## Stroke Reading Cylinder and Counter

## CE Series



## Air Cylinder with Measurement Function/Stroke Reading Cylinder CE Series

## Counter CEU Series

## Measurement is possible throughout the full stroke range.

The home position can be anywhere $\longrightarrow$ When the counter is reset by pressing within the cylinder stroke. the cylinder rod to the reference plane, that point becomes the home position.

Can be used in an environment where the product is exposed to fluids (water, oil,coolant, etc.)

CEP1 Series With special scraper as standard


## System Configuration



# Achieve rationalization of production lines Stroke reading cylinder with position feedback 

## Tolerances of preset values can be set.

Tolerances can be set for preset values.

+ set tolerance, - set tolerance (separate settings)


## Multi-counter (CEU5)



- Output terminal: 5 points
- Number of output settings:

20 points (Bank switching)
31 points (Binary output)

- Communication function with RS-232C
- With BCD output (Option)
- Maximum counting speed 100 kHz
- Prescale function
- With multiplication switching
(1, 2, 4 multiplication)
- DIN rail mountable
- 6 digits count display


## Series Variations

## CE1 Series

| $\begin{gathered} \text { Bore size } \\ (\mathrm{mm}) \end{gathered}$ | Standard stroke (mm) |  |  |  |  |  |  |  |  |  |  |  | Manufacturable ${ }^{*}$ stroke range |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | 25 | 50 | 75 | 100 | 125 | 150 | 175 | 200 | 250 | 300 | 400 | 500 |  |
| 12 | $\bigcirc$ | - | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ |  |  |  |  |  |  | 25 to 150 |
| 20 | - | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | - | - |  |  |  |  | 25 to 300 |
| 32 |  | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ |  |  | 25 to 400 |
| 40 |  |  |  | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | 25 to 600 |
| 50 |  |  |  |  |  |  |  | $\bigcirc$ |  | $\bigcirc$ |  | $\bigcirc$ | 25 to 600 |
| 63 |  |  |  |  |  |  |  | $\bigcirc$ |  | $\bigcirc$ |  | $\bigcirc$ | 25 to 600 |

CEU5

| O Count data output | RS-232C+BCD | RS-232C |  |  |
| :---: | :---: | :---: | :---: | :---: |
| Poutpout tran sistor mode <br> supply volage | NPN | PNP | NPN | PNP |
| 100 to 240 VAC | $\bullet$ | $\bullet$ | $\bullet$ | $\bullet$ |
| 24 VDC | $\bullet$ | $\bullet$ | $\bullet$ | $\bullet$ |

Extension Cable


## CEP1 Series

| Bore size (mm) | Standard stroke (mm) |  |  |  | Manufacturable stroke range |
| :---: | :---: | :---: | :---: | :---: | :---: |
|  | 25 | 50 | 75 | 100 |  |
| 12 equivalent | $\bigcirc$ | - | $\bigcirc$ | $\bigcirc$ | 1 to 150 |
| 20 equivalent | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | 1 to 300 |

* Strokes other than standard strokes are available upon request. Consult with SMC separately.


## Application Examples

## Parts inspection

Measures the dimensions of parts, discriminates between good and defective articles, and prevents the mingling of different parts, etc.


## Confirmation of press-in

Can confirm the press-in of a hydraulic cylinder by detecting its stroke.
Even if the size of the workpiece changes, the point of press-in completion can be easily changed.


Discrimination of direction
Maintains a constant height of measuring workpiece height.


Detection of lifter position
Can continuously monitor a lifter's stroke.


Measurement of machining dimensions

Performs adjustment of machining depth, etc. by measuring the part dimensions before machining.


## Measurement Principle

The amount of rod movement in the stroke reading cylinder is detected using an MR element (magnetic resistance element) whose resistance value changes due to magnetic force. The detection unit containing this MR element is called the sensor head. An amplifying circuit and a dividing circuit are required to produce output which can be read by the counter, and these are attached to the cylinder case. The sensor head and amplifier section together are referred to as the sensor unit.


The stroke reading cylinder is equipped with the capability of outputting the piston stroke movement as a pulse signal. The measurement principle is as shown in the drawing below.


1. Scales of magnetic layers and non-magnetic layers are etched at a certain pitch on the piston rod.
2. With movement of the piston rod, a sin, cos 2-phase signal (Signal (1)) is received by the magnetic resistance element. For this wave form, 1 pitch ( 0.8 mm ) becomes exactly 1 cycle.
3. This is amplified and divided into $1 / 8$ parts. As a result, a $90^{\circ}$ phase difference pulse signal of $0.1 \mathrm{~mm} /$ pulse (Signal (2)) is output.
4. By measuring this pulse signal with the counter, it is possible to detect the piston position with a resolution of 0.1 mm .
5. In the case of the high precision stroke reading cylinder, the sin, cos 2-phase signal obtained in 2 is amplified and divided into $1 / 20$ parts. As a result, a $90^{\circ}$ phase difference pulse signal of 0.04 mm /pulse (Signal (2)) is output.
6. By multiplying this pulse signal by 4 with the counter, it is possible to detect the piston position with a resolution of 0.01 mm.

## A/B Phase Difference Output ( $90^{\circ}$ phase difference output)

When movement is expressed by a single line of pulses, it is impossible to accurately identify the current position, because pulse waves appear in both upward and downward directions.
Accordingly, in A/B phase difference output, two lines of pulses are provided, wherein one line detects the movement and the other distinguishes the direction.
The CE1 also employs this system.


## 4 Times Multiplication Function

This function increases resolution 4 times by counting 4 for each cycle of pulses, instead of counting 1 for each cycle as is normally the case. In principle, this function counts each time there is a rise or fall in either of the A or B phase pulses.


## Counting Speed (kHz, kcps)

Counting speed indicates the number of pulses that can be counted per second. If the stroke reading cylinder is operated at high speeds, pulse waves are output in shorter cycles. The counting speed of the counter must be higher than the pulse speed for the maximum piston speed when operating. Since the stroke reading cylinder outputs one pulse for each 0.1 mm of movement, 5,000 pulses will be output for each 500 mm of movement. Therefore, a speed of $500 \mathrm{~mm} / \mathrm{s}$ is equivalent to $5 \mathrm{kcps}(\mathrm{kHz})$, but a counting speed 2 to 3 times greater is recommended for actual operation.

## Accuracy

The accuracy is the difference between the dimensions based upon the signals of the stroke reading cylinder and the absolute dimensions.
The maximum display error that will appear on the counter's digital display is equal to twice ( $\pm 1$ count) the resolution when the home position is reset and when dimensions are measured.

# Specific Product Precautions 

## Be sure to read this before handling the products. <br> Refer to back page 50 for Safety Instructions and pages 3 to 12 for Actuator and Auto Switch Precautions.

## $\triangle$ Caution

## Operating Environment

Use in an environment where liquid (water, oil, coolant, etc.) splashes on the product may result in a malfunction; therefore, if using in such an environment, be sure to take measures such as installing a waterproof, dust-proof cover, etc. (CE1)

## Mounting

1. When screwing a nut or fitting, etc. onto the threaded section at the end of the piston rod, return the piston rod to its fully retracted position, and grasp the exposed portion of the rod across two parallel sides with a wrench. In the case of the high precision stroke reading cylinder, there are no parallel sides. Secure the workpiece with a double nut.
Note) Do not apply rotational torque to the piston rod.

2. Operate the cylinder in such a way that the load is always applied in the axial direction.

- In case the load is applied in a direction other than the axial direction of the cylinder, provide a guide to constrain the load itself.
- When mounting a cylinder, centering should be done carefully.

3. Avoid using the air cylinder in such a way that rotational torque would be applied to the piston rod.

4. Be careful to avoid scratches or dents, etc. on the sliding sections of the piston rod.

## Sensor Unit

1. The sensor unit is adjusted to an appropriate position at the time of shipment. Therefore, never detach the sensor unit from the body.
2. The sensor cable should not be pulled with a strong force.
3. Since the sensor for stroke reading cylinder adopts the magnetic method, it may result in malfunction if there is a strong magnetic field around the sensor. Use it under the external magnetic field with 14.5 mT or less.

> This is equivalent to a magnetic field of approximately 18 cm in radius from a welding area using a welding amperage of almost 15,000 amperes. To use the system in a magnetic field that exceeds this value, use a magnetic material to shield the sensor unit.
4. Switches or relays, etc. should not be installed in the power supply line (12 to 24 VDC).

## $\triangle$ Caution

## Effects of Noise

When the stroke reading cylinder is used near a motor, welding machine or other source of noise generation, there is a possibility of miscounting. In this case, noise should be suppressed as much as possible and the following countermeasure should be taken.

1. Connect the shield wire to FG (flame ground).
2. The maximum transmission distance for the stroke reading cylinder is 23 m , but since the output signal is a pulse output, the sensor cable should be wired separately from other power lines.

*When using SMC extension cable and counter.

## Noise Counter Measures

Methods of dealing with noise are given below.

1. Connect only the shield wire to FG (frame ground).
2. Use a power source separate from large motors and AC valves, etc.
3. Run the stroke reading cylinder's cable away from other power lines.
4. Install a noise filter in the 100 VAC power line, a varistor in the DC power supply of the sensor cable and a ferritic core in the signal line (sensor cable).


## <Counting speed of counter>

When the speed of the stroke reading cylinder is greater than the counting speed of the counter, the counter will miscount.
For CE1 (when measuring to 0.1 mm ), a counter should be used with a counting speed of $10 \mathrm{kHz}(\mathrm{kcps})$ or more.
And for CEP1 (when measuring to 0.01 mm ), use a counter with a counting speed of 50 kHz (kcps) or more when 4 times multiplication is input.

## <Malfunction due to lurching and bounding>

When lurching or bounding occurs at the beginning or end of stroke reading cylinder, or due to other causes, the cylinder speed momentarily increases, and there is a possibility of exceeding the counting speed of the counter or the response speed of the sensor, thereby causing a miscount.

## Handling of Technical Material

The operation manuals should be read before using the CEP1 series high precision stroke reading cylinder, CEU5 multi counter, CE1 scale cylinder and CEU1 3 point preset counter.

# High Precision Stroke Reading Cylinder Non－rotating Piston Type 

 CEP1 Series$\varnothing 12, \varnothing 20$
Note）CE－compliant：When connecting to a multi－counter（CEU5 $\square \square-D$ ， power supply voltage 24 VDC）． Refer to the multi－counter operation manual for details．


Applicable Auto Switches／Refer to pages 941 to 1067 for further information on auto switches．

| Type | Special function | Electrical entry |  | Wiring （Output） | Load voltage |  |  | Auto switch model |  | Lead wire length（ m ） |  |  |  | Pre－wired connector | Applicable load |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  |  |  | DC |  | AC | Perpendicular | In－line | $\begin{gathered} 0.5 \\ \text { (Nil) } \end{gathered}$ | $\begin{gathered} 1 \\ (\mathrm{M}) \end{gathered}$ | $\begin{gathered} 3 \\ \text { (L) } \end{gathered}$ | $\begin{gathered} 5 \\ (Z) \end{gathered}$ |  |  |  |
|  |  | Grommet |  | 3－wire（NPN） | 24 V | $5 \mathrm{~V}, 12 \mathrm{~V}$ | － | M9NV | M9N | $\bigcirc$ | － | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | IC circuit | Relay， PLC |
|  |  |  | $\stackrel{』}{\varnothing}$ | 3－wire（PNP） |  |  |  | M9PV | M9P | $\bigcirc$ | $\bigcirc$ | － | $\bigcirc$ | $\bigcirc$ |  |  |
|  |  |  |  | 2－wire |  | 12 V |  | M9BV | M9B | $\bigcirc$ | $\bigcirc$ | － | $\bigcirc$ | $\bigcirc$ | － |  |
|  |  |  |  | 3－wire（NPN） |  | $5 \mathrm{~V}, 12 \mathrm{~V}$ <br> 12 V |  | M9NWV | M9NW | － | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | IC circuit |  |
|  | （2－color indicator） |  |  | 3－wire（PNP） |  |  |  | M9PWV | M9PW | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ |  |  |
|  |  |  |  | 2－wire |  |  |  | M9BWV | M9BW | － | － | － | $\bigcirc$ | $\bigcirc$ | － |  |
|  |  |  |  | 3－wire（NPN） |  | $5 \mathrm{~V}, 12 \mathrm{~V}$ |  | M9NAV＊1 | M9NA＊1 | $\bigcirc$ | $\bigcirc$ | － | $\bigcirc$ | $\bigcirc$ | IC circuit |  |
|  | Water resistant <br> （2－color indicator） |  |  | 3－wire（PNP） |  |  |  | M9PAV＊1 | M9PA＊1 | $\bigcirc$ | $\bigcirc$ | － | $\bigcirc$ | $\bigcirc$ |  |  |
|  |  |  |  | 2－wire |  | 12 V |  | M9BAV＊${ }^{\text {＊}}$ | M9BA＊1 | $\bigcirc$ | $\bigcirc$ | － | $\bigcirc$ | $\bigcirc$ | － |  |
| 镸 |  | Grommet | $\frac{\stackrel{y}{\infty}}{\stackrel{\otimes}{<}}$ | 3－wire （NPN equivalent） | － | 5 V | － | A96V | A96 | － | － | － | － | － | IC circuit | － |
| 을 |  |  |  | 2－wire | 24 V | 12 V | 100 V | A93V＊2 | A93 | － | － | － | － | － | － | Relay， PLC |
| 菻 |  |  |  |  |  |  | 100 V or less | A90V | A90 | $\bigcirc$ | － | $\bigcirc$ | － | － | IC circuit |  |

1 Water resistant type auto switches can be mounted on the above models，but in such case SMC cannot guarantee water resistance．
Consult with SMC regarding water resistant types with the above model numbers．
＊2 1 m type lead wire is only applicable to D－A93．
＊Lead wire length symbols： $0.5 \mathrm{~m} . . . . . . .$. Nil
（Example）M9NW （Example）M9NWM
（Example）M9NWL
（Example）M9NWZ
＊Solid state auto switches marked with＂$\bigcirc$＂are produced upon receipt of order．

＊Refer to page 655 for details on other applicable auto switches than listed above．
＊For details about auto switches with pre－wired connector，refer to pages 1014 and 1015
＊Auto switches are shipped together（not assembled）．

Cylinder Specifications



## Symbol



Made to Order Specifications
Click here for details

| Symbol | Specifications |
| :--- | :--- |
| -XC22 | Fluororubber seals |

## Precautions

Sensor Specifications

| Cable | $ø 7,6$ core twisted pair shielded wire (Oil, Heat \& Flame resistant) |
| :---: | :---: |
| Maximum transmission distance | 23 m (when using SMC cable and counter) |
| Position detection method | Magnetic scale rod, sensor head <Incremental type> |
| Magnetic field resistance | 14.5 mT |
| Power supply | 10.8 to 26.4 VDC (Power supply ripple: $1 \%$ or less) |
| Current consumption | 50 mA |
| Resolution | 0.01 mm (With 4 times multiplication) |
| Accuracy | $\pm 0.02 \mathrm{~mm}^{(1)}$ (at $\left.20^{\circ} \mathrm{C}\right)$ |
| Output type | Open collector (24 VDC, 40 mA ) |
| Output signal | A/B phase difference output |
| Insulation resistance | $500 \mathrm{VDC}, 50 \mathrm{M} \Omega$ or more (between case and 12E) |
| Vibration resistance | 33.3 Hz 6.8 G 2 hrs. each in $\mathrm{X}, \mathrm{Y}$ directions 4 hrs. in Z direction based upon JIS D 1601 |
| Impact resistance | 30 G 3 times each in $\mathrm{X}, \mathrm{Y}, \mathrm{Z}$ directions |
| Enclosure | IP-67 (IEC Standard) ${ }^{(2)}$ |
| Extension Cable (Option) | CE1-R* $5 \mathrm{~m}, 10 \mathrm{~m}, 15 \mathrm{~m}, 20 \mathrm{~m}$ |

Note 1) This includes the digital display error of the counter (CEU5).
When strokes are over 100 mm , accuracy is $\pm 0.05 \mathrm{~mm}$.
Moreover, the overall accuracy after mounting on equipment will vary depending on mounting conditions and the environment. Therefore, the customer should calibrate the equipment as a whole.
Note 2) Except for the connector, the cylinder section is the equivalent of an SMC water resistant cylinder.

## Cylinder Stroke

| Model | Standard stroke (mm) |  |  |  | Manufacturable <br> stroke range |
| :---: | :---: | :---: | :---: | :---: | :---: |
|  | 25 | 50 | 75 | 100 |  |
| CEP1B12 |  |  |  |  | 1 to 300 |
| CEP1B20 |  |  |  |  |  |

* Strokes other than standard strokes are available upon request for special. Consult with SMC separately.

Weight (Sensor cable length 0.5 m , With connector, Without mounting bracket (both ends tapped))

| Bore size <br> $(\mathrm{mm})$ | Cylinder stroke (mm) |  |  |  |
| :---: | :---: | :---: | :---: | :---: |
|  | 25 | 50 | 75 | 100 |
| $\mathbf{1 2}$ | 0.36 | 0.4 | 0.44 | 0.48 |
| $\mathbf{2 0}$ | 0.56 | 0.62 | 0.68 | 0.74 |

Note) For the type with a sensor cable length of 0.5 m and without connector (CE1CD-CZ), 40 g is subtracted from the weight shown above. For the type with a sensor cable length of 3 m and connector (CE1DC-DL), add 160 g to the weight shown above. For the type with a sensor cable length of 3 m and without connector (CE1DC-ロZL), add 120 g to the weight shown above.

Auto Switch Proper Mounting Position

Regarding dimensions for the auto switch proper mounting position (at stroke end), refer to page 655.

## Mounting Bracket

(kg)

|  | 12 | 20 |
| :--- | :---: | :---: |
| Rod side flange (F) | 0.045 | 0.1 |
| Foot (L) | 0.035 | 0.045 |

Note 1) Including mounting bolt.
Note 2) The foot shows the weight for one set (2 pcs.).

## Rod End Nut Dimensions



| Part no. | Applicable bore size $(\mathrm{mm})$ | d | H | B | $\mathbf{C}$ | D |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| DA00032 | $\mathbf{1 2}$ | $\mathrm{M} 5 \times 0.8$ | 3 | 8 | 9.2 | 7.8 |
| DA00040 | $\mathbf{2 0}$ | $\mathrm{M} 8 \times 1.25$ | 5 | 13 | 15.0 | 12.5 |

## Electrical Wiring

## Output type

The output signal of the high precision stroke reading cylinder is $A / B$ phase difference output (open collector output) as shown in the figure below.
The relation between the movement distance and the signal output of the high precision stroke reading cylinder is that for each 0.04 mm of movement a one pulse signal is output to both output terminals A and B. In order to measure with a discrimination of 0.01 mm , a counter with a 4 times multiplication function (CEU5) is required.


## Input/Output

The input/output of the stroke reading cylinder is performed by a $\varnothing 7$ shielded twisted pair wire from the sensor section plus a connector.


Output circuit of stroke reading cylinder
Signal

| Contact signal | Wire color | Signal name |
| :---: | :---: | :---: |
| A | White | A phase |
| B | Yellow | B phase |
| C | Brown | COM (0 V) |
| D | Blue | COM (0 V) |
| E | Red | +12 to 24 V |
| F | Black | 0 V |
| G | - | Shield |

## CEP1 Series

Construction
$\varnothing 12, \varnothing 20$


Component Parts

| No. | Description | Material | Note |
| :---: | :--- | :---: | :---: |
| $\mathbf{1}$ | Cylinder tube | Aluminum alloy | Hard anodized |
| $\mathbf{2}$ | Rod cover | Aluminum alloy | Hard chrome plated |
| $\mathbf{3}$ | Head cover | Aluminum alloy | Hard anodized |
| $\mathbf{4}$ | Piston A | Aluminum alloy | Hard anodized |
| $\mathbf{5}$ | Piston B | Aluminum alloy | Hard anodized |
| $\mathbf{6}$ | Piston rod | Carbon steel | Hard chrome plated |
| $\mathbf{7}$ | Tie-rod | Carbon steel | Chromated |
| $\mathbf{8}$ | Tie-rod nut | Carbon steel | Chromated |
| $\mathbf{9}$ | Seal ring | Aluminum alloy | White anodized |
| $\mathbf{1 0}$ | Centering location ring | Aluminum alloy | White anodized |
| $\mathbf{1 1}$ | Rod end pin | Stainless steel | Quenched |
| $\mathbf{1 2}$ | Sensor unit | - | With or without connector |
| $\mathbf{1 3}$ | Wear ring | Special resin |  |
| $\mathbf{1 4}$ | Bushing | Cast iron |  |

Component Parts

| No. | Description | Material | Note |
| :---: | :--- | :---: | :---: |
| $\mathbf{1 5}$ | Magnet | - |  |
| $\mathbf{1 6}$ | Cross recessed countersunk head screw | Chromium molybdenum steel | Chromated |
| $\mathbf{1 7}$ | Hexagon socket head cap screw | Stainless steel |  |
| $\mathbf{1 8}$ | Hexagon nut | Carbon steel | Chromated |
| $\mathbf{1 9}$ | Spring washer | Steel wire | Chromated |
| $\mathbf{2 0}$ | Spring washer | Steel wire | Chromated |
| $\mathbf{2 1}$ | Hexagon nut | Carbon steel | Rod end nut |
| $\mathbf{2 2}$ | Sensor case gasket | NBR |  |
| $\mathbf{2 3}$ | Piston seal | NBR |  |
| 24 | Scraper | NBR |  |
| $\mathbf{2 5}$ | Tube gasket | NBR |  |
| 26 | Rod seal | NBR |  |
| $\mathbf{2 7}$ | O-ring | NBR |  |
| 28 | O-ring | NBR |  |

* Since there is a possibility of improper operation, please contact SMC regarding the replacement of seals.

Dimensions: ø12
Direct mounting, rod side tapped type:

## CEP1B12 - Stroke



CEP1


## CEP1 Series

## Dimensions: ø12

## Foot type:

CEP1L12 - Stroke


## Rod side flange type:

CEP1F12 - Stroke


## Dimensions: ø20

Direct mounting, rod side tapped type:

## CEP1B20 - Stroke



CEP1


## CEP1 Series

## Dimensions: ø20

Foot type:
CEP1L20 - Stroke


Rod side flange type:
CEP1F20 - Stroke


## CEP1 Series <br> Auto Switch Mounting

## Auto Switch Proper Mounting Position (Detection at Stroke End)



Auto Switch Proper Mounting Position (mm)

|  | $\begin{aligned} & \text { D-A9 } \square \\ & \text { D-A9 } \square \text { V } \end{aligned}$ |  | $\begin{aligned} & \text { D-M9 } \square \\ & \text { D-M9 } \square \mathbf{V} \\ & \text { D-M9 } \mathbf{W} \\ & \text { D-M9 } \quad \text { WV } \\ & \text { D-M9 } \\ & \text { D-M9 A } \end{aligned}$ |  |
| :---: | :---: | :---: | :---: | :---: |
|  | A | B | A | B |
| 12 | 75 | 8 | 79 | 12 |
| 20 | 82 | 12 | 86 | 16 |

Note) Adjust the auto switch after confirming the operating conditions in the actual setting.

## Operating Range

|  |  | (mm) |  |
| :--- | :---: | :---: | :---: |
| Auto switch model | Bore size |  |  |
|  | $\mathbf{1 2}$ | $\mathbf{2 0}$ |  |
| D-A9 $\square /$ A9 $\square \mathbf{V}$ | 6 | 10 |  |
| D-M9 $\square /$ M9 $\square$ V <br> D-M9 $\square$ W/M9 $\square \mathbf{W V}$ <br> D-M9 $\square$ A/M9 $\square$ AV | 3 | 4 |  |

* Since the operating range is provided as a guideline including hysteresis, it cannot be guaranteed (assuming approximately $\pm 30 \%$ dispersion). It may vary substantially depending on an ambient environment.

CEP1

I For solid state auto switches, auto switches with a pre-wired connector are also available. Refer to pages 1014 and 1015 for details.
I * Normally closed ( $\mathrm{NC}=\mathrm{b}$ contact), solid state auto switch (D-F9G/F9H type) are also available. For details, refer to page 959. I

# Stroke Reading Cylinder CE1 Series <br> $\varnothing 12, \varnothing 20, \varnothing 32, \varnothing 40, \varnothing 50, \varnothing 63$ 

Note) CE-compliant: When connecting to a multi-counter (CEU5 $\square \square-\mathrm{D}$, power supply voltage 24 VDC). Refer to the counter operation manual for details.

How to Order


Applicable Auto Switches/Refer to pages 941 to 1067 for further information on auto switches.

| Type | Special function | Electrical entry | $\begin{array}{\|l\|} \hline \text { 흔 } \\ \text { 흉 } \\ \text { 흔 } \end{array}$ | Wiring (Output) | Load voltage |  |  | Auto switch model |  | Lead wire length (m) |  |  |  |  | Pre-wired connector | Applicable load |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  |  |  | DC |  | AC | Perpendicular | In-line | $\begin{gathered} 0.5 \\ (\mathrm{Nil}) \end{gathered}$ | $\begin{array}{c\|} \hline 1 \\ (\mathrm{M}) \end{array}$ | $\begin{array}{\|c\|} \hline 3 \\ (\mathrm{~L}) \end{array}$ | $\begin{gathered} 5 \\ (\mathrm{Z}) \end{gathered}$ | None $(\mathrm{N})$ |  |  |  |
|  |  | Grommet |  | 3-wire (NPN) | 24 V | $\begin{gathered} 5 \mathrm{~V}, \\ 12 \mathrm{~V} \\ \hline \end{gathered}$ | - | M9NV | M9N | - | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | - | $\bigcirc$ | IC circuit | Relay, PLC |
|  |  |  |  | 3-wire (PNP) |  |  |  | M9PV | M9P | - | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | - | $\bigcirc$ |  |  |
|  |  |  |  | 2-wire |  | 12 V |  | M9BV | M9B | - | - | $\bigcirc$ | $\bigcirc$ | - | $\bigcirc$ | - |  |
|  |  | Connector |  |  |  |  |  | J79C | - | - | - | - | $\bigcirc$ | $\bigcirc$ | - |  |  |
|  | Diagnostic indication (2-color indicator) | Grommet | $\stackrel{\varnothing}{\succ}$ | 3-wire (NPN) |  | 5 V , |  | M9NWV | M9NW | - | - | - | $\bigcirc$ | - | $\bigcirc$ | IC circuit |  |
|  |  |  |  | 3-wire (PNP) |  | 12 V |  | M9PWV | M9PW | - | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | - | $\bigcirc$ |  |  |
|  |  |  |  | 2-wire |  | 12 V |  | M9BWV | M9BW | - | $\bullet$ | $\bullet$ | $\bigcirc$ | - | $\bigcirc$ | - |  |
|  | Water resistant (2-color indicator) |  |  | 3-wire (NPN) |  | 5 V , |  | M9NAV*1 | M9NA* ${ }^{\text {¹ }}$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | - | $\bigcirc$ | IC circuit |  |
|  |  |  |  | 3-wire (PNP) |  | 12 V |  | M9PAV*1 | M9PA*1 | $\bigcirc$ | $\bigcirc$ | - | $\bigcirc$ | - | $\bigcirc$ |  |  |
|  |  |  |  | 2-wire |  | 12 V |  | M9BAV*1 | M9BA*1 | $\bigcirc$ | $\bigcirc$ | - | $\bigcirc$ | - | $\bigcirc$ | - |  |
|  | $\underset{\substack{\text { With diagnostic output } \\ \text { (2-color indicator) }}}{\text { ( }{ }^{\text {a }} \text { ( }}$ |  |  | 4-wire |  | $5 \mathrm{~V}, 12 \mathrm{~V}$ |  | - | F79F | - | - | $\bullet$ | $\bigcirc$ | - | $\bigcirc$ | IC circuit |  |
| $\underset{\sim}{0}$ | - | Grommet | $\stackrel{\varnothing}{\underset{\sim}{\infty}}$ | 3-wire (NPN equivalent) | - | 5 V | - | A96V | A96 | - | - | - | - | - | - | IC circuit | - |
|  |  |  |  | 2-wire |  | - | 200 V | A72 | A72H | - | - | $\bigcirc$ | - | - | - | - | Relay, PLC |
|  |  |  |  |  | 24 V | 12 V | 100 V | A93V*2 | A93 | - | - | $\bigcirc$ | - | - | - |  |  |
|  |  |  | 2 |  |  | $5 \mathrm{~V}, 12 \mathrm{~V}$ | 100 V or less | A90V | A90 | - | - | $\bigcirc$ | - | - | - | IC circuit |  |
|  |  | Connector | 嵥 |  |  | 12 V | - | A73C | - | $\bigcirc$ | - | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | - | - |  |
|  |  |  | \% |  |  | $5 \mathrm{~V}, 12 \mathrm{~V}$ | 24 V or less | A80C | - | - | - | $\bigcirc$ | - | $\bigcirc$ | - | IC circuit |  |
|  | (iagnostic indication | Grommet | 范 |  |  | - | - | A79W | - | - | - | $\bigcirc$ | - | - | - | - |  |

*1 Water resistant type auto switches can be mounted on the above models, but in such case SMC cannot guarantee water resistance. Consult with SMC regarding water resistant types with the above model numbers.
*2 1 m type lead wire is only applicable to D-A93.

* Lead wire length symbols: 0.5 m ..........Nil (Example) M9NW * Solid state auto switches marked with " $\bigcirc$ " are produced upon receipt of order.

| $1 \mathrm{~m} \ldots \ldots . . . .$. | M |
| ---: | :--- | (Example) M9NWM

* Refer to page 666 for details on other applicable auto switches than listed above.
* For details about auto switches with pre-wired connector, refer to pages 1014 and 1015.
* When $\mathrm{D}-\mathrm{A9} \square(\mathrm{~V}) / \mathrm{M} 9 \square(\mathrm{~V}) / \mathrm{M} 9 \square \mathrm{~W}(\mathrm{~V}) / \mathrm{M} 9 \square \mathrm{~A}(\mathrm{~V}) \mathrm{L}$ types with $ø 32$ to $\varnothing 63$ are mounted on a side other than the port side, order auto switch mounting brackets.
separately. Refer to page 666 for details.
* Auto switches are shipped together (not assembled).


## Cylinder Specifications




## Symbol



## Mounting Bracket Part No.

| Bore size <br> $(\mathrm{mm})$ | Foot Note 1$)$ Flange | Double <br> clevis |  |
| :---: | :---: | :---: | :---: |
| $\mathbf{1 2}$ | CQ-L012 | CQ-F012 | CQ-D012 |
| $\mathbf{2 0}$ | CQ-L020 | CQ-F020 | CQ-D020 |
| $\mathbf{3 2}$ | CQ-L032 | CQ-F032 | CQ-D032 |
| $\mathbf{4 0}$ | CQ-L040 | CQ-F040 | CQ-D040 |
| $\mathbf{5 0}$ | CQ-L050 | CQ-F050 | CQ-D050 |
| $\mathbf{6 3}$ | CQ-L063 | CQ-F063 | CQ-D063 |

Note 1) When ordering the foot bracket, order 2 pcs. per cylinder.
Note 2) Parts belonging to each bracket are as follows.
Foot, Flange/Body mounting bolts Double clevis/Clevis pin, type C retaining ring for shaft, Body mounting bolts

Sensor Specifications

| Cable | ø7, 6 core twisted pair shielded wire (Oil, Heat \& Flame resistant cable) |
| :---: | :---: |
| Maximum transmission distance | 23 m (when using SMC cable and counter) |
| Position detection method | Magnetic scale rod <br> <Non-rotating> Sensor head <br> <Incremental type> |
| Magnetic field resistance | 14.5 mT |
| Power supply | 10.8 to 26.4 DC (Power supply ripple: $1 \%$ or less) |
| Current consumption | 40 mA |
| Resolution | $0.1 \mathrm{~mm} /$ pulse |
| Accuracy | $\pm 0.2 \mathrm{~mm}\left(\mathrm{at} 20^{\circ} \mathrm{C}\right){ }^{(1)}$ |
| Output type | Open collector (24 VDC, 40 mA ) |
| Output signal | A/B phase difference output |
| Insulation resistance | $50 \mathrm{M} \Omega$ or more ( 500 VDC measured via megohmmeter) (between case and 12E) |
| Vibration resistance | 33.3 Hz, 6.8 G 2 hrs. each in $X, Y$ directions 4 hrs. in $Z$ direction based upon JIS D 1601 |
| Impact resistance | 30 G 3 times each in $\mathrm{X}, \mathrm{Y}, \mathrm{Z}$ directions |
| Enclosure | IP65 (IEC Standard) ${ }^{(2)}$ Except connector part |
| Extension cable (Option) | $5 \mathrm{~m}, 10 \mathrm{~m}, 15 \mathrm{~m}, 20 \mathrm{~m}$ |

Note 1) This includes the digital display error of the counter (CEU5).
Moreover, the overall accuracy after mounting on equipment will vary depending on the mounting conditions and the environment. Therefore, the customer should calibrate the equipment as a whole. Note 2) The cylinder section does not have a water resistant enclosure.

## Cylinder Stroke

| Bore size (mm) | Standard Stroke (mm) |  |  |  |  |  |  |  |  |  |  |  | Manufacturable stroke range |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | 25 | 50 | 75 | 100 | 125 | 150 | 175 | 200 | 250 | 300 | 400 | 500 |  |
| 12 | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | - | $\bigcirc$ | $\bigcirc$ | - | - | - | - | - | - | 25 to 150 |
| 20 | $\bigcirc$ | $\bigcirc$ | - | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | - | - | - | - | 25 to 300 |
| 32 | - | $\bigcirc$ | - | $\bigcirc$ | - | - | - | - | - | $\bigcirc$ | - | - | 25 to 400 |
| 40 | - | - | - | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | - | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | - | 25 to 600 |
| 50 | - | - | - | - | - | - | - | $\bigcirc$ | - | $\bigcirc$ | - | - | 25 to 600 |
| 63 | - | - | - | - | - | - | - | - | - | - | - | - | 25 to 600 |

[^0]Weight（Sensor cable length 0.5 m ，With connector，Without mounting bracket（both ends tapped））

| $\begin{aligned} & \text { Bore size } \\ & (\mathrm{mm}) \end{aligned}$ | Cylinder stroke（mm） |  |  |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | 25 | 50 | 75 | 100 | 125 | 150 | 175 | 200 | 250 | 300 | 400 | 500 |
| 12 | 0.28 | 0.32 | 0.35 | 0.39 | 0.42 | 0.46 | － | － | － | － | － | － |
| 20 | 0.48 | 0.55 | 0.62 | 0.69 | 0.76 | 0.83 | 0.9 | 0.97 | － | － | － | － |
| 32 | － | 0.84 | 0.95 | 1.05 | 1.16 | 1.26 | 1.37 | 1.48 | 1.69 | 1.9 | － | － |
| 40 | － | － | － | 1.58 | 1.71 | 1.83 | 1.96 | 2.08 | 2.33 | 2.58 | 3.08 | 3.58 |
| 50 | － | － | － | － | － | － | － | 3.26 | － | 3.96 | － | 5.36 |
| 63 | － | － | － | － | － | － | － | 4.04 | － | 4.84 | － | 6.44 |

Note 1）For the type with a sensor cable length of 0.5 m and without connector（CE1口ロ－$\square \mathrm{Z}$ ）， 40 g is subtracted from the weight shown above．
For the type with a sensor cable length of 3 m and connector（CE1ロप－$\square \mathrm{L}$ ），add 160 g to the weight shown above．
For the type with a sensor cable length of 3 m and without connector（CE1 $\square \square-\square Z \mathrm{Z}$ ），add 120 g to the weight shown above．
Note 2）The mounting bracket weight is shared with the compact cylinder（CQ2 series）．So，refer to the CQ2 series catalog．

## Rod End Nut Dimensions

（ 1 pc ．is attached as standard．）
Material ø12，20：Steel
$\varnothing 32$ to $\varnothing 63$ ：Rolled steel

Auto Switch Proper Mounting Position

Regarding dimensions for the auto switch proper mounting position（at stroke end），refer to page 665.

## Electrical Wiring

## Output type

The output signal of the stroke reading cylinder is $A / B$ phase difference output（open collector output）as shown in the figure below．
The relation between the movement distance and the signal output of the stroke reading cylinder is that for each 0.1 mm of movement a one pulse signal is output to both output terminals A and B ．
Furthermore，the maximum response speed of the sensor for the stroke reading cylinder is at a maximum cylinder speed of $1500 \mathrm{~mm} / \mathrm{s}(15 \mathrm{kcps})$ ．


## Input／Output

The input／output of the stroke reading cylinder is performed by a $\varnothing 7$ shielded twisted pair wire from the sensor section plus a connector．


## Output circuit of stroke reading cylinder

Signal

| Contact signal | Wire color | Signal name |
| :---: | :---: | :---: |
| A | White | A phase |
| B | Yellow | B phase |
| C | Brown | COM（0 V） |
| D | Blue | COM（0 V） |
| E | Red | +12 to 24 V |
| F | Black | 0 V |
| G | - | Shield |

# Stroke Reading Cylinder 

CE1 Series

Construction

ø40 to ø63


## Component Parts

| No. | Description | Material | Note |
| :---: | :---: | :---: | :---: |
| 1 | Cylinder body | Aluminum alloy |  |
| 2 | Rod cover | Brass | $\varnothing 12$ to ø20 |
|  |  | Aluminum alloy | ø32 to ø63 |
| 3 | Head cover | Aluminum alloy |  |
| 4 | Piston | Aluminum alloy |  |
| 5 | Piston rod | Stainless steel |  |
| 6 | Rod cover disk | Aluminum alloy |  |
| 7 | Sensor unit | - |  |
| 8 | Sensor setting bracket | Stainless steel |  |
| 9 | Sensor setting piece assembly | - | ø20 to ø63 |
| 10 | Pin | Stainless steel | $\varnothing 12$ to ø32 |
| 11 | Sensor guide | Lead-bronze casted | ø32 to ø63 |
| 12 | Case setting nut | Carbon steel | ø32 to ø63 |
| 13 | Cushion ring A | Rolled steel | $\varnothing 40$ to ø63 |
| 14 | Cushion ring B | Rolled steel | ø40 to ø63 |
| 15 | Cushion valve | - | $\varnothing 40$ to ø63 |
| 16 | Piston nut | Rolled steel | $\varnothing 40$ to ø63 |
| 17 | Port joint | Stainless steel | $\varnothing 40$ to ø63 |
| 18 | Wear ring | Resin | ø40 to ø63 |

Component Parts

| No. | Description | Material | Note |
| :---: | :---: | :---: | :---: |
| 19 | Rod end nut | Carbon steel |  |
| 20 | Sensor setting plate | Cold rolled special steel strip |  |
| 21 | Type C retaining ring | Carbon steel |  |
| 22 | Magnet | - |  |
| 23 | Round head Phillips screw | Carbon steel wire |  |
| 24 | Cross recessed countersunk head screw | Carbon steel wire |  |
| 25 | Hexagon socket head cap screw | Chromium molybdenum steel |  |
| 26 | Spring washer | Steel wire |  |
| 27 | Case gasket | NBR |  |
| 28 | Case screw gasket | NBR |  |
| 29 | Piston seal | NBR |  |
| 30 | Rod seal | NBR |  |
| 31 | Gasket | NBR |  |
| 32 | Cushion seal | NBR |  |
| 33 | Piston gasket | NBR |  |
| 34 | Port seal | NBR |  |
| 35 | Joint seal | NBR |  |
| 36 | Valve seal | NBR |  |
| 37 | Valve retainer seal | NBR |  |
| 38 | Spacer for switch type | Aluminum alloy | $ø 12$ |

* Since there is a possibility of improper operation, please contact SMC regarding the replacement of seals.


## CE1 Series

Dimensions: ø12, ø20
Both ends tapped type:

## CE1B Bore size - Stroke



| Bore size (mm) | Standard stroke | A | B | C | D | E | G | H | I | K | L | M |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 12 | 25, 50, 75, 100, 125, 150 | 93.5 | 69 | 15 | 6 | 25 | 42.5 | M5 $\times 0.8$ | 16 | 5.2 | 24.5 | 15.5 |
| 20 | 25, 50, 75, 100, 125, 150, 175, 200 | 106 | 78 | 15.5 | 10 | 36 | 53.5 | M8 $\times 1.25$ | 10 | 8 | 28 | 25.5 |


| Bore size (mm) | $\mathbf{N}$ | $\mathbf{O}$ | $\mathbf{P}$ | $\mathbf{Q}$ | $\mathbf{R}$ | $\mathbf{T}^{*}$ | $\mathbf{V}$ | $\mathbf{Y}$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $\mathbf{1 2}$ | - | $\mathrm{M} 4 \times 0.7$ | $\mathrm{M} 5 \times 0.8$ | 47 | 7 | 53.5 | 22 | 7 |
| $\mathbf{2 0}$ | 5.5 | $\mathrm{M} 6 \times 1$ | $\mathrm{M} 5 \times 0.8$ | 50 | 15 | 62.5 | 36 | 5 |

[^1]
## Foot type:

## CE1L Bore size - Stroke



## Rod side flange type:

## CE1F Bore size - Stroke



Head side flange type:
CE1G Bore size Stroke


## Double clevis type:



| Bore size (mm) | Common | Foot type |  |  |  |  |  |  |  |  |  |  | Rod side flange, Head side flange |  |  |  |  | $\begin{array}{\|c\|} \hline \text { Head side flange } \\ \hline \mathbf{A} \\ \hline \end{array}$ | Double clevis type |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | 0 | A | LA | LB | LD | LE | LH | LL | LS | LX | LY | LZ | FD | FL | FV | FX | FZ |  | A | CD | CL | CU | CW | CX | CZ | RR |
| 12 | M $4 \times 0.7$ | 106 | 4.5 | 8 | 4.5 | 29.5 | 17 | 2 | 85 | 34 | 52 | 44 | 4.5 | 5.5 | 25 | 45 | 55 | 99 | 113.5 | 5 | 107.5 | 7 | 14 | 5 | 10 | 6 |
| 20 | M6 $\times 1$ | 121 | 5.8 | 9.2 | 6.6 | 42 | 24 | 3.2 | 96.4 | 48 | 66.5 | 62 | 6.6 | 8 | 39 | 48 | 60 | 114 | 133 | 8 | 124 | 12 | 18 | 8 | 16 | 9 |

## CE1 Series

Dimensions: ø32, ø40, ø50, ø63
Both ends tapped type:

## CE1B Bore size - Stroke



| Bore size (mm) | Standard stroke | A | B | C | D | E | F | G | H | I | J | K |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 32 | 50, 75, 100, 125, 150, 175, 200, 250, 300 | 131 | 90 | 27 | 16 | 45 | 49.5 | 64 | M14 $\times 1.5$ | 14 | 4.5 | 14 |
| 40 | 100, 125, 150, 175, 200, 250, 300,400,500 | 177 | 136 | 27 | 16 | 52 | 57 | 71.5 | M14 $\times 1.5$ | 24 | 5 | 14 |
| 50 | 200, 300, 500 | 193 | 144 | 32 | 20 | 64 | 71 | 85.5 | M18 $\times 1.5$ | 25.5 | 7 | 18 |
| 63 | 200, 300, 500 | 194 | 145 | 32 | 20 | 77 | 84 | 98.5 | M18 $\times 1.5$ | 21 | 7 | 18 |


| Bore size (mm) | $\mathbf{L}$ | $\mathbf{M}$ | $\mathbf{N}$ | $\mathbf{O}$ | $\mathbf{P}$ | $\mathbf{Q}$ | $\mathbf{T}^{*}$ | $\mathbf{X}$ | $\mathbf{Z}$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $\mathbf{3 2}$ | 41 | 34 | 5.5 | $\mathrm{M} 6 \times 1$ | Rc $1 / 8$ | 56 | 57.5 | 30 | 14 |
| $\mathbf{4 0}$ | 41 | 40 | 5.5 | $\mathrm{M} 6 \times 1$ | Rc $1 / 8$ | 62 | 64.5 | 30 | 14 |
| $\mathbf{5 0}$ | 49 | 50 | 6.6 | $\mathrm{M} 8 \times 1.25$ | Rc $1 / 4$ | 61.5 | 76.5 | 35 | 19 |
| $\mathbf{6 3}$ | 49 | 60 | 9 | $\mathrm{M} 10 \times 1.5$ | Rc $1 / 4$ | 64 | 89.5 | 35 | 19 |

* For rod end nut accessory bracket, refer to page 658. * Dimensions for auto switch model D-F79W.


## Foot type:

## CE1L Bore size - Stroke



## Rod side flange type:

## CE1F Bore size-Stroke



## Head side flange type:

## CE1G Bore size - Stroke



## Double clevis type:

## CE1D Bore size - Stroke



| Bore size (mm) | Common | Foot type |  |  |  |  |  |  |  |  |  |  | Rod side flange, Head side flange |  |  |  |  |  |  |  | $\begin{array}{\|c\|} \hline \begin{array}{c} \text { Rod side } \\ \text { flange } \end{array} \\ \hline \mathbf{A} \end{array}$ | $\begin{array}{\|c\|} \hline \begin{array}{c} \text { Heads side } \\ \text { flange } \end{array} \\ \hline \mathbf{A} \end{array}$ | Double clevis type |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | 0 | A | LA | LB | LD | LE | LH | LS | LT* | LX | LY | LZ | FD | FG | FL | FT* | FV | FX | FZ | M |  |  | A | CD | CL | CU | CW | CX | CZ | RR | T |
| 32 | M6x 1 | 148 | 5.8 | 11.2 | 6.6 | 52.5 | 30 | 1124 | 65 | 57 | 72.5 | 71 | 5.5 | 69.5 | 8 | 59 | 48 | 56 | 65 | 34 | 131 | 139 | 161 | 10 | 151 | 14 | 20 | 18 | 36 | 10 | 57.5 |
| 40 | M6 x 1 | 195.2 | 7 | 11.2 | 6.6 | 59 | 33 | 158.4 | 71.5 | 64 | 79.5 | 78 | 5.5 | 76.5 | 8 | 65.5 | 54 | 62 | 72 | 40 | 177 | 185 | 209 | 10 | 199 | 14 | 22 | 18 | 36 | 10 | 64.5 |
| 50 | M $8 \times 1.25$ | 215.7 | 8 | 14.7 | 9 | 71 | 39 | 173.4 | 83.5 | 79 | 94 | 95 | 6.6 | 91 | 9 | 78 | 67 | 76 | 89 | 50 | 193 | 202 | 235 | 14 | 221 | 20 | 28 | 22 | 44 | 14 | 76.5 |
| 63 | M10 $\times 1.5$ | 219.2 | 9 | 16.2 | 11 | 84.5 | 46 | 177.4 | 97 | 95 | 109.5 | 113 | 9 | 107 | 9 | 91 | 80 | 92 | 108 | 60 | 194 | 203 | 238 | 14 | 224 | 20 | 30 | 22 | 44 | 14 | 89.5 |

[^2]
## CE1 Series <br> Auto Switch Mounting

Auto Switch Proper Mounting Position (Detection at Stroke End) and Its Mounting Height

| D-A9 | D-A9 $\square \mathbf{V}$ |
| :--- | :--- |
| D-M9 | D-M9 |
| D-M9 | D-M9 |
| D-M9 | DAV |
|  | D-M9 $\square$ AV |

$\varnothing 12$ to $\varnothing 20$

$\varnothing 32$ to $\varnothing 63$

| D-A9 | D-A9 $\square \mathbf{V}$ |
| :--- | :--- |
| D-M9 | D-M9 |
| D-M9 | D |
| D-M9 $\square$ A | D-M9 |
|  |  |



| D-A7ロ | D-F7NT |
| :--- | :--- |
| D-A80 | D-F7BA |
| D-A7ロH | D-A73C |
| D-A80H | D-A80C |
| D-F7■ | D-J79C |
| D-J79 | D-A79W |
| D-F7■W | D-F7■WV |
| D-J79W | D-J7■V |
| D-F79F | D-F7BAV |

$\varnothing 12$ to $\varnothing 20$

$\varnothing 32$ to $\varnothing 63$


## Auto Switch Proper Mounting Position（Detection at Stroke End）and Its Mounting Height

Auto Switch Proper Mounting Position

|  | $\begin{aligned} & \text { D-A9 } \square \\ & \text { D-A9 } \square \text { V } \end{aligned}$ |  | $\begin{aligned} & \text { D-M9 } \square \\ & \text { D-M9 } \square \mathbf{V} \\ & \text { D-M9 } \square \mathbf{W} \\ & \text { D-M9 } \square \mathbf{W V} \\ & \text { D-M9 } \square \mathbf{A} \\ & \text { D-M9 } \square \mathbf{A V} \end{aligned}$ |  | $\begin{aligned} & \text { D-A73 } \\ & \text { D-A80 } \end{aligned}$ |  | D－A72／A7■H／A80H <br> D－A73C／A80C／F7口 <br> D－F79F／J79／F7■V <br> D－J79C／F7口W <br> D－J79W／F7口WV <br> D－F7BAV／F7BA |  | D－F7NT |  | D－A79W |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | A | B | A | B | A | B | A | B | A | B | A | B |
| 12 | 37 | 5.5 | 41 | 9.5 | 38 | 6.5 | 38.5 | 7 | 43.5 | 12 | 35.5 | 4.5 |
| 20 | 46 | 12 | 50 | 16 | 47 | 13 | 47.5 | 13.5 | 52.5 | 18.5 | 44.5 | 10.5 |
| 32 | 54 | 16 | 58 | 20 | 55 | 17 | 55 | 17.5 | 60.5 | 22.5 | 52.5 | 14.5 |
| 40 | 78 | 38 | 82 | 42 | 79 | 39 | 79.5 | 39.5 | 84.5 | 44.5 | 76.5 | 36.5 |
| 50 | 81 | 43 | 85 | 47 | 82 | 44 | 82.5 | 44.5 | 87.5 | 49.5 | 79.5 | 41.5 |
| 63 | 84.5 | 40.5 | 88.5 | 44.5 | 85.5 | 41.5 | 86 | 42 | 91 | 47 | 83 | 39 |

Note）Adjust the auto switch after confirming the operating conditions in the actual setting．
Auto Switch Mounting Height

|  | D－A9■V | $\begin{aligned} & \text { D-M9 } \square V \\ & \text { D-M9 } \square \mathbf{W V} \\ & \text { D-M9 } \square \text { AV } \end{aligned}$ | $\begin{aligned} & \text { D-A7■ } \\ & \text { D-A80 } \end{aligned}$ | $\begin{aligned} & \text { D-A7■H } \\ & \text { D-A80H } \\ & \text { D-F7口 } \\ & \text { D-J79 } \\ & \text { D-F7■W } \\ & \text { D-J79W } \\ & \text { D-F7BA } \\ & \text { D-F79F } \\ & \text { D-F7NT } \end{aligned}$ | $\begin{aligned} & \text { D-A73C } \\ & \text { D-A80C } \end{aligned}$ | $\begin{aligned} & \text { D-F7■V } \\ & \text { D-F7 } \square W V \\ & \text { D-F7BAV } \end{aligned}$ | D－J79C | D－A79W |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $(\mathrm{mm})$ | U | U | U | U | U | U | U | U |
| 12 | 20.5 | 20.5 | 19.5 | 20.5 | 26.5 | 23 | 26 | 22 |
| 20 | 25.5 | 25.5 | 24.5 | 25.5 | 31.5 | 28 | 31 | 27 |
| 32 | 27 | 29 | 31.5 | 32.5 | 38.5 | 35 | 38 | 34 |
| 40 | 30.5 | 32.5 | 35 | 36 | 42 | 38.5 | 41.5 | 37.5 |
| 50 | 36.5 | 38.5 | 41 | 42 | 48 | 44.5 | 47.5 | 43.5 |
| 63 | 40 | 42 | 47.5 | 48.5 | 54.5 | 51 | 54 | 50 |

＊Auto switch mounting brackets BQ2－012 are not used for sizes over ø32 of D－A9 $\square \mathrm{V} / \mathrm{M} 9 \square \mathrm{~V} / \mathrm{M} 9 \square \mathrm{WV} / \mathrm{M} 9 \square \mathrm{AVL}$ types．In that case，the above values indicate the operating range when mounted with the current auto switch installation groove．

## Minimum Auto Switch Mounting Stroke


Note）The dimensions stated in（）shows the minimum stroke for the auto switch mounting when the auto switch does not project from the end surface of the cylinder body and hinder the lead wire bending space．（Refer to the figure below．） Order auto switches and auto switch mounting brackets separately．


Operating Range

| Auto switch model | Bore size（mm） |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | 12 | 20 | 32 | 40 | 50 | 63 |
| D－A9 $\square$（V） | 7 | 9 | 9.5 | 9.5 | 9.5 | 11.5 |
| $\begin{aligned} & \text { D-M9 } \square(V) \\ & \text { D-M9 } \square(V) \\ & \text { D-M9 } \square \mathbf{A}(V) \end{aligned}$ | 2.5 | 4 | 6 | 6 | 6 | 6.5 |
| $\begin{aligned} & \text { D-A7 } \square(\mathrm{H})(\mathrm{C}) \\ & \text { D-A80 } \square(\mathrm{H})(\mathrm{C}) \end{aligned}$ | 9.5 | 12 | 12 | 11 | 10 | 12 |
| D－A79W | 11.5 | 13 | 13 | 14 | 14 | 16 |
| $\begin{aligned} & \text { D-F7口(V) } \\ & \text { D-J79(C) } \\ & \text { D-F7■W(V) } \\ & \text { D-F7BA(V) } \\ & \text { D-F7NT } \\ & \text { D-F79F } \end{aligned}$ | 4 | 5.5 | 6 | 6 | 6 | 6.5 |

＊Since the operating range is provided as a guideline including hysteresis，it cannot be guaranteed（assuming approximately $\pm 30 \%$ dispersion）．It may vary substantially depending on an ambient environment．

## CE1 Series

## Auto Switch Mounting Bracket: Part No.



Note 1) When a compact auto switch is mounted on the three sides ( A $B$ and $C$ above) other than the port side of CE1ロ32 to 50, the auto switch mounting brackets above are required. Order them separately from cylinders.
(It is the same as when mounting compact cylinders with an auto switch mounting rail, but not with CE1 $\square 63$ to 100 compact auto switch installation groove.
Example order:
CE1B32-100-M9BW ...... 1 unit BQ-2 ...... 2 pcs. BQ2-012 ...... 2 pcs.
Note 2) Auto switch mounting brackets and auto switches are shipped ogether with cylinders.
Note 3) D-A9■ and D-A9■V auto switches cannot be used with the produc with a bore size of $\varnothing 12$ (CE1口12).

| Auto switch model | Bore size (mm) |  |  |
| :---: | :---: | :---: | :---: |
| Auto swith model | $\varnothing 12$ to ø20 | $\varnothing 32$ | $\varnothing 40$ to ø63 |
| D-A7 $\square /$ A80 |  |  |  |
| D-A73C/A80C |  |  |  |
| D-A7 $\square$ H/A80H |  |  |  |
| D-A79W |  |  |  |
| D-F7 $\square / \mathrm{J} 79$ |  |  |  |
| D-F7 $\square$ V | BQ-1 |  | BQ-2 |
| D-J79C |  |  |  |
| D-F7 $\square$ W/J79W |  |  |  |
| D-F7 $\square$ WV |  |  |  |
| D-F7BA/F7BAV |  |  |  |
| D-F79F/F7NT |  |  |  |

Mounting screw set made of stainless steel]
The following set of mounting screws made of stainless steel (including nuts) is available. Use it in accordance with the operating environment. (Please order $B Q-2$ separately, since the auto switch spacer (for BQ-2) is not included.)

BBA2: For D-A7/A8/F7/J7 types
D-F7BA/F7BAV auto switches are set on the cylinder with the stainless steel screws above when shipped.
When an auto switch is shipped independently, BBA2 is attached.
Note 5) Refer to page 1051 for the details of BBA2.
Note 6) When mounting D-M9■A(V) on a port other than the ports for ø32, ø40 and $\varnothing 50$, order auto switch mounting brackets BQ2-012S, BQ-2 and stainless steel screw set BBA2 separately.

Auto Switch Mounting Bracket Weight

| Auto switch mounting <br> bracket part no. | Applicable bore size | Weight (g) |
| :--- | :---: | :---: |
| BQ-1 | $\varnothing 12$ to $\varnothing 20$ | 1.5 |
| BQ-2 | $\varnothing 32$ to $\varnothing 63$ | 1.5 |
| BQ2-012 | $\varnothing 12$ to $\varnothing 63$ | 5 |

## Other Applicable Auto Switches

| Auto switch type | Model | Electrical entry (Fetching direction) | Features |
| :---: | :---: | :---: | :---: |
| Reed | D-A73 | Grommet (Perpendicular) | - |
|  | D-A80 |  | Without indicator light |
|  | D-A73H, A76H | Grommet (In-line) | - |
|  | D-A80H |  | Without indicator light |
| Solid state | D-F7NV, F7PV, F7BV | Grommet (Perpendicular) | - |
|  | D-F7NWV, F7BWV |  | Diagnostic indication (2-color indicator) |
|  | D-F7BAVL |  | Water resistant (2-color indicator) |
|  | D-F79, F7P, J79 | Grommet (In-line) | - |
|  | D-F79W, F7PW, J79W |  | Diagnostic indication (2-color indicator) |
|  | D-F7BA |  | Water resistant (2-color indicator) |
|  | D-F7NT |  | With timer |

Auto switch mounting brackets and auto switches are shipped together with cylinders.

* For solid state auto switches, auto switches with a pre-wired connector are also available. Refer to pages 1014 and 1015 for details.
* Normally closed ( $\mathrm{NC}=\mathrm{b}$ contact), solid state auto switch (D-F9G/F9H type) are also available. For details, refer to page 959.


## CEU Series

Counter/Extension Cable

Note) CE-compliant: When connecting to a stroke reading cylinder (CE1), a high precision stroke reading cylinder (CEP1) and a stroke reading cylinder with brake (CE2). (CEU5ロロ-D type) Refer to the operation manual for details.

Multi-counter
How to Order


| NiI | RS- -32 C |
| :---: | :---: |
| B | $\mathrm{RS}-32 \mathrm{C}+\mathrm{BCD}$ |

## Connection Method



BCD output (Refer to page 676.) function is available only for CEU5 $\square \mathrm{B}-\square$.
(1) BCD output connector: D-Sub half pitch connector

D x 10M-36S (Made by HIROSE ELECTRIC CO., LTD.)
(2) Applicable connectors: D x 30AM-36P (Plug: Made by HIROSE ELECTRIC CO., LTD.) *

D x 30M-36-CV (Cover: Made by HIROSE ELECTRIC CO., LTD.)*
Other interchangeable commercial cables with connectors can be also used.

* Pressure welding tools are required to connect the connector (plug, cover) models listed above and cables (order separately). The following products, including pre-assembled connectors and cables, are also available. Contact the manufacturer (Misumi Corporation) directly.
SHPT-H-A-36-*: Male connector on one end, cable cut off on one end
SHPT-HH-A-36-*: Male connectors on both ends
* 0.2 to 50 (This shows the cable length. Unit: m)


## CEU Series

## Multi-counter/Specifications

| Model | CEU5 | CEU5-D | CEU5P | CEU5P-D | CEU5B | CEU5B-D | CEU5PB | CEU5PB-D |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Type | Multi-counter |  |  |  |  |  |  |  |
| Mounting | Surface mounting (DIN rail or Screw stop) |  |  |  |  |  |  |  |
| Operating system | Adding - subtracting type |  |  |  |  |  |  |  |
| Operation mode | Operating mode, Data setting mode, Function setting mode |  |  |  |  |  |  |  |
| Reset system | External reset terminal |  |  |  |  |  |  |  |
| Display system | LCD (With back light) |  |  |  |  |  |  |  |
| Number of digits | 6 digits |  |  |  |  |  |  |  |
| Memory holding \{Storage medium\} | Setting value (always held), Count value (Hold/Non-hold switching), \{E²ROM (Warning display after writing approx. 800,000 times: E2FUL) $\}$ |  |  |  |  |  |  |  |
| Input signal type | Count input, Control signal input (Reset, Hold, Bank selection) |  |  |  |  |  |  |  |
| Count input | No-voltage pulse input |  |  |  |  |  |  |  |
| Pulse signal system | $90^{\circ}$ phase difference input *1/ UP/DOWN separate input*2 |  |  |  |  |  |  |  |
| Counting speed | 100 kHz *1 |  |  |  |  |  |  |  |
| Control signal input | Voltage input (12 VDC or 24 VDC ) |  |  |  |  |  |  |  |
| Sensor power supply | 10.8 to 13.2 VDC, 60 mA |  |  |  |  |  |  |  |
| Output signal type | Preset output, Cylinder stop output |  |  |  | Preset output, Cylinder stop output, BCD output |  |  |  |
| Preset output configuration | Compare/Hold/One-shot (100 ms fixed pulse) |  |  |  |  |  |  |  |
| Output type | Separate 5 point output/Binary code output |  |  |  |  |  |  |  |
| Output delay time | 5 ms or less (for normal output)/60 ms or less (Binary output) |  |  |  |  |  |  |  |
| Communication system | RS-232C |  |  |  |  |  |  |  |
| Output transistor mode | NPN open collector Max 30 VDC, 50 mA |  | PNP open collector Max 30 VDC, 50 mA |  | NPN open collector Max 30 VDC, 50 mA *3 |  | PNP open collector Max 30 VDC, 50 mA *3 |  |
| Power supply voltage | 90 to 264 VAC | 21.6 to 26.4 VDC | 90 to 264 VAC | 21.6 to 26.4 VDC | 90 to 264 VAC | 21.6 to 26.4 VDC | 90 to 264 VAC | 21.6 to 26.4 VDC |
| Power consumption | 20 VA or less | 10 W or less | 20 VA or less | 10 W or less | 20 VA or less | 10 W or less | 20 VA or less | 10 W or less |
| Withstand voltage | Between case and AC line: 1500 VAC for 1 min . <br> Between case and signal ground: 500 VAC for 1 min . |  |  |  |  |  |  |  |
| Insulation resistance | Between case and AC line: $50 \mathrm{M} \Omega$ or more (500 VDC measured via megohmmeter) |  |  |  |  |  |  |  |
| Ambient temperature | 0 to $+50^{\circ} \mathrm{C}$ (No freezing) |  |  |  |  |  |  |  |
| Ambient humidity | 35 to 85\% RH (No condensation) |  |  |  |  |  |  |  |
| Noise resistance | Square wave noise from a noise simulator (pulse duration $1 \mu \mathrm{~s}$ ) between power supply terminals $\pm 2000 \mathrm{~V}, \mathrm{l} / \mathrm{O}$ line $\pm 600 \mathrm{~V}$ |  |  |  |  |  |  |  |
| Shock resistance | Endurance 10 to 55 Hz ; Amplitude $0.75 \mathrm{~mm} ; \mathrm{X}, \mathrm{Y}, \mathrm{Z}$ for 2 hours each |  |  |  |  |  |  |  |
| Impact resistance | Endurance $10 \mathrm{G} ; \mathrm{X}, \mathrm{Y}, \mathrm{Z}$ directions, 3 times each |  |  |  |  |  |  |  |
| Weight | 350 g or less |  |  |  |  |  |  |  |

*1) $90^{\circ}$ phase difference input


$$
\begin{aligned}
& \left.\begin{array}{l}
\text { A: } \\
\text { B: } \\
\text { C: } \\
\text { D }:
\end{array}\right\} 2.5 \mu \mathrm{sec} \text { or more required } \\
& t: 10 \mu \mathrm{sec} \text { or more required } \\
& \text { Counting speed } f=\frac{1}{\mathrm{t}}=\frac{1}{10 \times 10^{-6}}=100000 \mathrm{~Hz} \\
&
\end{aligned} \begin{aligned}
& \cong 100 \mathrm{kHz}
\end{aligned}
$$

* 2) UP/DOWN input

Input wave form conditions: At a maximum of 100 kHz the UP/DOWN wave form should be as shown below.


* 3) 15 mA when BCD is output (Refer to page 676.)

Multi-counter/Dimensions


## Wiring with External Equipment

<Wiring with multi-counter CEU5>

1. Wiring of power source for driving counter For power source for driving counter, use the one with 90 to 264 VAC, $50 / 60 \mathrm{~Hz}$ or 21.6 to 26.4 VDC, 0.4 A or more.
2. Wiring for control signal input
(Selection among Reset, Hold, Bank (Refer to page 676.)) Make each control signal to be the transistor which can run more than 15 mA or the contact output. Input time for reset signal should be more than 10 ms . Bank (Refer to page 676.) selection and hold will function only when the input signal is applied.
COM is common to each signal input. Applicable to NPN and PNP input. Use 24 VDC or 12 VDC for the power source of COM. Connect DCwhen PNP is applied, and DC+ when NPN is applied.

## 3. Output circuit

There are two outputs, the NPN open collector and the PNP open collector.
The maximum rating is $30 \mathrm{VDC}, 50 \mathrm{~mA}$. Operating the controller by exceeding this voltage and amperage could damage the electric circuit.
Therefore, the equipment to be connected must be below this rating.



## Extension Cable

## How to Order



## CEU Series

Operating Condition of each Output Mode
One-shot Output
Without allowable values

| When the counter value passes the preset value, output is |
| :--- |
| turned ON for 100 ms . |


| When the counter value passes the sum of the preset |
| :--- |
| value + the allowed value, output is turned ON for 100 ms . |

When moving in (+) direction OUT Counting direction

## Hold Output

| Without allowable values | With allowable values |
| :--- | :--- |
| When the counter value passes the preset value, output is <br> turned ON and that state is maintained. <br> Output is cancelled when the power is turned off, the reset <br> signal is input or when the setting value is changed. | When the counter value passes the sum of the preset <br> value + the allowed value, output is turned ON. <br> Output is cancelled when the power is turned off, the reset <br> signal is input or when the setting value is changed. |
| When moving in (+) direction OUT |  |

Compare Output


## CEU Series

CEU5 Operation


## Display detail



## Key and Functions

| Key |  |
| :--- | :--- |
| MODE | Changes the mode. In any given condition, it shifts to the next mode. <br> Does not write data. |
| SEL. | Shifts the cursor to the next item. Does not write data. |
| SET | Writes displayed data into the memory when setting. |
| RIGHT | Shifts the cursor to the right when setting numerical values. |
| LEFT | Shifts the cursor to the left when setting numerical values. |
| UP | Changes the contents of a setting. Increases the value when setting numerical values. |
| DOWN | Changes the contents of a setting. Decreases the value when setting numerical values. |

[^3]Mode cycle using mode key


## Basic Operation

| $\bullet$ SET key | : In any of the conditions (1) through (5), this writes the display <br> data into the memory and shifts to (1). |
| :--- | :--- |
| $\bullet$ SEL. key | : Shifts to the next item, but does not write data. |
| $\bullet$ MODE key | In any given condition, this shifts to the next mode, but does <br> not write data. |
| - Direction keys $:$ LEFT/RIGHT keys shift the digits, and UP/DOWN keys |  |
| increase or decrease numerical values. |  |

Binary output display
Displays only when matched with preset

2. Setting of preset mode


## CEU Series

## CEU5 Operation

## 3. Explanation of settings in the function mode

If the UP/DOWN keys are pressed when an item name is flashing, it shifts to another setting item. When the SEL. key is pressed, the cursor shifts and it is possible to change the content of the setting for the item which is being displayed.




- The output system setting mode is selected by pressing the SEL. key while OUTPUT is flashing.
- The input type setting mode is selected by pressing the SEL. key while INPUT is flashing.

- Select phase difference input with the UP/DOWN keys. ( $\pm 2$ PHASE) or separate input ( $\pm$ UP/DOWN) with the UP/ DOWN keys.
- If the polarity changes, the count direction reverses.

- Store the setting with the SET key.
- The SEL. key only shifts the cursor without storing the setting.

- The count value backup setting mode is selected by pressing the SEL. key while BACKUP is flashing.
- Select ON or OFF with the UP/DOWN keys.
- Store the setting with the SET key.
- The SEL. key only shifts the cursor without storing the setting.

- The RS-232C (Refer to page 676.) communication speed setting mode is selected by pressing the SEL. key while RS-232 is flashing.
- Select the communication speed from 1200, 2400, 4800, 9600 or 19200 with the UP/DOWN keys.
- Store the setting with the SET key.
- The SEL. key only shifts the cursor without storing the setting.

- The unit number registration mode is selected by pressing the SEL. key while UNIT is flashing.
- Set numerical values with the direction keys.
- Settings can be made from 00 to 99.
- Store the setting with the SET key.

- Select ON or OFF with the UP/DOWN key,
- Store the setting with the SET key.

Note) When the digital filter setting (ON/OFF) is changed, an error count will occur. Reset the count value.

## CEU Series

## Glossary (Functions of CEU5)

## BCD Output

This is a system which expresses one digit of a decimal number with a 4 digit binary number.
The count value is expressed by the ON/OFF state of each BCD output terminal. In the case of 6 digits, 24 terminals are required.

The relation between decimal numbers and BCD codes is shown in the table below.

| Decimal no. | 0 | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 |
| :--- | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| BCD | 0000 | 0001 | 0010 | 0011 | 0100 | 0101 | 0110 | 0111 | 1000 | 1001 |

Ex.) 1294.53 is expressed as follows.
000100101001010001010011

## RS-232C

This is the interface standard for the serial transmission method, which is standard equipment on a personal computer.

## Prescale Function

This function allows free setting of how many millimeters will indicate one pulse.

## Binary Output

31 point preset output is possible without bank switching, by means of binary system output from a 5 point output terminal. Cylinder stop output is used as the readout release signal.


The coincident preset number is expressed as a 5 digit binary number.

## Bank Function

5 points of preset output are possible simultaneously, however, a maximum of 20 types of work discrimination, etc. can be performed by using the 5 points of preset values as one of a maximum of four quadrats, and switching its use during operation.


For example, when bank 2 is selected, presets 6 through 10 are valid and when the count value coincides with the setting value of 6 through 10, the respective output terminals 1 through 5 are turned ON.

## Bank Switching Correspondence

| Bank no. | BANK2 | BANK1 |
| :---: | :---: | :---: |
| 1 | OFF | OFF |
| 2 | OFF | ON |
| 3 | ON | OFF |
| 4 | ON | ON |

## Display Offset Function

Normally the count value returns to " 0 " after resetting, but with this function, the initial value can be set to any desired value.

## Hold Function

When "hold" is input, the counter holds the current count value in memory. Next, when the count value is read into a PLC which uses serial or BCD output, etc., the count value that was held can be read in, even if there is a time lag.

## Setting the Tolerances of Preset Values

The tolerance can be set as $+\bigcirc \mathrm{mm}$ and $-\boldsymbol{\Delta} \mathrm{mm}$. Additionally, the setting of $+\bigcirc \mathrm{mm}$ and $+\Delta \mathrm{mm}$, or $-\bigcirc \mathrm{mm}$ and $-\Delta \mathrm{mm}$ is also possible. (However, $\bigcirc>\Delta$ and $\mathbf{\Delta}>$ should be satisfied.)

By including preset tolerance setting, superior performance is exhibited in parts inspections, etc. In a workpiece to be measured, there are tolerances which assure a good product. For example, in the case of $10_{-0.02}^{+0.05}$, the CEU5 allows these tolerances to be input as they stand. If the workpiece is within tolerances the OK signal is sent.
<Simple input as per drawing dimensions> Tolerances can be set with the preset value.

OK/NG signal is output by the counter Labor savings can be realized in parts inspections.


## Count Value Protection

In the past, the count value returned to " 0 " when the power supply was cut off, but this function holds the previous value even after a power failure. This function can be switched between active and inactive settings.

## Cylinder Stop Output

When workpiece discrimination is performed using a preset counter, it has been common to estimate the amount of time from the cylinder's start of operation until it touches the workpiece and stops, using a timer to read the output after a fixed amount of time. Since cylinder stop output is now output when there is no cylinder movement for a fixed amount of time, timing of preset output and external output, etc. is simplified.


[^0]:    * Strokes other than standard strokes are available upon request for special. Consult with SMC separately.
    Especially, be careful of an eccentric load applied to the rod when the stroke is over 100 mm with a bore size of 12 mm .

[^1]:    * For rod end nut accessory bracket, refer to page 658. * Dimensions for auto switch model D-F79W.

[^2]:    * Dimensions for auto switch model D-F79W.

[^3]:    In the explanations of the operating method, references to "Direction keys" indicate the 4 keys RIGHT, LEFT, UP and DOWN.

