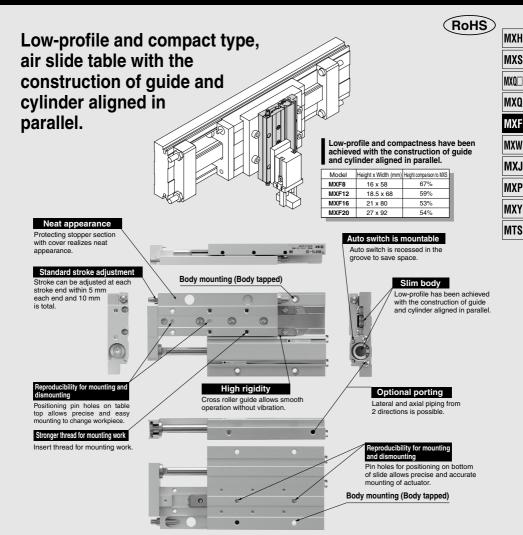
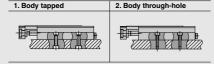
Low Profile Slide Table

MXF Series

Ø8, Ø12, Ø16, Ø20



Mounting can be done from 2 directions top side (through-hole) and bottom side (body tapped).



Series Variations

Model	Bore size (mm)	Stroke (mm)	Auto switch
		10 20 30 50 75 100	Reed auto switch
MXF8	8	 	D-A9□, D-A9□V Solid state auto switch
MXF12	12	 	D-M9□, D-M9□V
MXF16	16	 	2-color indicator solid state auto switch
MXF20	20	 	D-M9□W, D-M9□WV

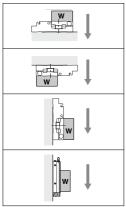


Model Selection

Model Selection Step Formula/Data Selection Example **Operating Conditions** · Model to be used Cylinder: MXF20-50 Enumerate the operating conditions Cushion: Rubber bumper considering the mounting position Type of cushion Workpiece table mounting and workpiece configuration. · Workpiece mounting position Mounting: Horizontal wall mounting Check that the load weight does not Mounting orientation Average operating speed: exceed the maximum allowable Average operating speed Va (mm/s) Va = 300 [mm/s] load weight and that the average • Load mass W (kg): Fig. (1) · Table (2) Allowable load: W = 0.5 [kg] operating speed does not exceed • Overhang Ln (mm): Fig. (2) L₁ = 10 mm the operating speed range. $1_2 = 30 \text{ mm}$ Kinetic Energy $E = \frac{1}{2} \cdot W \left(\frac{V}{1000} \right)^2$ Find the kinetic energy E (J) $E = \frac{1}{2} \cdot 0.5 \left(\frac{420}{1000} \right)^2 = 0.044$ of the load. Find the allowable kinetic Collision speed V = 1.4 . Va *) Correction factor (Reference values) V = 1.4 × 300 = 420 energy Ea (J). Ea = K-Emax Confirm that the kinetic energy Workpiece mounting coefficient K: Fig. (3) of the load does not exceed Max. allowable kinetic energy Emax: Table (1) Ea = 1 · 0.16 = 0.16 the allowable kinetic energy. Kinetic energy (E) ≤ Allowable kinetic energy (Ea) Can be used based on E = 0.044 ≤ Ea = 0.16 Load Factor 2=1 Load factor of load mass Find the allowable load mass Wa (kg). $Wa = K \cdot \beta \cdot Wmax$ Wa = 1 x 1 x 4 = 4 Workpiece mounting coefficient K: Fig. (3) Note) No need to consider this load K = 1Allowable load mass coefficient β: Graph (1) factor in the case of using $\beta = 1$ perpendicularly in a vertical Max. allowable load mass Wmax: Table (2) Wmax = 4position. (Define $\Omega_1 = 0$) $CL_1 = 0.5/4 = 0.125$ Find the load factor of the load mass C(1. $\Omega_1 = W/Wa$ 3-2 Load factor of the static moment Yawing Rolling Examine My. Examine Mr. Find the static moment M (N·m). $M = W \times 9.8 (Ln + An)/1000$ $My = 0.5 \times 9.8 (10 + 11)/1000 = 0.11$ $Mr = 0.5 \times 9.8 (30 + 17)/1000 = 0.23$ Find the allowable static moment Moment center position distance Ma (N·m). $A_6 = 17$ compensation amount An: Table (3) Ma = K.Y.Mmax Mar = 9.14 (Same as May) $May = 1 \times 1 \times 9.14 = 9.14$ Workpiece mounting coefficient K: Fig. (3) Mymax = 9.14 Allowable moment coefficient 7: Graph (2) K = 1Maximum allowable moment Mmax: Table (4) $\gamma - 1$ Find the load factor Ω2 of the CL₂ = M/Ma O(2) = 0.23/9.14 = 0.025O(2 = 0.11/9.14 = 0.012static moment. Load factor of dynamic moment Pitching Examine Mep. $Me = 1/3 \cdot We \times 9.8 \frac{(Ln + An)}{}$ Mep = $1/3 \times 8.4 \times 9.8 \times \frac{(30 + 17)}{1000} = 1.3$ Find the dynamic moment Me (N·m). We = 4/100 x 0.5 x 420 = 8.4 Collision equivalent to impact We = $\delta \cdot W \cdot V$ A₂ = 17 δ: Bumper coefficient Meap = $1 \times 0.7 \times 9.14 = 6.40$ With urethane bumper (Standard) = 4/100 K = 1 Corrected value for moment $\gamma = 0.7$ center position distance An: Table (3) Mpmax = 9.14 O(3 = 1.3/6.40 = 0.20Find the allowable dynamic $Mea = K \cdot \gamma \cdot Mmax$ Yawing Examine Mey. moment Mea (N·m). Workpiece mounting coefficient K: Fig. (3) Mey = $1/3 \times 8.4 \times 9.8 \times \frac{(30 + 34)}{1000} = 1.8$ Allowable moment coefficient 7: Graph (2) Max. allowable moment Mmax: Graph (4) $A_4 = 34$ Find the load factor O(3 of the $CX_3 = Me/Mea$ Meay = 6.40 (Same value as Meap) dynamic moment. $\Omega_3' = 1.8/6.4 = 0.28$ 3-4 Sum of the load factors Use is possible if the sum of the $\sum C(n) = C(n) + C(n) + C(n) \le 1$ $\sum \Omega \ln = \Omega 1 + \Omega 2 + \Omega 2 + \Omega 3 + \Omega 3$ load factors does not exceed 1. $= 0.125 + 0.012 + 0.025 + 0.20 + 0.28 = 0.642 \le 1$ And it is possible to use.

Model Selection MXF Series

Fig. (1) Load Mass: W (kg)



Note) No need to consider this load factor in the case of using perpendicularly in a vertical position.

Fig. (3) Workpiece Mounting Coefficient: K

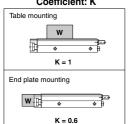


Table (2) Maximum Allowable Load Mass: Wmax (kg)

Model	Maximum allowable load mass
MXF8	0.6
MXF12	1
MXF16	2
MXF20	4

Table (3) Moment Center Position Distance

Compensation Amount: An (mm)												
	Moment cer	nter position	distance com	pensation a	mount (Refe	r to Fig. (2).)						
Model	A ₁	A ₂	Аз	A ₄	A 5	A 6						
MXF8	6 ^{Note)}	10	6 ^{Note)}	21	21	10						
MXF12	10	11	10	23	23	11						
MXF16	10	12	10	28	28	12						
MXF20	11	17	11	34	3/1	17						

SMC

Note) 16 mm for MXF8-10 only.

Model

MXF8

MXF12

MXF16

MXF20

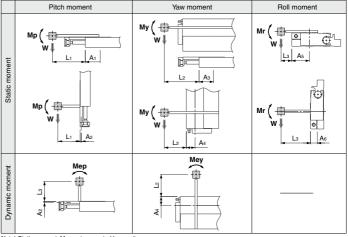
Table (4) Maximum Allowable Moment: Mmax (N·m)

Mandal			Stroke	(mm)		
Model	10	20	30	50	75	100
MXF8	0.56	0.78	0.98			
MXF12		1.65	2.22	3.34		
MXF16			3.41	5.69	7.96	
MXF20			6.66	9.14	13.70	18.27

Cumbal

Symbol		
Symbol	Definition	Unit
An (n = 1 to 6)	Correction values of moment center position distance	mm
E	Kinetic energy	J
Ea	Allowable kinetic energy	J
Emax	Max. allowable kinetic energy	J
Ln (n = 1 to 3)	Overhang	mm
M (Mp, My, Mr)	Static moment (pitch, yaw, roll)	N⋅m
Ma (Map, May, Mar)	Allowable static moment (pitch, yaw, roll)	N⋅m
Me (Mep, Mey)	Dynamic moment (pitch, yaw)	N⋅m
Mea (Meap, Meay)	Allowable dynamic moment (pitch, yaw)	N-m
Mmax (Mpmax, Mymax, Mrmax)	Maximum allowable moment (pitch, yaw, roll)	N⋅m
V	Collision speed	mm/s

Fig. (2) Overhang: Ln (mm), Correction Values for Moment Center Distance: An (mm)



Note) Static moment: Moment generated by gravity
Dynamic moment: Moment generated by impact when colliding with stopper Table (1) Maximum Allowable Kinetic

Energy: Emax (J)

Allowable kinetic energy

Rubber bumper

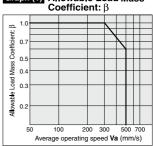
0.027

0.055

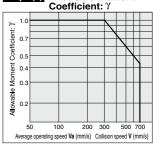
0.11

0.16

Graph (1) Allowable Load Mass Coefficient: B



Graph (2) Allowable Moment



Note) Use the average operating speed when calculating static moment. Use the collision speed when calculating dynamic moment.

Symbol	Definition	Unit
Va	Average operating speed	mm/s
W	Load mass	kg
Wa	Allowable load mass	kg
We	Mass equivalent to impact	kg
Wmax	Max. allowable load mass	kg
α	Load factor	
β	Allowable load mass coefficient	
γ	Allowable moment coefficient	
δ	Damper coeficient	
K	Workpiece mounting coefficient	

D-□ -X□

MXH MXS MXQ□

MXQ

MXF

MXW

MXJ

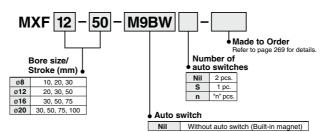
MXP

MXY

MTS



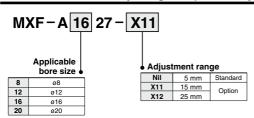
How to Order



^{*} For the applicable auto switch model, refer to the table below.

* Solid state auto switches marked with " " are produced upon receipt of order.

How to Order Stroke Adjusting Bolt (Accessory)



^{* -}X12 (adjustable range 25 mm) is not available in the MXF8/MXF12 series.

Applicable Auto Switches/Refer to pages 1119 to 1245 for the detailed specifications of auto switches.

						oad volta		Auto swit		Lead		onati	(m)										
Туре	Special function	Electrical entry	Indicator light	Wiring (Output)		DC	AC	Perpendicular	In-line	0.5 (Nil)	1	3	5	Pre-wired	Applio loa								
				3-wire (NPN)		5V.12V		M9NV	M9N	•	•	•	0	0	IC circuit								
switch				3-wire (PNP)		50,120		M9PV	M9P	•	•	•	0	0	IC circuit								
S				2-wire		12V		M9BV	M9B	•	•	•	0	0	_								
anto	D:		1	1	1						3-wire (NPN)		5V,12V	51/ 101/	M9NWV	M9NW	•	•	•		0	IC circuit	D 1
	(2-color indicator)		Yes	3-wire (PNP)	24V	30,120		M9PWV	M9PW	•	•	•	0	0	IC Circuit	Relay, PLC							
state				2-wire] [7	12V		M9BWV	M9BW	•	•	•	0	0	_								
		Vater resistant		3-wire (NPN)	5)/ 10)/	5V,12V	M9NAV*1	M9NA*1		0	•		0	IC circuit									
Solid	(2-color indicator)		3-wire (PNP)	1	50,120		50,120	50,120		M9PAV*1	M9PA*1	0	0	•	0	0	IC circuit						
ű	(2-color indicator)			2-wire		12V		M9BAV*1	M9BA*1	0	0	•	0	0	_								
Reed auto switch	Grommet	Yes	3-wire (Equiv. to NPN)	_	5V	_	A96V	A96	•	-	•	-	_	IC circuit									
D S		Grommet		2-wire	24V	V 12V 10	100V	A93V*2	A93	•	•	•	•	_	_	Relay,							
an			None	Z-Wire	24V	120	100V or less	A90V	A90	•	 -	•	_	_	IC circuit	PLC							

- *1 Water resistant type auto switches can be mounted on the above models, but in such case SMC cannot guarantee water resistance.
- *2 1 m type lead wire is only applicable to D-A93.
- * Lead wire length symbols: 0.5 m ······ Nil (Example) M9NW
 - 1 m M (Example) M9NWM 3 m L (Example) M9NWL
 - 3 m ······ L (Example) M9NWL 5 m ····· Z (Example) M9NWZ
- st Since there are other applicable auto switches than listed, refer to page 277 for details.
- * For details about auto switches with pre-wired connector, refer to pages 1192 and 1193
- * Auto switches are shipped together (not assembled).



OUT ← □

Specifications

Bore size (mm)	8	12	16 20				
Piping port size	M3 x 0.5		M5 x 0.8				
Fluid		А	ir				
Action		Double	acting				
Operating pressure		0.15 to 0).7 MPa				
Proof pressure		1.05	MPa				
Ambient and fluid temperature		−10 to 60 °C					
Operating speed range (Average operating speed) Note)		50 to 50	0 mm/s				
Cushion		Rubber bumpe	r on both sides				
Lubrication		Non-	lube				
Auto switch (Option)		Reed auto switch solid state auto switch (2-wire, 3-wire) adicator solid state auto switch (2-wire, 3-wi					
Stroke length tolerance		+1 m	m				
Stroke adjustment range	Exten	sion end 5 mm/	Retraction end	5 mm			
	•						

Note) Average operating speed: Speed that the stroke is divided by a period of time from starting the operation to reaching the end.

Theoretical Output

	meoretica	ai Output				ш				(N)	
	Bore size	Rod size	Operating Piston area		Operating pressure (MPa)						
	(mm)	(mm)	direction	(mm ²)	0.2	0.3	0.4	0.5	0.6	0.7	
	8	4	OUT	50	10	15	20	25	30	35	
		4	IN	38	8	11	15	19	23	27	
	12	6	OUT	113	23	34	45	57	68	79	
	12		IN	85	17	26	34	43	51	60	
	16	8	OUT	201	40	60	80	101	121	141	
s	10	0	IN	151	30	45	60	76	91	106	
.)	20	10	OUT	314	63	94	126	157	188	220	
٦	20	10	IN	236	47	71	94	118	142	165	

Note) Theoretical output (N) = Pressure (MPa) x Piston area (mm²)

Made to Order: Individual Specifications (For details, refer to pages 278 and 279.)

Symbol	Specifications
-X7	PTFE grease
-X9	Grease for food processing machines
-X11	Adjusting bolt, long specification (Adjustment range: 15 mm)
-X33	Without built-in auto switch magnet
-X39	Fluororubber seal
-X42	Anti-corrosive specifications for guide unit
-X45	EPDM seal

Standard Stroke

Model	Standard stroke (mm)
MXF8	10, 20, 30
MXF12	20, 30, 50
MXF16	30, 50,7 5
MXF20	30, 50, 75, 100

Moisture **Control Tube IDK Series**

When operating an actuator with a small diameter and a short stroke at a high frequency, the dew condensation (water droplet) may occur inside the piping depending on the conditions. Simply connecting the moisture control tube to the actuator will prevent dew condensation from occurring. For details, refer to the IDK series in the Best Pneumatics No. 6.

Weight (g)										
Model	Standard stroke (mm)									
Model	10	20	30	50	75	100				
MXF8	120	130	170	_	-	_				
MXF12	_	210	250	360	-	_				
MXF16	_	_	360	500	690	_				
MXF20	_	_	600	750	1060	1370				

-X□

MXH MXS $\mathsf{MXQ}\square$ MXQ MXF MXW

MXJ

MXP

MXY MTS





Table Deflection (Reference Values)

Table displacement due to pitch moment load

Table displacement when loads are applied to the section marked with the arrow at the full stroke.



Table displacement due to yaw moment load

Table displacement when loads are applied to the section marked with the arrow at the full stroke.

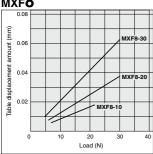


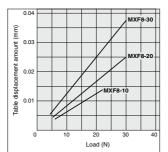
Table displacement due to roll moment load

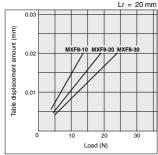
Table displacement of section A when loads are applied to the section F with the slide table retracted.

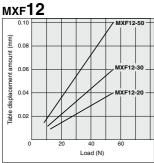


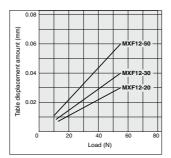
MXF8

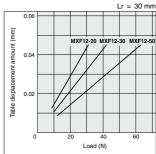












The graphs below show the table displacement when the static moment load is applied to the table. The graphs do not show the loadable mass. Refer to the Model Selection for the loadable mass.

Table displacement due to pitch moment load

Table displacement when loads are applied to the section marked with the arrow at the full stroke.



Table displacement due to yaw moment load

Table displacement when loads are applied to the section marked with the arrow at the full stroke.

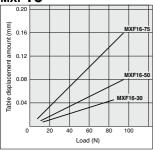


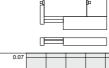
Table displacement due to roll moment load

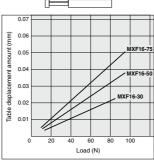
Table displacement of section A when loads are applied to the section F with the slide table retracted.

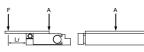


MXF16

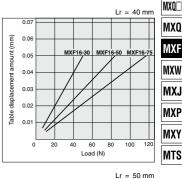


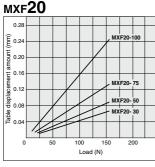


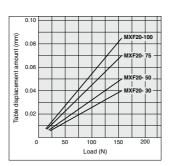


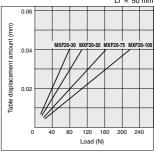


MXH MXS



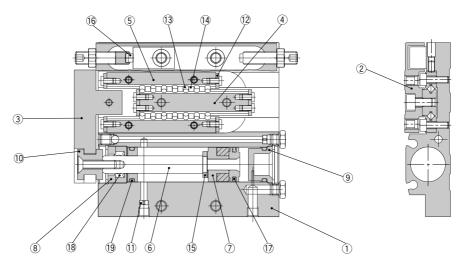








Construction



Component Parts

No.	Description	Massacial	Note
INO.	Description	Material	
1	Body	Aluminum alloy	Hard anodized
2	Table	Aluminum alloy	Hard anodized
3	End plate	Aluminum alloy	Hard anodized
4	Rail	Carbon tool steel	Heat treated
5	Guide	Carbon tool steel	Heat treated
6	Rod	Stainless steel	
7	Piston assembly	_	With magnet
8	Seal support	Brass	Electroless nickel plated
9	Head cap	Resin	
10	Floating bushing	Stainless steel	
11	Orifice	Brass	Electroless nickel plated
12	Roller stopper	Stainless steel	
13	Cylindrical roller	High carbon chrome bearing steel	
14	Roller spacer	Resin	
15	Rod bumper	Polyurethane	

Component Parts

No.	Description	Material	Note
16	Adjust bumper	Polyurethane	
17	Piston seal	NBR	
18	Rod seal	NBR	
19	O-ring	NBR	

Replacement Parts: Seal Kit

Bore size (mm)	Kit no.	Contents
8	MXF8-PS	
12	MXF12-PS	Set of nos. above 17 to 19
16	MXF16-PS	Set of nos. above (1) to (3)
20	MXF20-PS	

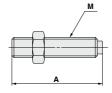
^{*} Seal kit includes (7, 18, 19). Order the seal kit, based on each bore size.

Replacement Part: Grease Pack

Applied part	Grease pack part no.
Guide	GR-S-010 (10g) GR-S-020 (20g)
Cylinder	GR-L-005 (5g) GR-L-010 (10g)

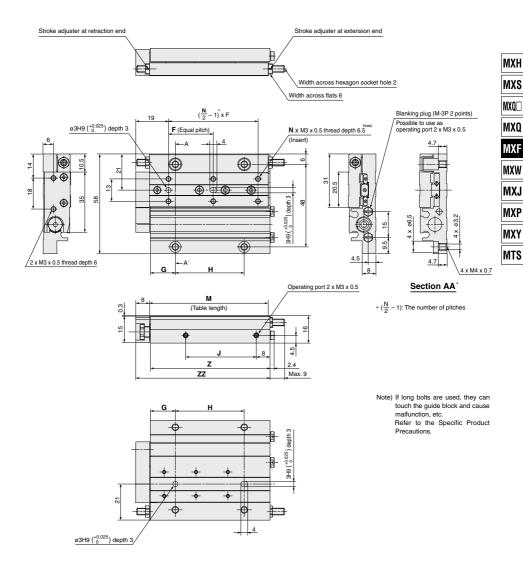
Dimensions: Stroke Adjustment Bolt





Applicable size	Model	Stroke adjustment range (mm)	A	В	С	М	
MXF8	MXF-A827	5	17	6	2	M4 x 0.7	
IVIAFO	MXF-A827-X11	15	27	ľ	-	IVI-4 X U.7	
MXF12	MXF-A1227	5	23.5	7	2.5	M5 x 0.8	
WAFIZ	MXF-A1227-X11	15	33.5	l ′	2.5	IVIS X U.O	
	MXF-A1627	5	26.5				
MXF16	MXF-A1627-X11	15	36.5	8	3	M6 x 1	
	MXF-A1627-X12	25	46.5				
	MXF-A2027	5	30				
MXF20	MXF-A2027-X11	15	40	12	4	M8 x 1	
	MXF-A2027-X12	25	50				

Dimensions: MXF8

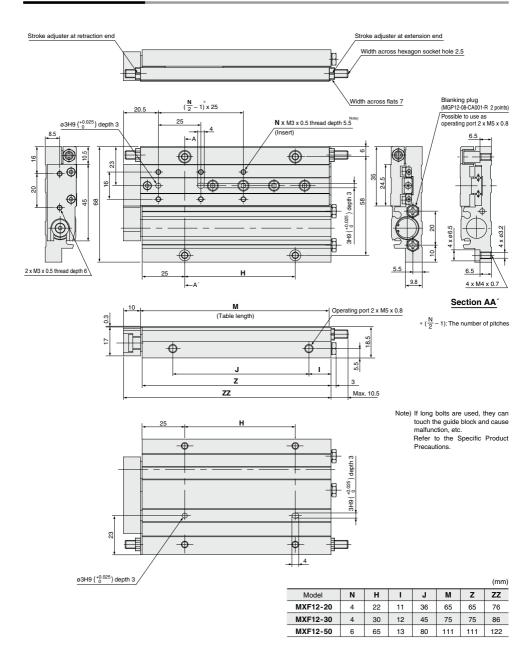


								(mm)
Model	F	N	G	Н	J	М	Z	ZZ
MXF8-10	20	4	13.5	22	21	49	49.5	58
MXF8-20	26	4	14.5	26	26	54	54.5	63
MXF8-30	26	6	14.5	40	41	69	69.5	78

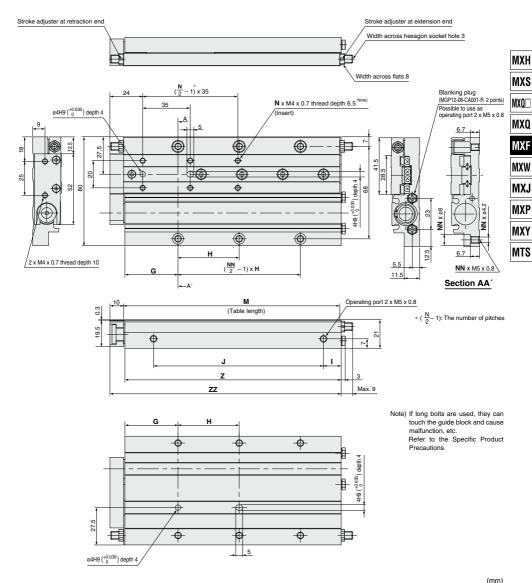
D-□ -X□

SMC

Dimensions: MXF 12



Dimensions: MXF16

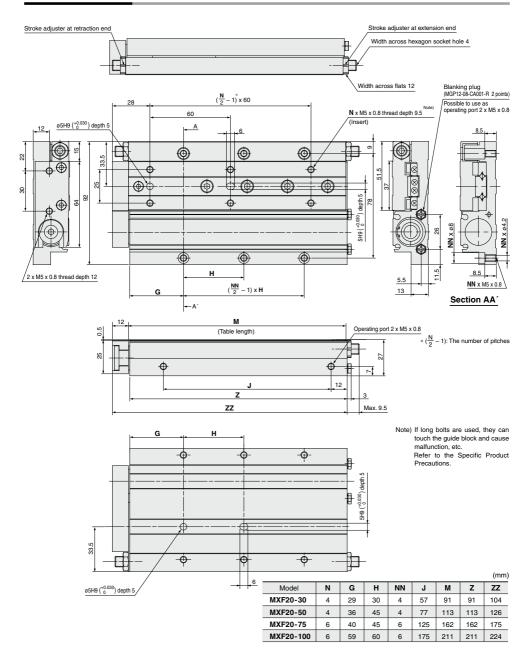


									(111111)
Model	N	G	Н	NN	1	J	М	Z	ZZ
MXF16-30	4	29	25	4	12	50	83	83	94
MXF16-50	6	29	55	4	12	80	113	113	124
MXF16-75	6	39	45	6	13	125	159	159	170



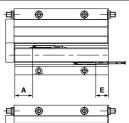


Dimensions: MXF20



Auto Switch Mounting

Auto Switch Proper Mounting Position (Detection at Stroke End)



				В				E							
Model	A		Stroke					Stroke							
		10	20	30	50	75	100	10	20	30	50	75	100		
MXF8	9.5	10	5	10	_	_	_	8 (5.5)	3 (0.5)	8 (5.5)	_	_	_		
MXF12	12	_	13.1	13.1	29.1	_	_	_	11.1 (8.6)	11.1 (8.6)	27.1 (24.6)	_	_		

Reed Auto Switch: D-A90, D-A93, D-A96, D-A90V, D-A93V, D-A96V (mm)

| 17.2 | -- | -- | 15.8 | 25.8 | 46.8 | -- | -- | -- | \(\frac{13.8}{(11.3)} \\ \frac{23.8}{(21.3)} \\ \frac{44.8}{(42.3)} \] 20.7 22.7 46.2 70.7

Solid State Auto Switch: D-M9B, D-M9N, D-M9P, D-M9BW, D-M9NW, D-M9PW, D-M9DA (mm)

				E	3				E					E (D-M9□A)					
Model	Α			Str	oke					Str	oke					Str	oke		
		10	20	30	50	75	100	10	20	30	50	75	100	10	20	30	50	75	100
MXF8	13.5	14	9	14	_	_	_	4	-1	4	_	_	_	2	-3	2	_	_	_
MXF12	16	_	17.1	17.1	33.1	_	_	_	7.1	7.1	23.1	_	_	_	5.1	5.1	21.1	_	_
MXF16	21.2	_	_	19.8	29.8	50.8	_	_	_	9.8	19.8	40.8	_	_	_	7.8	17.8	38.8	_
MXF20	23.4	ı	_	24.7	26.7	50.2	74.7	ı	_	14.7	16.7	40.2	64.7	-	_	12.7	14.7	38.2	62.7

Solid State Auto Switch: D-M9BV, D-M9NV, D-M9PV, D-M9BWV, D-M9PWV, D-M9PWV,

		В							E	•			E (D-M9□AV)						
Model	Α	Stroke					Stroke						Stroke						
		10	20	30	50	75	100	10	20	30	50	75	100	10	20	30	50	75	100
MXF8	13.5	14	9	14	_	_	_	6	1	6	_	_	_	4	-1	4	_	_	_
MXF12	16	_	17.1	17.1	33.1	_	_	_	9.1	9.1	25.1	_	_	_	7.1	7.1	23.1	_	_
MXF16	21.2	_	_	19.8	29.8	50.8	_	_	_	11.8	21.8	42.3	_	_	_	9.8	19.8	40.3	_
MXF20	23.4	ı	_	24.7	26.7	50.2	74.7	ı	ı	16.7	18.7	42.2	66.7	ı	_	14.7	16.7	40.2	64.7

* (): Denotes the values of D-A93.

Note) Adjust the auto switch after confirming the operating conditions in the actual setting.

Auto Switch Mounting

Auto Switch Mounting Tool

Caution When adjusting the auto switch mounting screw (included with auto switch), use a watchmaker's screwdriver with a handle about 5 to 6 mm in diameter.

Tightening Torque

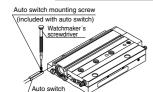
Tightening Torque of Auto Switch Mounting Screw (N-m)

	(11 11)
Auto switch model	Tightening torque
D-A9□(V)	0.10 to 0.20
D-M9□(V)	0.05 to 0.15
D-M9□W(V)	0.05 to 0.15
D-M9□A(V)	0.05 to 0.10

Operating Range

Auto switch model	Apı	Applicable bore size (mm)								
Auto switch model	8	12	16	20						
D-A9□(V)	4.5	5	6	7						
D-M9□, M9□V D-M9□W, M9□WV D-M9□A, M9□AV	3	3	4.5	5						

* Since the operating range is provided as a guideline including hysteresis, it cannot be guaranteed (assuming approximately ±30% dispersion). It may vary substantially depending on an ambient environment.



Other than the models listed in "How to Order", the following auto switches are applicable.

* Normally closed (NC = b contact) solid state auto switches (D-F9G/F9H types) and solid state auto switch D-F8 are also available. For details, refer to pages 1136 and 1137.

MXH MXS |MXO||

MXQ

MXF

MXW MXJ MXP MXY MTS



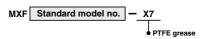
Made to Order: Individual Specifications 1

Please contact SMC for detailed dimensions, specifications and lead times.



1 PTFE Grease

Symbol -X7



PTFE grease is used for all parts that grease is applied.

Specifications

Туре	PTFE grease	
Bore size (mm)	8, 12, 16, 20	

 \ast Dimensions other than the above is the same as the standard type.

⚠ Warning

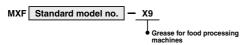
Precautions

Be aware that smoking cigarettes, etc. after your hands have come into contact with the grease used in this cylinder can create a gas that is hazardous to humans.

Symbol Sy

Grease for Food Processing Machines

-X9



Grease for food processing machines is used for all parts that grease is applied.

Specifications

Туре	Grease for food processing machines (NSF-H1 certified)/Aluminum complex soap base grease
Bore size (mm)	8, 12, 16, 20

* Dimensions other than the above is the same as the standard type.

⚠ Caution

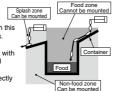
Do not use this cylinder in a food-related environment.

<Cannot be mounted>

Food zone..-Food may directly contact with this cylinder, and is treated as food products. <Can be mounted> Splash zone..-Food may directly contact with

this cylinder, but is not treated as food products.

Non-food zone...This cylinder do not directly contact food.



Symbol

-X33

3 Without Built-in Auto Switch Magnet

MXF Standard model no. — X33

Without built-in auto switch magnet

Auto switch magnet is not built in.

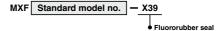
Specifications

Туре	Without built-in auto switch magnet	
Bore size (mm)	8, 12, 16, 20	
Auto switch	Not mountable	

* Dimensions other than the above is the same as the standard type

4 Fluororubber Seal

Symbol -X39



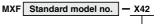
Change the materials for the piston seal, rod seal and O-rings to fluororubber.

Specifications

Туре	Fluororubber seal	
Bore size (mm)	8, 12, 16, 20	
Seal material	Fluororubber	

* Dimensions other than the above is the same as the standard type.

Anti-corrosive Specifications for Guide Unit -X42



 Anti-corrosive specifications for guide unit

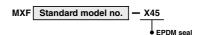
Rail and guide are given anti-corrosive treatment.

Specifications

-			
	Туре	Anti-corrosive guide unit	
	Bore size (mm)	8, 12, 16, 20	
ſ	Surface treatment	Special anti-corrosive treatment (2)	

- * 1 Dimensions other than the above is the same as the standard type.
- $\ast\,2$ Special anti-corrosive treatment makes the rail and the guide black.

6 EPDM Seal Symbol -X45



Change the materials for the piston seal, rod seal and O-rings to $\ensuremath{\mathsf{EPDM}}$.

Specifications

Туре	EPDM seal	
Bore size (mm)	8, 12, 16, 20	
Seal material	EPDM	
Grease	PTFE grease	

* Dimensions other than the above is the same as the standard type.

⚠ Warning

Precautions

Be aware that smoking cigarettes, etc. after your hands have come into contact with the grease used in this cylinder can create a gas that is hazardous to humans.

Made to Order: Individual Specifications 2 Please contact SMC for detailed dimensions, specifications and lead times.



MXH

MXS

 $\mathsf{MXQ}\square$

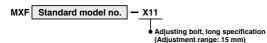
MXQ

MXF

MXW MXJ MXP MXY MTS

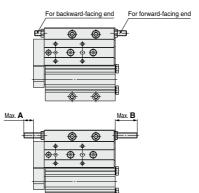
7 Adjusting Bolt, Long Specification (Adjustment range: 15 mm)

Symbol -X11



The average adjusting stroke range was extended from 5 mm to 15 mm with a long adjusting bolt.

Dimensions



		(mm)
Model	Α	В
MXF8	10	19
MXF12	10	20.5
MXF16	10	19
MXF20	10	19.5

D--X□



MXF Series Specific Product Precautions

Be sure to read this before handling the products. Refer to back page 50 for Safety Instructions and pages 3 to 12 for Actuator and Auto Switch Precautions.

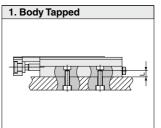
Mounting

⚠ Caution

- Do not scratch or dent the mounting side of the body, table or end plate. It causes play in the guide section and increases sliding resistance.
- Do not scratch or dent on the forward side of the rail or guide. It will result in looseness of the guide section and increased sliding resistance.
- Keep away from objects which are influenced by magnets.
 - As the piston part has magnets built-in, do not allow close contact with magnetic disks, magnetic cards or magnetic tapes. Data may be erased.
- 4. When mounting the body, use screws with appropriate length and do not exceed the maximum tightening torque. Tightening with a torque above the limit could malfunction. Whereas tightening insufficiently could result in misalignment or come to a droo.
- Be careful when adjusting stroke not to allow cylinder end plate to bottom out against cylinder body.

Mounting of Body

The slide table can be mounted from 2 directions. Select the best direction according to your application.



Model	Bolt	Maximum tightening torque (N·m)	Maximum screw-in depth L (mm)	Model	
MXF8	M4 x 0.7	2.1	4.7	MXF8	М
MXF12	M4 x 0.7	2.1	6.5	MXF12	M
MXF16	M5 x 0.8	4.4	6.7	MXF16	M

2. Body Through-hole		

Model	Bolt	tightening torque (N·m)	Maximum screw-in depth L (mm)
MXF8	M3 x 0.5	1.2	4.7
MXF12	M3 x 0.5	1.2	6.5
MXF16	M4 x 0.7	2.8	6.7
MXF20	M4 x 0.7	2.8	8.5

▲ Caution 0.02 mm or less of flatness is recommended for the body mounting surface. An uneven mounting surface of a workpiece or a base may cause vibration or increase sliding resistance.

8.5

Positioning

⚠ Caution

 The positioning hole on the table and on the bottom of the body does not have the same center. Positioning hole is meant to be for reproducibility for mounting and dismounting.

Selection

$oldsymbol{\Delta}$ Caution

 If intermediate stop by external stopper is done, avoid ejection.

If ejection occurs, it may cause damage. In the case the slide table is stopped an intermediate position by an external stopper then forwarded to the front, return the slide table to the back for just a moment to retract the stopper, then supply pressure to the opposite port to operate slide table.

Do not use it in such a way that excessive external force or impact force could work on it.

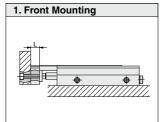
This could result in damage.

Mounting of Workpiece

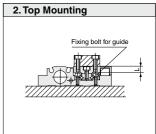
MXF20 M5 x 0.8

Work can be mounted on two sides of the body.

4.4



Model	Bolt	Maximum tightening torque (N·m)	Maximum screw-ii depth L (mm)	
MXF8	M3 x 0.5	0.9	6	
MXF12	M3 x 0.5	0.9	6	
MXF16	M4 x 0.7	2.1	10	
MXF20	M5 x 0.8	4.4	12	



Model	Bolt	Maximum tightening torque (N·m)	Maximum screw-in depth L (mm)
MXF8	M3 x 0.5	0.9	6.5
MXF12	M3 x 0.5	0.9	5.5
MXF16	M4 x 0.7	2.1	6.5
MXF20	M5 x 0.8	4.4	9.5

⚠ Caution

To prevent the workpiece holding bolts from touching the guide holding bolts, use bolts that are 0.5 mm or more shorter than the maximum screw-in depth.

If the bolts are too long, they hit the end plate and may cause malfunctions.