



# KR 6 R500 Z200



## **Technical data**

Maximum reach	500 mm
Maximum payload	6 kg
Pose repeatability (ISO 9283)	± 0.02 mm
Number of axes	4
Mounting position	Floor
Footprint	262 mm x 190 mm
Weight	approx. 20 kg

# Axis data

Motion range	
Motion range, axis 1	±132 °
Motion range, axis 2	±145 °
Motion range, axis 3	-200 mm / 0 mm
Motion range, axis 4	±355 °
Speed with rated payload	
Axis velocity, axis 1	420 °/s
Axis velocity, axis 2	720 °/s
Axis velocity, axis 3	1.1 m/s
Axis velocity, axis 4	2000 °/s

# **Operating conditions**

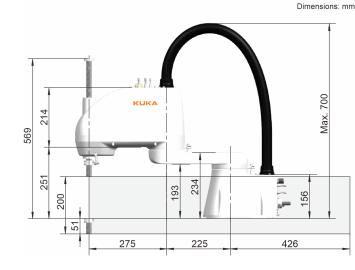
Ambient temperature during operation 5 °C to 40 °C (278 K to 313 K)

#### **Protection rating**

# Controller

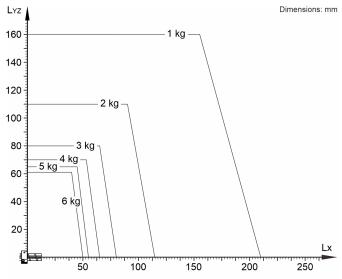
# Teach pendant

Teach pendant	KUKA smartPAD-2
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# Payload diagram

Workspace graphic



The KR 6 R500 Z200 is designed for a rated payload of 3 kg in order to optimize the dynamic performance of the robot. With reduced load center distances, higher loads up to the maximum payload may be used. The specific load case must be verified using KUKA.Load. For further consultation, please contact KUKA Support.

### Cycle time

166 cycl	es per minute (25 mm	/ 305 mm / 25 mm, 1 kg)
R 25 mm		R 25 mm
4	305 mm	→

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