive Secondary Battery Compatible

4 Lead [mm]

9 Driver type\*5

В

Nil

**A1** 

**B1** 

**B2** 

C1

<u>S1</u>

N<sub>2</sub>

Example)

Symbol 25A-LEJS40 25A-LEJS63 16

Without driver

LECSA1-S□

LECSA2-S

LECSB1-S

LECSB2-S□

LECSB2-T□

LECSC1-S□

LECSC2-S

LECSC2-T□

LECSS1-S□

LECSS2-S

LECSS2-T□

LECSN2-T□

LECSN2-T□-9

LECSN2-T□-E

LECSN2-T□-P

S2: Standard cable (2 m)

Nil: Without cable and driver

8

25A-LEJS Series

Refer to page 175 for model selection.

LECY□ Series p. 672

How to Order



20

10

Compatible drivers | Power supply voltage [V] | UL-compliant

100 to 120

200 to 230

100 to 120

200 to 230

200 to 240

100 to 120

200 to 230

100 to 120

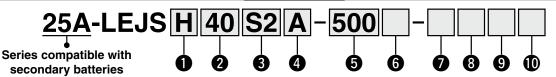
200 to 230

200 to 240



•

•



<b>U</b> Ac	curacy
Niil	Basic tv

Nil	Basic type
Н	High-precision type
<u> </u>	



### 5 Stroke [mm]\*3

_	
20	00
te	0
15	00

<sup>\*3</sup> Refer to the applicable stroke table for details.

#### 6 Motor option Nil Without option With lock

O INIC	otor type				
Symbol	Type	Output [W]	Actuator size	Compatible*3 drivers	UL- complian
S2*1	AC servo motor (Incremental encoder)	100	40	LECSA□-S1	•
S3	AC servo motor (Incremental encoder)	200	63	LECSA□-S3	•
S6*1	AC servo motor (Absolute encoder)	100	40	LECSB□-S5 LECSC□-S5 LECSS□-S5	_
<b>S</b> 7	AC servo motor (Absolute encoder)	200	63	LECSB□-S7 LECSC□-S7 LECSS□-S7	_
T6*2		100	40	LECSB2-T5 LECSC2-T5 LECSN2-T5-□	_
Т7	AC servo motor			LECSS2-T5	•
	(Absolute encoder)	200	63	LECSB2-T7 LECSC2-T7 LECSN2-T7-□	_
				LECSS2-T7	•

<sup>\*1</sup> For motor type S2 and S6, the compatible driver part number suffixes are S1 and S5 respectively.

#### Cable type\*5, \*6, \*7

Nil	Without cable
S	Standard cable
R	Robotic cable (Flexible cable)

<sup>\*6</sup> The motor and encoder cables are included. (The lock cable is included when the motor with lock option is selected.)

Nil Without cable			
2	2		
5	5		
Α	10		

<sup>\*8</sup> The length of the motor, encoder, and lock cables are the same.

Cal	ole length [m]*5, *8
Nil	Without cable
_	

I/O cable length [m]*9						
Nil	Without cable					
Н	Without cable (Connector only)					
1	1.5					

\*5 When a driver type is selected, a cable is included.

S2S2: Standard cable (2 m) + Driver (LECSS2)

Select the cable type and cable length.

\*9 When "Without driver" is selected for driver type, only "Nil: Without cable" can be selected. Refer to page 797 if I/O cable is required.

For auto switches, refer to page 681.

Applicable Stroke Table <sup>∗4</sup> ●: Standard											
Stroke Model [mm]	200	300	400	500	600	700	800	900	1000	1200	1500
25A-LEJS40											<b>—</b>
25A-LEJS63	_										

<sup>\*4</sup> Please consult with SMC for non-standard strokes as they are produced as special orders.

#### Compatible Drivers\*10

\* The 25A- series specifications and dimensions are the same as those of the standard model.

Driver type	Pulse input type/ Positioning type	Pulse input type	CC-Link direct input type	SSCNET II type	Pulse input type	CC-Link direct input type	type	Network card type
Series	LECSA	LECSB	LECSC	LECSS	LECSB-T	LECSC-T	LECSS-T	LECSN-T
Number of point tables*11	Up to 7	_	Up to 255	_	Up to 255	Up to 255 (2 stations occupied)	_	Up to 255
Pulse input	0	0	_	_	0	_	_	_
Applicable network	_	_	CC-Link	SSCNETII	_	CC-Link	SSCNET III/H	PROFINET EtherCAT® EtherNet/IP™
Control encoder	Incremental	Absolute	Absolute	Absolute	Absolute	Absolute	Absolute	Absolute
Control encoder	17-bit encoder	18-bit encoder	18-bit encoder	18-bit encoder	22-bit encoder	18-bit encoder	22-bit encoder	22-bit encoder
Communication function	USB communication	USB communication, I	RS422 communication	USB communication	USB communication,	RS422 communication	USB communication	USB communication
Power supply voltage [V]	100 to 120	VAC (50/60 Hz),	200 to 230 VAC	(50/60 Hz)	200 to 240 VAC (50/60 Hz)	200 to 230 VAC (50/60 Hz)	200 to 240 VAC (50/60 Hz)	200 to 240 VAC (50/60 Hz)
Reference page				7	77			

<sup>\*10</sup> Copper and zinc materials are used for the motors, cables, controllers/drivers. \*11 The LECSN-T only supports PROFINET and EtherCAT®.

<sup>\*2</sup> For motor type T6, the compatible driver part number is LECS□2-T5.

<sup>\*7</sup> Standard cable entry is "(A) Axis side."

## **Electric Actuator/High Rigidity Slider Type**

Ball Screw Drive Secondary Battery Compatible

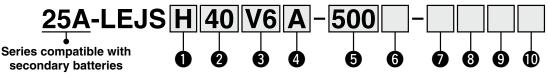
25A-LEJS Series LEJS40, 63

Refer to page 186 for model selection.

(RoHS)

LECS□ Series p. 671

#### **How to Order**



Accuracy

Nil	Basic type
Н	High-precision type

2 Size 40

U	Мо	tor	type	*1

Symbol	Туре	Output [W]	Actuator size	Compatible drivers
V6	AC servo motor (Absolute encoder)	100	40	LECYM2-V5 LECYU2-V5
<b>V</b> 7	AC servo motor (Absolute encoder)	200	63	LECYM2-V7 LECYU2-V7

\*1 For motor type V6, the compatible driver part number suffix is V5.

4 Lead [mm]

Symbol	25A-LEJS40	25A-LEJS63
Н	24	30
Α	16	20
В	8	10

5 Stroke [mm]\*3

200	*3 Refer to the
4	"O Helel to the
to	applicable stroke
4500	
1500	table for details.

6 Motor option Without option With lock

LEB

ᄪ

LEY-X5

11-LEFS

11-LEJS

| LECY□ | LECS□

**7** Cable type\*5, \*6, \*7

Nil	Without cable				
S	Standard cable				
R	Robotic cable (Flexible cable)				

- \*6 The motor and encoder cables are included. (The lock cable is included when the motor with lock option is
- \*7 Standard cable entry is "(A) Axis side."

8 Cable length [m] \*5, \*8

Nil	Without cable
3	3
5	5
Α	10
С	20

\*8 The length of the motor, encoder, and lock cables are the same.

9 Driver type \*5

	Compatible drivers	Power supply voltage [V]
Nil	Without driver	_
M2	LECYM2-V□	200 to 230
U2	LECYU2-V□	200 to 230

\*5 When a driver type is selected, a cable is included. Select the cable type and cable length.

Example)

S2S2: Standard cable (2 m) + Driver (LECSS2)

S2: Standard cable (2 m) Nil: Without cable and driver

I/O cable length [m]\*9

Nil	Without cable Without cable (Connector only)	
Н		
1	1.5	

\*9 When "Without driver" is selected for driver type, only "Nil: Without cable" can be selected. Refer to page 808 if I/O cable is required.

Applicable Stroke Table*4 ●: Standard											
Stroke Model [mm]		300	400	500	600	700	800	900	1000	1200	1500
25A-LEJS40											_
25A-LEJS63	_				•		•		•		

\*4 Please consult with SMC for non-standard strokes as they are produced as special orders.

Solid state auto switches should be ordered separately. For details on auto switches, refer to page 681.

#### Applicable auto switches

D-M9N(V)-900, D-M9P(V)-900, D-M9B(V)-900

D-M9NW(V)-900, D-M9PW(V)-900, D-M9BW(V)-900 \* The 25A- series specifications and dimensions are the same as those of the standard model.

notible Drivere

Compatible Drivers					
Driver type	MECHATROLINK-II type	MECHATROLINK-III type			
Series	LECYM	LECYU			
Applicable network	MECHATROLINK-II	MECHATROLINK-Ⅲ			
Control encoder	Absolute 20-bit encoder				
Communication device	USB communication, I	USB communication, RS-422 communication			
Power supply voltage [V]	y voltage [V] 200 to 230 VAC (50/60 Hz)				
Reference page	80	01			

<sup>\*</sup> Copper and zinc materials are used for the motors, cables, controllers/drivers.



## **Electric Actuator** Rod Type Secondary Battery Compatible

**25A-LEY Series** LEY16, 25, 32, 40



RoHS

Refer to page 299 for model selection.

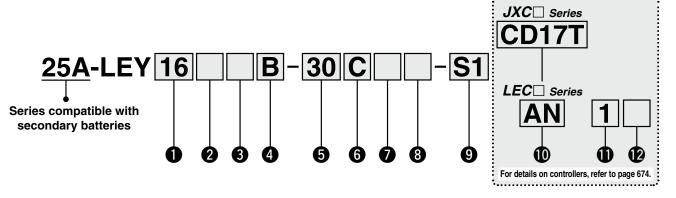
Dust-tight/Water-jet-proof ▶p. 611

**How to Order** 



Motor mounting position: Top/Parallel

Motor mounting position: In-line



#### Size 16

### 25 32 40

#### **Motor mounting** position

poortion				
Nil Top mountin				
R	Right side parallel			
L	Left side parallel			
D	In-line			

#### Motor type

0	T	Applicable size			Compatible controllers/		
Symbol	Type	LEY16	LEY25	LEY32/40	·	drivers	
Nil	Step motor (Servo/24 VDC)	•	•	•	JXCE1 JXC91 JXCP1 JXCD1 JXCL1	JXCM1 JXC51 JXC61	LECP1 LECPA
A	Servo motor (24 VDC)	•	•	_		LECA6	

#### 4 Lead [mm]

Symbol	LEY16	LEY25	LEY32/40
Α	10	12	16
В	5	6	8
С	2.5	3	4

5 Stroke [mm]

30	30
to	to
500	500

<sup>\*</sup> For details, refer to the applicable stroke table below.

#### 6 Motor option\*2

С	With motor cover	
W	With lock/motor cover	

·	
Motor	

#### Rod end thread

Nil	Rod end female thread
М	Rod end male thread
IVI	(1 rod end nut is included.)

#### 8 Mounting\*5

Symbol	Type	Motor mounting position		
Syllibol	туре	Top/Parallel	In-line	
Nil	Ends tapped/Body			
IVII	bottom tapped*6	_	•	
L	Foot	•	_	
F	Rod flange*6	●*8	•	
G	Head flange*6	●*9	_	
D	Double clevis*7	•	_	

#### 9 Actuator cable type/length\*11

Standard cable [m]					
Nil	None				
S1	1.5*12				
S3	3*12				
S5	5*12				

Roboti	[m]		
R1	1.5	RA	10*10
R3	3	RB	15* <sup>10</sup>
R5	5	RC	20*10
R8	8*10		

#### Mounting Bracket Part Nos. for the 25A- Series\*4

Applicable size Foot*3		Flange	Double clevis		
16	25-LEY-L016	25-LEY-F016	25-LEY-D016		
25	25-LEY-L025	25-LEY-F025	25-LEY-D025		
32, 40	25-LEY-L032	25-LEY-F032	25-LEY-D032		
Surface treatment	RAYDENT®	RAYDENT®	Coating (Size 16: Electroless nickel plating)		

Solid state auto switches should be ordered separately. For details on auto switches, refer to page 681.

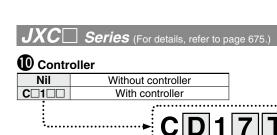
#### Applicable auto switches

D-M9N(V)-900, D-M9P(V)-900, D-M9B(V)-900 D-M9NW(V)-900, D-M9PW(V)-900, D-M9BW(V)-900

#### nliaahla Ctuaka Tahla\*1

Applicable Stroke Table • Standard												
Stroke	30	50	100	150	200	250	300	350	400	450	500	Manufacturable
Model [mm]	30	30	100	130	200	230	300	550	700	730	300	stroke range
25A-LEY16			•	•	•	•	•	_	_	_	_	10 to 300
25A-LEY25			•		•					_	_	15 to 400
25A-LEY32/40												20 to 500





(Communication protocol/Input/Output)

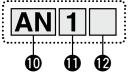
Е	EtherCAT®	L	IO-Link
9	EtherNet/IP™	М	CC-Link Ver 1.10
Р	PROFINET	5	Parallel input (NPN)
D	DeviceNet™	6	Parallel input (PNP)

7	Screw mounting
8*17	DIN rail

Communication plug connector I/O cable\*18

Symbol	Type	Applicable interface
Nil	Without accessory	
S	Straight type communication plug connector	DeviceNet™
Т	T-branch type communication plug connector	CC-Link Ver 1.10
1	I/O cable (1.5 m)	Dorollol innert (NIDNI)
3	I/O cable (3 m)	Parallel input (NPN) Parallel input (PNP)
5	I/O cable (5 m)	raiallei liiput (FINF)

**Series** (For details, refer to page 675.)





Nil	Without controller/driver					
6N	LECA6	NPN				
6P	(Step data input type)	PNP				
1N	LECP1*13	NPN				
1P	P (Programless type)					
AN	LECPA*13 *14	NPN				
AP	(Pulse input type)	PNP				

#### I/O cable length\*15

Nil	Without cable (Without communication plug connector)
1	1.5 m
3	3 m* <sup>16</sup>
5	5 m* <sup>16</sup>



Nil	Screw mounting
D	DIN rail*17

- \*1 Please consult with SMC for non-standard strokes as they are
- produced as special orders. When "With lock" or "With lock/motor cover" is selected for the top mounting and right/left side parallel types, the motor body will stick out from the end of the body for size 16/40 with strokes of 30 mm or less. Check for interference with workpieces before selecting a model.

  \*3 When ordering foot brackets, order 2 pieces per actuator.
- Parts belonging to each bracket are as follows.
  Foot, Flange: Body mounting bolt, Double clevis: Clevis pin, Type C retaining ring for axis, Body mounting bolt
- \*5 The mounting bracket is shipped together with the product but does not come assembled.
- \*6 For the horizontal cantilever mounting of the rod flange, head flange, or ends tapped types, use the actuator within the following stroke range. LEY25: 200 mm or less LEY32/40: 100 mm or less
- For the mounting of the double clevis type, use the actuator within the following stroke range.
- \*8 The rod flange type is not available for the LEY16/40 with a 30 mm stroke and motor option "With lock," "With lock/motor cover."
  \*9 The head flange type is not available for the LEY32/40.
- \*10 Produced upon receipt of order (Robotic cable only)

- The standard cable should only be used on fixed parts. For use on moving parts, select the robotic cable. Refer to pages 758 and 759 if only the actuator cable is required.
- For details on controllers/drivers and compatible motors, refer to the
- compatible controllers/drivers on the next page. \*13 Only available for the motor type "Step motor"
- \*13 Only available for the motor type "Step motor"
  \*14 When pulse signals are open collector, order the current limiting resistor (LEC-PA-R-□) on page 736 separately.
  \*15 When "Without controller/driver" is selected for controller/driver types, I/O cable cannot be selected. Refer to page 713 (For LECA6), page 724 (For LECP1), or page 736 (For LECPA) if I/O cable is required.
- \*16 When "Pulse input type" is selected for controller/driver types, pulse input usable only with differential. Only 1.5 m cables usable with open collector \*17 The DIN rail is not included. It must be ordered separately. \*18 Select "Nil" for anything other than DeviceNet™, CC-Link, or parallel
- input.

Select "Nil," "S," or "T" for DeviceNet™ or CC-Link. Select "Nil," "1," "3," or "5" for parallel input.

#### **∕**∴Caution

#### [CE-compliant products]

1) EMC compliance was tested by combining the electric actuator LEY series and the controller LEC/JXC series.

The EMC depends on the configuration of the customer's control panel and the relationship with other electrical equipment and wiring. Therefore, compliance with the EMC directive cannot be certified for SMC components incorporated into the customer's equipment under actual operating conditions. As a result, it is necessary for the customer to verify compliance with the EMC directive for the machinery and equipment as a whole.

2 For the servo motor (24 VDC) specification, EMC compliance was tested by installing a noise filter set (LEC-NFA). Refer to page 713 for the noise filter set. Refer to the LECA series Operation Manual for installation.

#### [UL-compliant products (For the LEC series)]

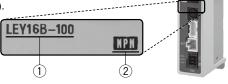
When compliance with UL is required, the electric actuator and controller/ driver should be used with a UL1310 Class 2 power supply.

#### The actuator and controller/driver are sold as a package.

Confirm that the combination of the controller/driver and actuator is correct.

#### <Check the following before use.>

- 1 Check the actuator label for the model number (after "25A-"). This number should match that of the controller/driver.
- 2 Check that the Parallel I/O configuration matches (NPN or PNP).



Refer to the Operation Manual for using the products. Please download it via our website: https://www.smcworld.com

LEJB LEJB

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LEPY LEPS

EB

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LEY-X5

11-LEFS 11-LEJS

25A-

CXC

Motorless

#### **Compatible Controllers/Drivers**

Туре	EtherCAT® direct input type	EtherNet/IP™ direct input type	PROFINET direct input type	DeviceNet™ direct input type	IO-Link direct input type	CC-Link direct input type
Series	JXCE1	JXC91	JXCP1	JXCD1	JXCL1	JXCM1
Features	EtherCAT® direct input	EtherNet/IP™ direct input	PROFINET direct input	DeviceNet™ direct input	IO-Link direct input	CC-Link direct input
Compatible motor			·	motor 24 VDC)		
Max. number of step data			64 p	oints		
Power supply voltage			24 \	/DC		
Reference page			74	41		

	Step data input type	Step data input type	Programless type	Pulse input type
Туре	Gac :	Out to		
Series	JXC51 JXC61	LECA6	LECP1	LECPA
Features	Parallel I/O	Value (Step data) input Standard controller	Capable of setting up operation (step data) without using a PC or teaching box	Operation by pulse signals
Compatible motor	Step motor (Servo/24 VDC)			motor 24 VDC)
Max. number of step data	64 p	oints	14 points	_
Power supply voltage		24 \	/DC	
Reference page	706-1	707	719	731

## **Electric Actuator** Rod Type Secondary Battery Compatible



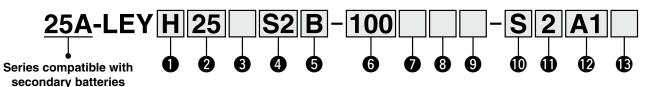
25A-LEY Series LEY25, 32 Size



LECY□ series > p. 679 Dust-tight/Water-jet-proof > p. 619

Refer to page 305 for model selection.

#### How to Order



## Accuracy

Nil Basic type High-precision type 2 Size 25 32

#### 3 Motor mounting position

Nil	Top mounting				
R	Right side parallel				
L	Left side parallel				
D	In-line				

Lead [mm]

	<u> </u>	
Symbol	LEY25	LEY32*1
Α	12	16 (20)
В	6	8 (10)
С	3	4 (5)

\*1 The values shown in ( ) are the leads for the size 32 top mounting, right/left side parallel types. (Equivalent leads which include the pulley ratio [1.25:1])

Motor type\*1

Symbol	Туре	Output [W]	Actuator size	Compatible drivers*3	UL- compliant
S2*1	AC servo motor	100	25	LECSA□-S1	•
S3	(Incremental encoder)	200	32	LECSA□-S3	•
S6*1	AC servo motor (Absolute encoder)	100	25	LECSB□-S5 LECSC□-S5 LECSS□-S5	_
<b>S7</b>		200	32	LECSB□-S7 LECSC□-S7 LECSS□-S7	_
<b>T6</b> *2		100	25	LECSB2-T5 LECSC2-T5 LECSN2-T5-□	_
	AC servo motor			LECSS2-T5	•
Т7	(Absolute encoder)	200	32	LECSB2-T7 LECSC2-T7 LECSN2-T7-□	_
				LECSS2-T7	•

- \*1 For motor type S2 and S6, the compatible driver part number suffixes are S1 and S5 respectively.
- \*2 For motor type T6, the compatible driver part number is LECS 2-T5.
- \*3 For details on the driver, refer to page 777.

#### 6 Stroke [mm]

30	30
to	to
500	500

\* For details, refer to the applicable stroke table below.

#### Motor option

Nil	Without option
В	With lock*1

When "With lock" is selected for the top mounting and right/left side parallel types, the motor body will stick out from the end of the body for size 25 with strokes of 30 mm or less. Check for interference with workpieces before selecting a model.

Motor

#### 8 Rod end thread

Nil	Rod end female thread
М	Rod end male thread
IVI	(1 rod end nut is included.)

#### Mounting Bracket Part Nos. for the 25A- Series

mounting 2	nounting Dracket rait from the Lort Confee									
Applicable size	Foot*1	Flange	Double clevis							
25	25-LEY-L025	25-LEY-F025	25-LEY-D025							
32	25-LEY-L032	25-LEY-F032	25-LEY-D032							
Surface treatment	RAYDENT®	RAYDENT®	Coating (Size 16: Electroless nickel plating)							

- \*1 When ordering foot brackets, order 2 pieces per actuator.
- Parts belonging to each bracket are as follows. Foot, Flange: Body mounting bolt, Double clevis: Clevis pin, Type C retaining ring for axis, Body mounting bolt

Applicable Stroke Table   •: Standard												
Stroke	30	ΕO	100	150	200	250	200	250	E0 400	450	500	Manufacturable stroke range [mm]
Model [mm]	30	50	100	150	200	250	300	330	400	450		stroke range [mm]
25A-LEY25	•		•	•	•	•	•	•	•	_	_	15 to 400
25A-LEY32	•	•	•	•	•	•	•	•	•	•	•	20 to 500

Please consult with SMC for non-standard strokes as they are produced as special orders.

#### 9 Mounting\*1

Symbol	Type	Motor mounting position			
Syllibol	туре	Top/Parallel	In-line		
Nil	Ends tapped/ Body bottom tapped *2	•	•		
L	Foot	•	_		
F	Rod flange*2	●*4	•		
G	Head flange*2	●*5	_		
D	Double clevis*3	•	_		

- \*1 The mounting bracket is shipped together with the product but does not come assembled.
- \*2 For the horizontal cantilever mounting of the rod flange, head flange, or ends tapped types, use the actuator within the following stroke range.
  - · 25A-LEY25: 200 mm or less
  - 25A-LEY32: 100 mm or less
- \*3 For the mounting of the double clevis type, use the actuator within the following stroke range.
  - · 25A-LEY25: 200 mm or less
  - · 25A-LEY32: 200 mm or less
- \*4 The rod flange type is not available for the 25A-LEY25 with a 30 mm stroke and motor option "With lock."
- \*5 The head flange type is not available for the 25A-LEY32

Solid state auto switches should be ordered separately. For details on auto switches, refer to page 681.

#### Applicable auto switches

D-M9N(V)-900, D-M9P(V)-900, D-M9B(V)-900 D-M9NW(V)-900, D-M9PW(V)-900, D-M9BW(V)-900







Motor mounting position: Top/Parallel

Motor mounting position: In-line

#### Cable type\*1 \*2

Nil	Without cable
S	Standard cable
R	Robotic cable (Flexible cable)

- \*1 The motor and encoder cables are included. (The lock cable is also included when the motor with lock option is selected.)
- \*2 Standard cable entry direction is
  - · Top/Parallel: (A) Axis side
  - · In-line: (B) Counter axis side

#### Cable length\*1 [m]

Nil	Without cable				
2	2				
5	5				
Α	10				

\*1 The length of the encoder, motor, and lock cables are the same.

#### Driver type\*1

	Compatible drivers	Power supply voltage [V]	UL-compliant				
Nil	Without driver	_	_				
<b>A</b> 1	LECSA1-S□	100 to 120	•				
A2	LECSA2-S□	200 to 230	•				
B1	LECSB1-S□	100 to 120	_				
B2	LECSB2-S□	200 to 230	_				
DZ	LECSB2-T□	200 to 240	•				
C1	LECSC1-S□	100 to 120	_				
C2	LECSC2-S□	200 to 230	_				
C2	LECSC2-T□	200 10 230	•				
S1	LECSS1-S□	100 to 120	_				
S2	LECSS2-S□	200 to 230	_				
52	LECSS2-T□	200 to 240	•				
N2	LECSN2-T□	200 to 240	•				
92	LECSN2-T□-9	200 to 240	_				
E2	LECSN2-T□-E	200 to 240	_				
P2	LECSN2-T□-P	200 to 240	_				
4 140 11 1 1 1 1 1 1 1 1 1 1 1							

\*1 When a driver type is selected, a cable is included. Select the cable type and cable length. Example)

S2S2: Standard cable (2 m) + Driver (LECSS2)

S2: Standard cable (2 m)

Nil: Without cable and driver

\* The 25A- series specifications and dimensions are the same as those of the standard model.

### I/O cable length [m]\*1

Nil	Without cable						
Н	Without cable (Connector only)						
1	1.5						

\*1 When "Without driver" is selected for driver type, only "Nil: Without cable" can be selected. Refer to page 797 if I/O cable is required.

#### Campatible Drivers\*1

Compatible Driv	ers*1					aro trio oarri	3 40 11000 01 1110	Staridard model.	
Driver type	Pulse input type/ Positioning type	Pulse input type	CC-Link direct input type	SSCNETⅢ type	Pulse input type	CC-Link direct input type	type	Network card type	
Series	LECSA LECSB LECSC LECSS LECSB-T LE		LECSC-T	LECSS-T	LECSN-T				
Number of point tables*2	Up to 7	_	Up to 255 (2 stations occupied)	_	Up to 255	Up to 255 (2 stations occupied)	_	Up to 255	
Pulse input	0	0	_	_	0	_	_	_	
Applicable network	_	_	CC-Link	SSCNETII	_	CC-Link	SSCNETⅢ/H	PROFINET EtherCAT® EtherNet/IP™	
Control encoder	Incremental 17-bit encoder	Absolute 18-bit encoder	Absolute 18-bit encoder	Absolute 18-bit encoder	Absolute 22-bit encoder	Absolute 18-bit encoder	Absolute 22-bit encoder	Absolute 22-bit encoder	
Communication function	USB communication	USB communication,	RS422 communication	USB communication	USB communication,	RS422 communication	USB communication	USB communication	
Power supply voltage [V]	100 to 120 VAC (50/60 Hz), 200 to 230 VAC (50/60 Hz)  200 to 240  VAC  VAC  VAC  (50/60 Hz)  (50/60 Hz)  (50/60 Hz)							200 to 240 VAC (50/60 Hz)	
Reference page		777							

- \*1 Copper and zinc materials are used for the motors, cables, controllers/drivers.
- \*2 The LECSN-T only supports PROFINET and EtherCAT®.



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LEY-X5

11-LEFS 11-LEJS

Motorless | LECY□ LAT3

678 A

## **Electric Actuator** Rod Type Secondary Battery Compatible

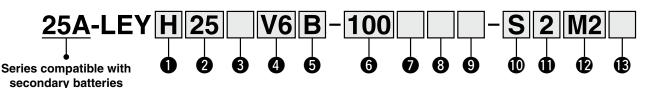
25A-LEY Series LEY25, 32 Size



LECS□ series p. 677 Dust-tight/Water-jet-proof p. 625

Refer to page 312 for model selection.

#### **How to Order**



Accuracy

Nil Basic type High-precision type

2 Size

25

32

Motor mounting position

Nil	Top mounting
R	Right side parallel
L	Left side parallel
D	In-line

4 Motor type

Sy	/mbol	Туре	Output [W]	Size	Compatible drivers
	V6*1	AC servo motor	100	25	LECYM2-V5 LECYU2-V5
	V7	(Absolute encoder)	200	32	LECYM2-V7 LECYU2-V7

<sup>\*1</sup> For motor type V6, the compatible driver part number suffix is V5.

6 Lead [mm]

Symbol	25A-LEY25	25A-LEY32*1
Α	12	16 (20)
В	6	8 (10)
С	3	4 (5)

\*1 The values shown in ( ) are the leads for the size 32 top mounting, right/left side parallel types. (Equivalent leads which include the pulley ratio [1.25:1])

6 Stroke [mm]

30	30
to	to
500	500

\* For details, refer to the applicable stroke table below.

Motor option

• meter option							
Nil	Without option						
В	With lock*1						

\*1 When "With lock" is selected for the top mounting and right/left side parallel types, the motor body will stick out from the end of the body for size 25 with strokes of 30 mm or less. Check for interference with workpieces before selecting a model.

Motor

8 Rod end thread

Nil	Rod end female thread
M	Rod end male thread
	(1 rod end nut is included.)

9 Mounting\*1

Cumbal	Tymo	Motor mounting position			
Symbol	Type	Top/Parallel	In-line	١,	
Nil	Ends tapped/ Body bottom tapped *2	•	•		
L	Foot	•	_		
F	Rod flange*2	●*4	•		
G	Head flange*2	●*5	_		
D	Double clevis*3	•	_		

- \*1 The mounting bracket is shipped together with the product but does not come assembled.
- \*2 For the horizontal cantilever mounting of the rod flange, head flange, or ends tapped types, use the actuator within the following stroke range.
- · LEY25: 200 mm or less · LEY32: 100 mm or less \*3 For the mounting of the double clevis type, use the actuator within the following stroke range.
- · LEY25: 200 mm or less · LEY32: 200 mm or less \*4 The rod flange type is not available for the LEY25
- with a 30 mm stroke and motor option "With lock." \*5 The head flange type is not available for the LEY32.

#### Mounting Bracket Part Nos. for the 25A- Series

Applicable size	Foot*1	Flange	Double clevis				
25	25-LEY-L025	25-LEY-F025	25-LEY-D025				
32	25-LEY-L032	25-LEY-F032	25-LEY-D032				
Surface treatment	RAYDENT®	RAYDENT®	Coating (Size 16: Electroless nickel plating)				

\*1 When ordering foot brackets, order 2 pieces per actuator.

\* Parts belonging to each bracket are as follows. Foot, Flange: Body mounting bolt, Double clevis: Clevis pin, Type C retaining ring for axis, D-M9NW(V)-900, D-M9PW(V)-900, D-M9PW(V)-900 Body mounting bolt

Solid state auto switches should be ordered separately. For details on auto switches, refer to page 681.

#### Applicable auto switches

D-M9N(V)-900, D-M9P(V)-900, D-M9B(V)-900

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Applicable Stroke Table   Standard												
Stroke		50	100	150	200	250	300	350	400	450	500	Manufacturable
Model [mm]	30	30	100	130	200	230	300	330	400	430	300	stroke range [mm]
25A-LEY25	•	•	•	•	•	•	•	•	•	_	_	15 to 400
25A-LEY32	•	•	•	•	•	•	•	•	•	•	•	20 to 500

Please consult with SMC for non-standard strokes as they are produced as special orders.



Motor mounting position: Top/Parallel



Motor mounting position: In-line

Cable type\*1 \*2

Cabic type							
Nil	Without cable						
S	Standard cable						
R	Robotic cable (Flexible cable)						

- \*1 The motor and encoder cables are included. (The lock cable is also included when the motor with lock option is selected.)
- \*2 Standard cable entry direction is
  - · Top/Parallel: (A) Axis side
  - · In-line: (B) Counter axis side

Cable length [m]\*1

Nil	Without cable
3	3
5	5
Α	10
С	20

\*1 The length of the motor and encoder cables are the same. (For with lock)

12 Driver type

	Compatible drivers	Power supply voltage [V]				
Nil	Without driver	_				
M2	LECYM2-V□	200 to 230				
U2	LECYU2-V□	200 to 230				

\* When a driver type is selected, a cable is included. Select the cable type and cable length.

I/O cable length [m]\*1

Nil	Without cable								
Н	Without cable (Connector only)								
1	1.5								

\*1 When "Without driver" is selected for driver type, only "Nil: Without cable" can be selected. Refer to page 808 if I/O cable is required.

> \* The 25A- series specifications and dimensions are the same as those of the standard model.

#### Compatible Drivers

Companible Drivers								
Driver type	MECHATROLINK-II type	MECHATROLINK-III type						
Series	LECYM	LECYU						
Applicable network	MECHATROLINK-Ⅱ	MECHATROLINK-Ⅲ						
Control encoder	Absolute 20-bit encoder							
Communication device	USB communication, RS-422 communication							
Power supply voltage [V]	200 to 230 VAC (50/60 Hz)							
Reference page	801							

<sup>\*</sup> Copper and zinc materials are used for the motors, cables, controllers/drivers.



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# 25A- Series Applicable Auto Switches

#### **Applicable Electric Actuator Series**

Auto switches								Electric actuators					
Tuno	Special function	Electrical entry	Indicator light	(Output) entry	Electrical	ry Auto switch	Lead wire length [m]				Pre-wired	LEJS	LEY
Туре					direction		0.5 Nil	1 M	3 L	5 Z	SDPC	40 to 63	16 to 40
	_	Grommet	Yes	3-wire (NPN)	7	D-M9N-900	•	•	•	0	_	•	•
				3-wire (PNP)		D-M9P-900	•	•	•	0	_	•	•
				2-wire		D-M9B-900	•	•	•	0	_	•	•
				3-wire (NPN)	4	D-M9NV-900	•	•	•	0	_	•	•
				3-wire (PNP)		D-M9PV-900	•	•	•	0	_	•	•
Solid state				2-wire		D-M9BV-900	•	•	•	0	_	•	•
auto switch				3-wire (NPN)	) In-line	D-M9NW-900	•	•	•	0	_	•	•
	Diagnostic indication (2-color indicator)			3-wire (PNP)		D-M9PW-900	•	•	•	0	_	•	•
				2-wire		D-M9BW-900	•	•	•	0	0	•	•
				3-wire (NPN)	Perpendicular	D-M9NWV-900	•	•	•	0	_	•	•
				3-wire (PNP)		D-M9PWV-900	•	•	•	0	_	•	•
				2-wire		D-M9BWV-900	•	•	•	0	0	•	•

- $\ast\,$  Solid state auto switches marked with "O" are produced upon receipt of order.
- \* Auto switches cannot be ordered with the actuator part number. They should be ordered separately. Please refer below for ordering. One each of the right-hand-type and the left-hand-type are shipped together with the actuator.

#### **Ordering the Auto Switches**

• Individual auto switch: D-M9BWL-900

(Place the order with the part number for auto switch shown in the table above.)

\* Lead wire length symbols: 0.5 m.....Nil (Example) M9NW

1 m..... M (Example) M9NWM

3 m..... L (Example) M9NWL

5 m..... Z (Example) M9NWZ



Be sure to read this before handling products.

Be sure to read the "Handling Precautions for SMC Products" (M-E03-3) and the "Operation Manual" before use.

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LEY-X5

11-LEJS

Motorless | LECY□ | LECS□

#### **Precautions**

### **⚠** Caution

#### ■ Change of material

For the 25A- series, there is a restriction on the use of copper and zinc as main components in the metal materials used. Keep in mind that the aluminum alloy, aluminum die cast, and some of the stainless steel materials contain traces of copper (Cu) and/or zinc (Zn) as an additive element.

However, copper is used in some parts-the coils of solenoid valves, the circuit boards, connector pins, and lead wires of electrical equipment and auto switches, and the motors, cables, and drivers of electric actuators-whose materials cannot be easily changed to alternative materials.

In addition, some magnets (including the surface treatment) contain copper (Cu) and/or zinc (Zn). However, due to their magnetic characteristics, it is impossible to use alternative materials.

#### ■ Chemical environment

Refrain from using the products in such environments as exposed to chemicals. Otherwise, resin parts may deteriorate.

If you want SMC to test the products for the effects of chemicals attached to them, send the products back to SMC after thoroughly cleaning them.

Consult your SMC sales representative for further details.

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