# **Oriental motor**



RoHS RoHS-Compliant

**Standard AC Motors** 

# World K Series

**Induction Motors Reversible Motors Electromagnetic Brake Motors Torque Motors** 



VORLD K SERIES



The World K Series The Standard AC Motors
Offering the Greatest Utility
for around the World

The World K Series is a global name of our standard

AC motors that is usable around the world. Its lineup has

been extended with the addition of models conforming to

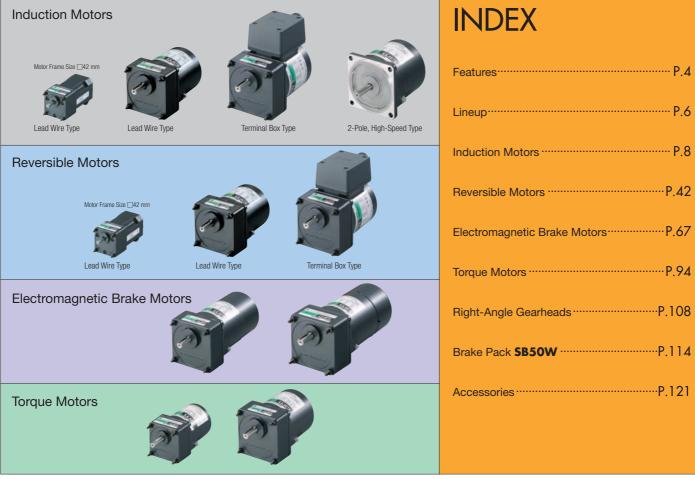
the RoHS Directive.

Offering high reliability and wide range of variations,

the World K Series supports effective equipment design.

# VVORLD K SERIES





# Features of the World K Series

If you're looking for reliable motors that can be used in various locations around the world, Oriental Motor has the answer with the **World K Series**.

These high-performance models are compatible with major international safety standards and voltage standards of each country and region, and also come in a range of configurations, gearhead types and accessories.

# Safety Standards for Safe, Reliable Operation

All **World K Series** models have a built-in overheat protection device and conform to major international safety standards.

■ Applicable Standards
UL/CSA Standards
CE Marking (Low Voltage Directive)



Models certified under CCC (China Compulsory Certification system) are also available. For details, please contact your nearest Oriental Motor sales

- Motor Overheat Protection Device
- ◆ Thermal Protector:
   A built-in feature of all motors with a frame size of 

  70 mm or more.
- Impedance Protection: Implemented in all motors with a frame size of □60 mm or less\*.
- \* Torque motors with a frame size of ☐60 mm are also equipped with a built-in thermal protector.

# Worldwide Voltage Compatibility

Usable with the power supply voltages in major countries.

The **World K Series** supports the power supply voltages used in major countries. Motors meeting the local voltage standard are readily available in major countries in Asia, North America and Europe.



**RoHS-Compliant** 

The **World K Series** conforms to the RoHS Directive that prohibits the use of six chemical substances including lead and cadmium.

#### RoHS (Restriction of Hazardous Substances) Directive:

Directive on restriction of the use of certain hazardous substances in electrical and electronic equipment (2002/95/EC).

The RoHS Directive prohibits the use of six chemical substances in electrical and electronic products sold in the EU member states. The six controlled substances are: lead, hexavalent chromium, cadmium, mercury and two specific brominated flame-retardants (PBB and PBDE).

# Wide Variations

# Select from a total of 4 models encompassing 336 types.

Oriental Motor has expanded its lineup with the addition of  $\square$ 42 mm motors, 2-pole, high-speed type induction motors and torque motors. You can choose the ideal motor from a total of 336 types according to your specific needs for motor type, voltage specification, output and application requirements.

#### ■ World K Series Output Table

Mod	Frame Size	□42 mm	□60 mm	□70 mm	□80 mm	□90 mm
	Lead Wire Type	1 W 3 W	6 W	15 W	25 W	40 W 60 W 90 W
Induction Motors	Terminal Box Type	_	6 W	_	25 W	40 W 60 W 90 W
	2-Pole, High- Speed Type	_	_	_	40 W 60 W	60 W 90 W 150 W
Reversible Motors	Lead Wire Type	1 W	6 W	15 W	25 W	40 W 60 W 90 W
Reversibl	Terminal Box Type	-	6 W	_	25 W	40 W 60 W 90 W
	Electromagnetic Brake Motors		6 W	15 W	25 W	40 W 60 W 90 W
Tor	que Motors	_	3 W	6 W	10 W	20 W

# Gearhead

# "Long life, parallel shaft gearhead" as well as various gearheads can be available.

#### Gearheads

We have dedicated gearheads offering wide gear ratios, as well as right-angle gearheads that minimize the installation space for your equipment.



Parallel Shaft Gearhead RoHS



Right-Angle Gearhead Hollow Shaft Type (RoHS)



Right-Angle Gearhead Solid Shaft Type (RoHS)

■ Parallel Shaft Gearhead with a Rated Life of 10000 hours

Adopting innovative technologies and structure, the new "long life, parallel shaft gearhead" achieves a rated life of 10000 hours, which is twice as long as the life of our conventional gearhead. The reliable gearhead reduces maintenance problem. Gearhead noise has also been reduced.

■ Motor's Bearing also Lasts 2 Times Longer
A motor's life is determined by its bearing. We
adopted high-performance bearing grease to
lubricate this important component. As a result, the
bearings of World K Series motors last twice as
long as our conventional bearings.

# Brake Pack/ Accessories

We offer a standard-compliant brake pack, as well as a range of accessories.

■ Standard-Compliant Brake Pack **SB50W**(RoHS)



An ideal brake pack for the World K Series, the SB50W provides useful functions such as instantaneous stop, forward/reverse operation, electromagnetic brake control and thermal protector.

#### Accessories

A range of accessories is available to facilitate motor installation in your equipment. Choose one according to the motor type you've selected.





# ■ Lineup of the World K Series



**Reversible Motors** 

Most suitable for applications where instantaneous reversal of direction is frequently required.



Lead Wire Type



Terminal Box Type

Electromagnetic Brake Motors Optimal for applications in which loads must be held.

Motors come with a power off activated type electromagnetic brake.





**Torque Motors** 

Suitable for winding and other operations involving tension control, as well as for applications requiring brake.





	Frame Size/Output Power	□42 mm	□60 mm	□70 mm	□80 mm		□90 mm		Page
Voltage/Type		1 W • 3 W	6 W	15 W	25 W	40 W	60 W	90 W	
Single-Phase 100 VAC*	Lead Wire Type	•	•	•	•	•	•	•	
Single-Phase 100 VAC	Terminal Box Type		•		•	•	•	•	
Single-Phase 110/115 VAC	Lead Wire Type	•	•	•	•	•	•	•	
Single-Phase 110/115 VAC	Terminal Box Type		•		•	•	•	•	
Single-Phase 200 VAC*	Lead Wire Type	•	•	•	•	•	•	•	8
Siligie-Pilase 200 VAC	Terminal Box Type		•		•	•	•	•	
Cingle Phase 220/220 VAC	Lead Wire Type		•	•	•	•	•	•	
Single-Phase 220/230 VAC	Terminal Box Type		•		•	•	•	•	
Thurs Dhass 000/000/000 VAC	Lead Wire Type		•		•	•	•	•	
Three-Phase 200/220/230 VAC	Terminal Box Type		•		•	•	•	•	
Three-Phase 400 VAC	Terminal Box Type				•	•	•	•	
ole, High-Speed Type									
	Frame Size/Output Power			□80	) mm		□90 mm		Pag
Voltage/Type				40 W	60 W	60 W	90 W	150 W	
Single-Phase 100 VAC*	Lead Wire Type			•	•	•	•	•	
Single-Phase 110/115 VAC	Lead Wire Type			•	•	•	•	•	
Single-Phase 200 VAC*	Lead Wire Type			•	•	•	•	•	37
Single-Phase 220/230 VAC	Lead Wire Type			•	•	•	•	•	
Three Phase 200/200/200 VAC	Lead Wire Type					•	•	•	
Three-Phase 200/220/230 VAC	Terminal Box Type							•	

Reversible Motors									
	Frame Size/Output Power	□42 mm	□60 mm	□70 mm	□80 mm		□90 mm		Page
Voltage/Type		1 W	6 W	15 W	25 W	40 W	60 W	90 W	
Single-Phase 100 VAC*	Lead Wire Type	•	•	•	•	•	•	•	
Single-rhase 100 VAC	Terminal Box Type		•		•	•	•	•	
0'I- Pl 440/445 VAO	Lead Wire Type	•	•	•	•	•	•	•	42
Single-Phase 110/115 VAC	Terminal Box Type		•		•	•	•	•	
Cinala Phasa 200 VAC*	Lead Wire Type	•	•	•	•	•	•	•	,,,
Single-Phase 200 VAC*	Terminal Box Type		•		•	•	•	•	
0'I Ph 000/000 VA0	Lead Wire Type		•	•	•	•	•	•	
Single-Phase 220/230 VAC	Terminal Box Type		•		•	•	•	•	

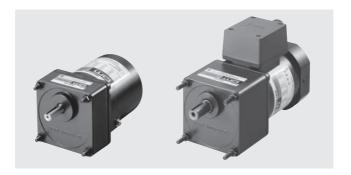
Electromagnetic Brake Motors							
Frame Size/Output Power	□60 mm	□70 mm	□80 mm		□90 mm		Page
Voltage	6 W	15 W	25 W	40 W	60 W	90 W	
Single-Phase 100 VAC*	•	•	•	•	•	•	
Single-Phase 110/115 VAC	•	•	•	•	•	•	67
Single-Phase 200 VAC*	•	•	•	•	•	•	07
Single-Phase 220/230 VAC	•	•	•	•	•	•	
Three-Phase 200/220/230 VAC	•		•	•	•	•	

Torque Motors							
	Frame Size/Output Power	□60 mm	□70 mm	□80 mm	□90 mm		Page
Voltage		3 W	6 W	10 W	20 W		
Single-Phase 100 VAC*		•	•	•	•		
Single-Phase 110/115 VAC		•	•	•	•		94
Single-Phase 200 VAC*		•	•	•	•		
Single-Phase 220/230 VAC		•	•	•	•		

# RoHS RoHS-Compliant

# **Induction Motors**





#### Features

#### Optimal for Uni-Directional Continuous Operation

Induction motors are optimal for uni-directional continuous operation such as a conveyor system.

## ■Safety Standards and CE Marking

Standards	Certification Body	Standards File No.	CE Marking
UL 1004 UL 2111	- UL	E64199 (1 W~6 W Type)	
CSA C22.2 No.100 CSA C22.2 No.77	OL.	E64197 (15 W~150 W Type)	
EN 60950-1 EN 60034-1 EN 60034-5 IEC 60664-1		Conform to EN/IEC Standards	Low Voltage Directives
GB 12350	CQC	2005010401150786 (Single-Phase 1 W, 3 W Type) 2003010401091525 (Single-Phase 6 W Type) 2003010401091527 (Three-Phase 6 W Type) 2003010401091522 (Single-Phase 15 W~90 W Type) 2003010401091520 (Three-Phase 25 W~90 W Type) 2005010401150785 (2-Pole, High-Speed Type, Single-Phase 40 W~150 W Type) 2005010401150788 (2-Pole, High-Speed Type, Three-Phase 60 W~150 W Type)	

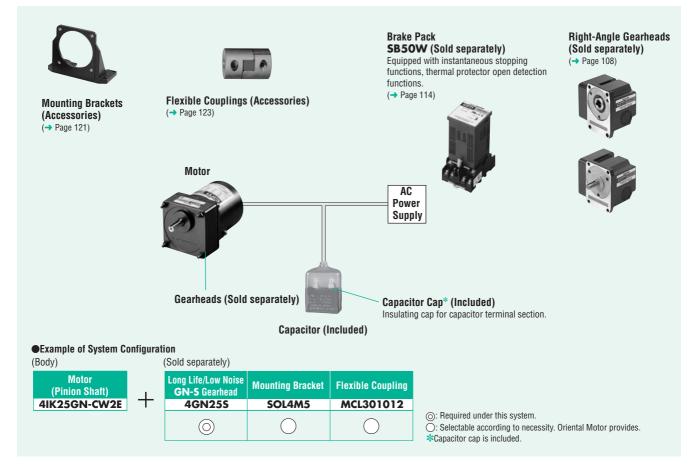
<sup>•</sup> When the motor is approved under various safety standards, the model name on the nameplate is the approved model name.

# 4IK25GN-UT4, 4IK25A-UT4, 5IK40GN-UT4, 5IK40A-UT4, 5IK60GE-UT4F, 5IK60A-UT4F, 5IK90GE-UT4F, 5IK90A-UT4F

Standards	Certification Body	Standards File No.	CE Marking
EN 60950-1 EN 60034-1 EN 60034-5	TÜV Rheinland	R50079501 J50083301	Low Voltage Directives

The following products are not applicable to the table above.

#### System Configuration



• The system configuration shown above is an example. Other configurations are available.

#### Product Number Code

Motor

# 5 I K 40 GN - CW 2 T E

1	Motor Frame Size	0: 42 mm <b>2</b> : 60 mm <b>3</b> : 70 mm <b>4</b> : 80 mm <b>5</b> : 90 mm
2	Motor Type	I: Induction Motor
3	Series	K: K Series
4	Output Power (W)	(Example) <b>40</b> : 40 W
(5)	Motor Shaft Type	GN: GN Type Pinion Shaft GE: GE Type Pinion Shaft A: Round Shaft
6	Power Supply Voltage/ Number of Poles	AW: Single-Phase 100 VAC, 110/115 VAC 4-Pole       BW: Single-Phase 100 VAC, 110/115 VAC 2-Pole       CW: Single-Phase 200 VAC, 220/230 VAC 2-Pole         DW: Single-Phase 200 VAC, 220/230 VAC 2-Pole       SW: Three-Phase 200/220/230 VAC 4-Pole       TW: Three-Phase 200/220/230 VAC 2-Pole         U: Three-Phase 400 VAC 4-Pole       TW: Three-Phase 200/220/230 VAC 2-Pole
7	2, 3: RoHS-Compliant	
8	T, T4, T4F, B: Terminal	Box Type
9	Included Capacitor	J: For Single-Phase 100 VAC, 200 VAC U: For Single-Phase 110/115 VAC E: For Single-Phase 220/230 VAC Blank: Three-Phase Type

<sup>•</sup> The J, U and E at the end of the model name indicate that the unit includes a capacitor. These letters are not listed on the motor nameplate. When the motor is approved under various safety standards, the model name on the nameplate is the approved model name.

(Example) Model: 5IK40GN-CW2E → Motor nameplate and product approved under various safety standards: 5IK40GN-CW2

Gearhead

# 5 GN 50 S

1	2	3	4
<u>(1)</u>	Gearhead I	rame Size	<b>O</b> : 4

1	Gearhead Frame Size	<b>0</b> : 42 mm <b>2</b> : 60 mm <b>3</b> : 70 mm <b>4</b> : 80 mm <b>5</b> : 90 mm
2	Type of Pinion	GN: GN Type Pinion GE: GE Type Pinion
3	Gear Ratio	(Example) <b>50</b> : Gear Ratio of 1:50 <b>10X</b> denotes the decimal gearhead of gear ratio 1:10
	<b>GN</b> Type Pinion	S: Long Life/Low Noise GN-S Gearhead, RoHS-Compliant RH: Right-Angle/Hollow Shaft Gearhead, RoHS-Compliant RA: Right-Angle/Solid Shaft Gearhead, RoHS-Compliant
4	<b>GE</b> Type Pinion	S: Long Life GE-S Gearhead, RoHS-Compliant RH: Right-Angle/Hollow Shaft Gearhead, RoHS-Compliant RA: Right-Angle/Solid Shaft Gearhead, RoHS-Compliant

<sup>\*</sup>GN-K gearhead of frame size 42 mm complies to RoHS directive.

# ■General Specifications of Motors

#### ●1 W, 3 W Type

Item	Specifications
Insulation Resistance	$100~M\Omega$ or more when 500 VDC megger is applied between the windings and the frame after rated motor operation under normal ambient temperature and humidity.
Dielectric Strength	Sufficient to withstand 1.5 kV at 50 Hz or 60 Hz applied between the windings and the frame for 1 minute after rated motor operation under normal ambient temperature and humidity.
Temperature Rise	Temperature rise of windings are 75°C or less measured by the resistance change method after rated motor operation under normal ambient temperature and humidity, with connecting a gearhead or equivalent heat radiation plate*1.
Insulation Class	UL/CSA standards: Class A (105°C), EN standards: Class E (120°C)
Overheat Protection	Impedance protected
Ambient Temperature	-10°C~+40°C (nonfreezing)
Ambient Humidity	85% or less (noncondensing)
Degree of Protection	IP20

#### ●6 W~90 W Type, 2-Pole, High-Speed Type

Item	Specifications
Insulation Resistance	$100 \text{ M}\Omega$ or more when 500 VDC megger is applied between the windings and the frame after rated motor operation under normal ambient temperature and humidity.
Dielectric Strength	Sufficient to withstand 1.5 kV (three-phase 400 VAC: 2 kV) at 50 Hz and 60 Hz applied between the windings and the frame for 1 minute after rated motor operation under normal ambient temperature and humidity.
Temperature Rise	Temperature rise of windings are 80°C or less measured by the resistance change method under normal ambient temperature and humidity, after rated motor operation with connecting a gearhead or equivalent heat radiation plate*i. (Three-phase type: 70°C or less)
Insulation Class*2	Class B (130°C)
Overheat Protection	6 W type has impedance protection.  All others have built-in thermal protector (automatic return type) Operating temperature; open: 130°C±5°C, close: 82°C±15°C
Ambient Temperature	Single-phase 100 VAC, Single-phase 200 VAC, Three-phase 200 VAC: $-10^{\circ}\text{C} \sim +50^{\circ}\text{C}$ (nonfreezing) Other voltage: $-10^{\circ}\text{C} \sim +40^{\circ}\text{C}$ (nonfreezing)
Ambient Humidity	85% or less (noncondensing)
Degree of Protection	Lead wire type: IP20 Terminal box type: Single-phase 100 VAC, 110/115 VAC, 200 VAC, 220/230 VAC, Three-phase 200/220/230 VAC Welling Type: IP65 (Excluding the installation surface of the round shaft type) Single-phase 400 VAC Welling Type: IP54 (Excluding the installation surface of the round shaft type) Three-phase 400 VAC Welling Type: IP60 Welling Type: IP64 Welling Type: IP64 Welling Type: IP64

#### \*1 Heat radiation plate (Material: Aluminum)

The radiation place (material radiation)											
Motor Type	Size (mm)	Thickness (mm)									
1 W, 3 W Type	80×80										
6 W Type	115×115										
15 W Type	125×125	5									
25 W Type (2-Pole, High-Speed <b>4IK40</b> Type, <b>4IK60</b> Type)	135×135	5									
40 W Type (2-Pole, High-Speed <b>5IK60</b> Type)	165×165										
60 W, 90 W, 150 W Type	200×200										

<sup>\*2</sup> The following products are recognized as class E (120°C).

4IK25GN-UT4, 4IK25A-UT4, 5IK40GN-UT4, 5IK40A-UT4, 5IK60GE-UT4F, 5IK60A-UT4F, 5IK90GE-UT4F, 5IK90A-UT4F

RoHS Induction Motors 1 W / 3 W

Frame Size: **□42** mm



(Gearhead sold separately)

## ■Specifications – Continuous Rating (RoHS)



Mode Lead Wire		Output Power	Voltage	Frequency	Current	Starting Torque	Rated Torque	Rated Speed	Capacitor
Pinion Shaft Type	Round Shaft Type	W	VAC	Hz	Α	mN·m	mN·m	r/min	μF
(ZP) OIK1GN-AW2J	OIK1A-AW2J	1	Single-Phase 100	50	0.107	- 8	9.5	1000	1.5
ZP UIKTGIN-AWZJ	UIK I A-AVV 2J	'	Sillyle-Filase 100	60	0.102	0	8	1200	1.5
ZP) OIK1GN-AW3U	OIK1A-AW3U	1	Single-Phase 110	60	0.074	- 8	8	1200	1.0
ZP UIKTGIN-AW30	OIK I A-AVV30	'	Single-Phase 115	00	0.078	0	0	1200	1.0
(ZP) OIK1GN-CW2J	OIK1A-CW2J	0.8	Single-Phase 200	50	0.057	7	8	1000	0.35
ZP OIK I GIN-CW ZJ	OIK I A-CW 23	1	Sillyle-Filase 200	60	0.055	,	0	1200	0.33
(ZP) OIK3GN-BW2J	OIK3A-BW2J	3	Single-Phase 100	50	0.109	6	12	2400	1.8
ZP UIKSGIN-BWZJ	UIK3A-BW2J	3	Siligie-Pliase 100	60	0.123	0	10	3000	1.0
(ZP) OIK3GN-BW3U	OIK3A-BW3U	3	Single-Phase 110	60	0.115	6	10	3000	1.5
ZP UIKSGIN-BWSU	UIK3A-BW3U	3	Single-Phase 115	00	0.118	0	10	3000	1.5
ZP 0IK3GN-DW2J 0IK3	OIKS V DAVOT	2.5	Cingle Phase 200	50	0.057	- 5	9.5	2500	0.45
	0IK3A-DW2J	3	Single-Phase 200	60	0.064	3	9.0	3100	0.45

<sup>•</sup> The J and U at the end of the model name indicate that the unit includes a capacitor. These letters are not listed on the motor nameplate.
When the motor is approved under various safety standards, the model name on the nameplate is the approved model name.

#### Product Line

#### ● Motor (RoHS)

Type	Model										
туре	Pinion Shaft Type	Round Shaft Type									
	0IK1GN-AW2J	0IK1A-AW2J									
	0IK1GN-AW3U	0IK1A-AW3U									
Lead Wire	0IK1GN-CW2J	0IK1A-CW2J									
Leau wire	0IK3GN-BW2J	0IK3A-BW2J									
	0IK3GN-BW3U	0IK3A-BW3U									
	0IK3GN-DW2J	0IK3A-DW2J									

#### ● Gearhead (Sold Separately) (RoHS)

Туре	Gearhead Model	Gear Ratio
Parallel Shaft	0GN□K	3, 3.6, 5, 6, 7.5, 9, 12.5, 15, 18, 25, 30, 36, 50, 60, 75, 90, 100, 120, 150, 180

<sup>■</sup> Enter the gear ratio in the box (□) within the model name.

 $<sup>{\</sup>bf Z\!P}\!\!: {\bf Impedance\ protected}$ 

#### Gearmotor – Torque Table

•Gearheads are sold separately. Decimal gearheads are not available.

■Enter the gear ratio in the box (□) within the model name.

A colored background indicates gear shaft rotation in the same direction as the motor shaft, while the others rotate in the opposite direction.

The speed is calculated by dividing the motor's synchronous speed (4-pole type; 50 Hz: 1500 r/min, 60 Hz: 1800 r/min, 2-pole type; 50 Hz: 3000 r/min, 60 Hz: 3600 r/min) by the gear ratio. The actual speed is 2 - 33% less than the displayed value, depending on the size of

the load.																					
>50 Hz																				Uni	t = N•
Model	Speed r/min	500	416	300	250	200	166	120	100	83	60	50	41	30	25	20	16	15	12.5	10	8.3
Motor/ Gearhead	Gear Ratio	3	3.6	5	6	7.5	9	12.5	15	18	25	30	36	50	60	75	90	100	120	150	180
0IK1GN-AW2J	/ OGN□K	0.023	0.028	0.038	0.046	0.058	0.069	0.087	0.1	0.12	0.16	0.19	0.23	0.31	0.38	0.42	0.5	0.56	0.67	0.84	1
0IK1GN-CW2J	/ OGN□K	0.019	0.023	0.032	0.039	0.049	0.058	0.073	0.088	0.11	0.13	0.16	0.19	0.26	0.32	0.35	0.42	0.47	0.57	0.71	0.8
																				Uni	t = N
Model	Speed r/min	1000	833	600	500	400	333	240	200	166	120	100	83	60	50	40	33	30	25	20	16
Motor/ Gearhead	Gear Ratio	3	3.6	5	6	7.5	9	12.5	15	18	25	30	36	50	60	75	90	100	120	150	18
OIK3GN-BW2J	/ OGN□K	0.029	0.035	0.049	0.058	0.073	0.087	0.11	0.13	0.16	0.2	0.24	0.29	0.4	0.48	0.53	0.64	0.71	0.85	1	1
0IK3GN-DW2J	/ OGN□K	0.023	0.028	0.038	0.046	0.058	0.069	0.087	0.1	0.12	0.16	0.19	0.23	0.31	0.38	0.42	0.5	0.56	0.67	0.84	1
>60 Hz																				Uni	t = N•
Model	Speed r/min	600	500	360	300	240	200	144	120	100	72	60	50	36	30	24	20	18	15	12	10
Motor/ Gearhead	Gear Ratio	3	3.6	5	6	7.5	9	12.5	15	18	25	30	36	50	60	75	90	100	120	150	180
OIK1GN-AW2J OIK1GN-AW3U OIK1GN-CW2J	OGNUK	0.019	0.023	0.032	0.039	0.049	0.058	0.073	0.088	0.11	0.13	0.16	0.19	0.26	0.32	0.35	0.42	0.47	0.57	0.71	0.8
																				Uni	t = N•
Model	Speed r/min	1200	1000	720	600	480	400	288	240	200	144	120	100	72	60	48	40	36	30	24	20
Motor/ Gearhead	Gear Ratio	3	3.6	5	6	7.5	9	12.5	15	18	25	30	36	50	60	75	90	100	120	150	18
OIK3GN-BW2J OIK3GN-BW3U	/ OGN□K	0.024	0.029	0.041	0.049	0.061	0.073	0.091	0.11	0.13	0.17	0.2	0.24	0.33	0.4	0.44	0.53	0.59	0.71	0.89	1
0IK3GN-DW2J	/ OGN□K	0.023	0.028	0.038	0.046	0.058	0.069	0.087	0.1	0.12	0.16	0.19	0.23	0.31	0.38	0.42	0.5	0.56	0.67	0.84	1

# ■Permissible Overhung Load and Permissible Thrust Load

Motor (Round shaft type) → Page 107 Gearhead → Page 107

#### Permissible Load Inertia J for Gearhead

→ Page 107

#### ■ Dimensions (Unit = mm)

Mounting screws are included with gearheads.

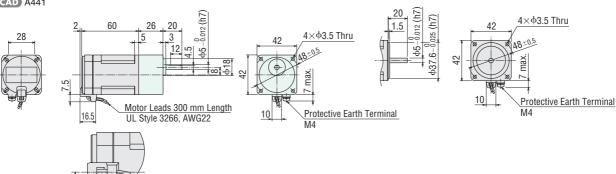
Mass: Motor 0.3 kg

Gearhead 0.2 kg

**CAD** A441

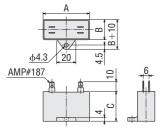
#### ♦ Shaft Section of Round Shaft Type

The mass and motor's dimensions (excluding the shaft section) are the same as those of the pinion shaft type.



Protective Earth Terminal M4

#### 

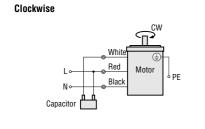


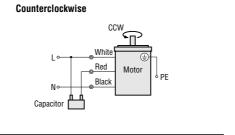
<u> </u>	` '						
Mo	odel	Capacitor	۸	В	С	Mass	Capacitor
Pinion Shaft Type	Round Shaft Type	Model	А	Ь	U	(g)	Cap
0IK1GN-AW2J	0IK1A-AW2J	CH15FAUL	31	14.5	23.5	18	
0IK1GN-AW3U	OIK1A-AW3U	CH10FAUL	31	14.5	23.5	18	
0IK1GN-CW2J	0IK1A-CW2J	CH035BFAUL	31	17	27	24	Included
0IK3GN-BW2J	OIK3A-BW2J	CH18FAUL	31	14.5	23.5	18	Illiciuueu
0IK3GN-BW3U	OIK3A-BW3U	CH15FAUL	31	14.5	23.5	18	
0IK3GN-DW2J	0IK3A-DW2J	CH045BFAUL	31	17	27	24	

## **■**Connection Diagrams

- •The direction of motor rotation is as viewed from the shaft end of the motor. CW represents the clockwise direction, while CCW represents the counterclockwise direction.
- Connection diagrams are also valid for the equivalent round shaft type.

#### OIK1GN-AW2J, OIK1GN-AW3U, OIK1GN-CW2J OIK3GN-BW2J, OIK3GN-BW3U, OIK3GN-DW2J





PE: Protective Earth

#### Note:

Change the direction of single-phase motor rotation only after bringing the motor to a stop.



Frame Size: ☐60 mm





(Gearhead sold separately)

# ■Specifications – Continuous Rating RoHS



	<u> </u>			3 —					07-0	15 🔾
	Model Upper Model Name: I Lower Model Name ( ):	Pinion Shaft Type	Output Power	Voltage	Frequency	Current	Starting Torque	Rated Torque	Rated Speed	Capacitor
	Lead Wire Type Dimension ①	Terminal Box Type Dimension ②	W	VAC	Hz	А	mN∙m	mN·m	r/min	μF
<b>ZP</b>	2IK6GN-AW2J	2IK6GN-AW2BJ	6	Single-Phase 100	50	0.199	45	49	1200	3.5
ZP	(2IK6A-AW2J)	(2IK6A-AW2BJ)	0	Sillyle-Filase 100	60	0.217	40	41	1450	3.3
ZP)	2IK6GN-AW2U	2IK6GN-AW2BU	6	Single-Phase 110	60	0.178	40	41	1450	2.5
ZP	(2IK6A-AW2U)	(2IK6A-AW2BU)	0	Single-Phase 115	00	0.182	40	41	1430	2.5
ZP)	2IK6GN-CW2J	2IK6GN-CW2BJ	6	Single-Phase 200	50	0.100	45	49	1150	0.8
ZP	(2IK6A-CW2J)	(2IK6A-CW2BJ)	0	Sillyle-Filase 200	60	0.103	40	41	1450	0.6
				Single-Phase 220	50	0.103	38	49	1150	
(ZD)	2IK6GN-CW2E	2IK6GN-CW2BE	6	Sillyle-Filase 220	60	0.091	40	41	1450	0.6
<b>ZP</b>	(2IK6A-CW2E)	(2IK6A-CW2BE)	О	Cinala Dhaca 220	50	0.107	45	49	1200	0.6
				Single-Phase 230	60	0.094	40	41	1450	
				Three-Phase 200	50	0.081	49	49	1200	
(ZD)	2IK6GN-SW2	2IK6GN-SW2B		Tillee-Filase 200	60	0.072	41	41	1400	
<b>ZP</b>	(2IK6A-SW2)	(2IK6A-SW2B)	6	6 Three-Phase 220	60	0.076	41	41	1500	_
				Three-Phase 230	60	0.079	41	41	1500	

The **J**, **U** and **E** at the end of the model name indicate that the unit includes a capacitor. These letters are not listed on the motor nameplate. When the motor is approved under various safety standards, the model name on the nameplate is the approved model name.

## Product Line

#### ● Motor (RoHS)

Type	N	lodel
туре	Pinion Shaft Type	Round Shaft Type
	2IK6GN-AW2J	2IK6A-AW2J
	2IK6GN-AW2U	2IK6A-AW2U
Lead Wire	2IK6GN-CW2J	2IK6A-CW2J
	2IK6GN-CW2E	2IK6A-CW2E
	2IK6GN-SW2	2IK6A-SW2
	2IK6GN-AW2BJ	2IK6A-AW2BJ
	2IK6GN-AW2BU	2IK6A-AW2BU
Terminal Box	2IK6GN-CW2BJ	2IK6A-CW2BJ
	2IK6GN-CW2BE	2IK6A-CW2BE
	2IK6GN-SW2B	2IK6A-SW2B

#### Gearhead (Sold Separately) RoHS

Туре	Gearhead Model	Gear Ratio
Long Life/Low Noise/ Parallel Shaft	2GN□5	3, 3.6, 5, 6, 7.5, 9, 12.5, 15, 18, 25, 30, 36, 50, 60, 75, 90, 100, 120, 150, 180
	2GN10XS (Decima	al gearhead)

● Enter the gear ratio in the box (□) within the model name.

**ZP**: Impedance protected

#### ■Gearmotor – Torque Table

- •Gearheads and decimal gearheads are sold separately.
- ●Enter the code that represents the terminal box type "B" in the box (□) within the model name.
- ■Enter the gear ratio in the box (□) within the model name.
- •A colored background indicates gear shaft rotation in the same direction as the motor shaft, while the others rotate in the opposite direction
- The speed is calculated by dividing the motor's synchronous speed (50 Hz: 1500 r/min, 60 Hz: 1800 r/min) by the gear ratio. The actual speed is 2 20% less than the displayed value, depending on the size of the load.
- To reduce the speed beyond the gear ratio in the table, attach a decimal gearhead (gear ratio: 10) between the gearhead and the motor. In that case, the permissible torque is 3 N·m.

<>50 HZ	SO HZ Unit = N°															t = N·m					
Model	Speed r/min	500	416	300	250	200	166	120	100	83	60	50	41	30	25	20	16	15	12.5	10	8.3
Motor/ Gearhead	Gear Ratio	3	3.6	5	6	7.5	9	12.5	15	18	25	30	36	50	60	75	90	100	120	150	180
2IK6GN-AW2  2IK6GN-CW2  2IK6GN-CW2  E  2IK6GN-SW2	<b>2GN</b> □S	0.12	0.14	0.20	0.24	0.30	0.36	0.50	0.60	0.71	0.89	1.1	1.3	1.6	1.9	2.4	2.9	3	3	3	3

<b>♦60 Hz</b>																				Uni	t = N·m
Model	Speed r/min	600	500	360	300	240	200	144	120	100	72	60	50	36	30	24	20	18	15	12	10
Motor/ Gearhead	Gear Ratio	3	3.6	5	6	7.5	9	12.5	15	18	25	30	36	50	60	75	90	100	120	150	180
2IK6GN-AW2 U 2IK6GN-AW2 U 2IK6GN-CW2 J 2IK6GN-CW2 E 2IK6GN-SW2	<b>2GN</b> □S	0.10	0.12	0.17	0.20	0.25	0.30	0.42	0.50	0.60	0.75	0.90	1.1	1.4	1.6	2.0	2.4	2.7	3	3	3

#### Permissible Overhung Load and Permissible Thrust Load

Motor (Round shaft type) → Page 107 Gearhead → Page 107

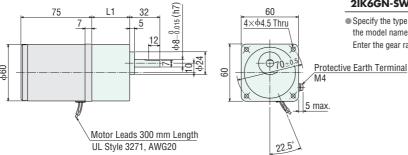
#### Permissible Load Inertia J for Gearhead

→ Page 107

#### **Dimensions** (Unit = mm)

Mounting screws are included with gearheads.

◇Lead Wire Type ①
Mass: Motor 0.7 kg
Gearhead 0.4 kg



Motor Model	Gearhead Model	Gear Ratio	L1	CAD
2IK6GN-AW2□ 2IK6GN-CW2□	2GN⊟S	3~18	30	A443A
2IK6GN-CW2	ZGN_3	<b>25</b> ~180	40	A443B

 $\blacksquare$  Specify the type of the capacitor to be included by entering  ${\bf J},\,{\bf U}$  or  ${\bf E}$  in the box (  $\blacksquare$  ) within the model name.

Enter the gear ratio in the box ( $\square$ ) within the model name.



Detail Drawing of Protective Earth Terminal

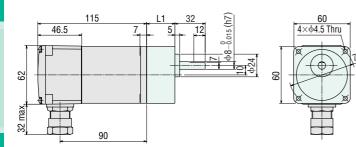
#### 

Mass: Motor 0.9 kg Gearhead 0.4 kg

Motor Model	Gearhead Model	Gear Ratio	L1	CAD
2IK6GN-AW2B	2GN□S	3~18	30	A445A
2IK6GN-SW2B	2GN□5	<b>25~180</b>	40	A445B

ullet Specify the type of the capacitor to be included by entering  ${f J}$ ,  ${f U}$  or  ${f E}$  in the box ( ${lue}$ ) within the model name.

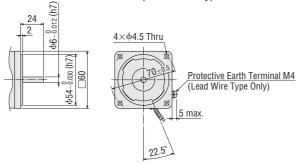
Enter the gear ratio in the box  $(\Box)$  within the model name.



 $\bullet$  Use cable with a diameter of  $\varphi 8 \sim \varphi 12$  mm.

#### ♦ Shaft Section of Round Shaft Type

The mass and motor's dimensions (excluding the shaft section) are the same as those of the pinion shaft type.

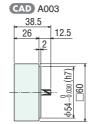


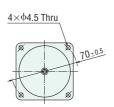
#### ♦ Decimal Gearhead

Can be connected to  $\boldsymbol{GN}$  pinion shaft type.

## 2GN10XS

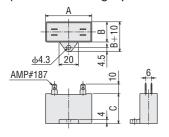
Mass: 0.2 kg





#### 

(Included with single-phase motors)

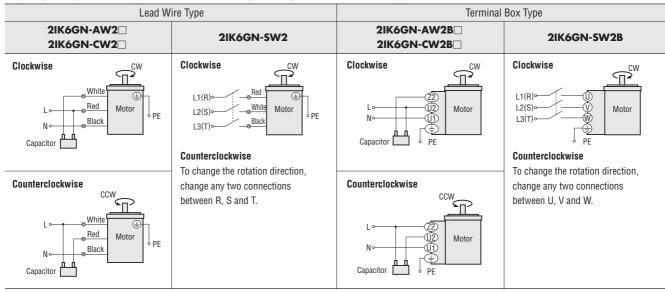


#### 

Upper Model Name	del e: Pinion Shaft Type ( ): Round Shaft Type	Capacitor Model	А	В	С	Mass (g)	Capacitor Cap
Lead Wire Type	Terminal Box Type						
2IK6GN-AW2J (2IK6A-AW2J)	2IK6GN-AW2BJ (2IK6A-AW2BJ)	CH35FAUL2	31	17	27	25	
2IK6GN-AW2U (2IK6A-AW2U)	2IK6GN-AW2BU (2IK6A-AW2BU)	CH25FAUL2	31	17	27	25	Included
2IK6GN-CW2J (2IK6A-CW2J)	2IK6GN-CW2BJ (2IK6A-CW2BJ)	CH08BFAUL	31	17	27	20	iliciuded
2IK6GN-CW2E (2IK6A-CW2E)	2IK6GN-CW2BE (2IK6A-CW2BE)	CH06BFAUL	31	14.5	23.5	15	

#### **■**Connection Diagrams

- •The direction of motor rotation is as viewed from the shaft end of the motor. CW represents the clockwise direction, while CCW represents the counterclockwise direction.
- Connection diagrams are also valid for the equivalent round shaft type.
- Specify the type of the capacitor to be included by entering J, U or E in the box (□) within the model name.



PE: Protective Earth

Note:

Change the direction of single-phase motor rotation only after bringing the motor to a stop.

**Induction Motors** 15 W

Frame Size: **□70** mm



(Gearhead sold separately)

# Specifications - Continuous Rating (RoHS)

c**91**°us **(€**€



Model Lead Wire		Output Power	Voltage	Frequency	Current	Starting Torque	Rated Torque	Rated Speed	Capacitor
Pinion Shaft Type	Round Shaft Type	W	VAC	Hz	Α	mN·m	mN∙m	r/min	μF
TP 3IK15GN-AW2J	3IK15A-AW2J	15	Single-Phase 100	50	0.36	80	125	1200	5.5
JP SIKTSGIV-AW25	JIK I JA-AWZJ	10	Sillyle-Filase 100	60	0.37	65	105	1450	5.5
TP) 3IK15GN-AW2U	3IK15A-AW2U	15	Single-Phase 110	60	0.33	- 65	105	1450	4.5
JP JIKTJGN-AW20	SIK I SA-AW 20	13	Single-Phase 115	00	0.34	0.5	103	1430	4.5
TP 3IK15GN-CW2J	3IK15A-CW2J	15	Single-Phase 200	50	0.18	80	125	1200	1.5
JP SIK150I4-CW25	SIK I SA-CW23	13	Siligie-Filase 200	60	0.19	65	105	1450	1.5
			Single-Phase 220	50	0.19	70	125	1200	
TP 3IK15GN-CW2E	3IK15A-CW2E	15	Sillyle-Filase 220	60	0.16	65	105	1450	1.0
IP SIKISGIN-CWZE	SIK I SA-CWZE	13	Single-Phase 230	50	0.19	75	125	1200	1.0
			Siligio-Filase 230	60	0.16	65	105	1450	

<sup>●</sup> The J, U and E at the end of the model name indicate that the unit includes a capacitor. These letters are not listed on the motor nameplate. When the motor is approved under various safety standards, the model name on the nameplate is the approved model name.

#### Product Line

#### ● Motor (RoHS)

Tuno	Mo	del
Type	Pinion Shaft Type	Round Shaft Type
	3IK15GN-AW2J	3IK15A-AW2J
Lead Wire	3IK15GN-AW2U	3IK15A-AW2U
Leau Wire	3IK15GN-CW2J	3IK15A-CW2J
	3IK15GN-CW2E	3IK15A-CW2E

#### Gearhead (Sold Separately) (RoHS)

Type	Gearhead Model	Gear Ratio
Туро	dournoud model	3331113113
Long Life/Low Noise/ Parallel Shaft	3GN□S	3, 3.6, 5, 6, 7.5, 9, 12.5, 15, 18, 25, 30, 36, 50, 60, 75, 90, 100, 120, 150, 180
	3GN10XS (Decim	al gearhead)

lacksquare Enter the gear ratio in the box ( $\Box$ ) within the model name.

<sup>(</sup>IP): Contains a built-in thermal protector. If a motor overheats for any reason, the thermal protector is opened and the motor stops. When the motor temperature drops, the thermal protector closes and the motor restarts. Be sure to turn the motor off before inspecting.

#### Gearmotor – Torque Table

- Gearheads and decimal gearheads are sold separately.
- ■Enter the gear ratio in the box (□) within the model name.
- A colored background indicates gear shaft rotation in the same direction as the motor shaft, while the others rotate in the opposite direction.
- The speed is calculated by dividing the motor's synchronous speed (50 Hz: 1500 r/min, 60 Hz: 1800 r/min) by the gear ratio. The actual speed is 2 - 20% less than the displayed value, depending on the size of the load.
- To reduce the speed beyond the gear ratio in the table, attach a decimal gearhead (gear ratio: 10) between the gearhead and the motor. In that case, the permissible torque is 5 N·m.

<b>♦50 Hz</b>																				Uni	it = N•m
Model	Speed r/min	500	416	300	250	200	166	120	100	83	60	50	41	30	25	20	16	15	12.5	10	8.3
Motor/ Gearhead	Gear Ratio	3	3.6	5	6	7.5	9	12.5	15	18	25	30	36	50	60	75	90	100	120	150	180
3IK15GN-AW2J 3IK15GN-CW2J 3IK15GN-CW2E	/ 3GN□S	0.30	0.36	0.51	0.61	0.76	0.91	1.3	1.5	1.8	2.3	2.7	3.3	4.1	5	5	5	5	5	5	5

<b>♦60 Hz</b>																				Uni	t = N·m
Model	Speed r/min	600	500	360	300	240	200	144	120	100	72	60	50	36	30	24	20	18	15	12	10
Motor/ Gearhead	Gear Ratio	3	3.6	5	6	7.5	9	12.5	15	18	25	30	36	50	60	75	90	100	120	150	180
3IK15GN-AW2J 3IK15GN-AW2U 3IK15GN-CW2J 3IK15GN-CW2E	<b>3GN</b> □S	0.26	0.31	0.43	0.51	0.64	0.77	1.1	1.3	1.5	1.9	2.3	2.8	3.5	4.2	5	5	5	5	5	5

## Permissible Overhung Load and Permissible Thrust Load

Motor (Round shaft type) → Page 107 Gearhead → Page 107

#### Permissible Load Inertia J for Gearhead

→ Page 107

#### Dimensions (Unit = mm)

Mounting screws are included with gearheads.

#### 

Mass: Motor 1.1 kg Gearhead 0.55 kg

80	L1	32 5 (L) (1) (1) (1) (1) (1) (1)	70 4×Φ5.5 Thru	the model name.	·
	-	25 0		<u>Protective Earth Terminal</u> M4	£
			22.5	<u>max</u> .	Protective M4
	7	7 Motor Leads	80 L1 32 5 7 5 00 25 00	80 L1 32 5 70 4×\(\phi 5.5 \) Thru  80 L1 32 5 70 4×\(\phi 5.5 \) Thru  82 ±0.5 70 4×\(\phi 5.5 \) Thru  82 ±0.5 70 70 4×\(\phi 5.5 \) Thru  82 ±0.5 70 70 70 70 70 70 70 70 70 70 70 70 70	80 L1 32 5 Enter the gear ratio 4x\phi5.5 Thru  Protective Earth Terminal M4  Motor Leads 300 mm Length

Gearhead Model Motor Model Gear Ratio L1 CAD 3~18 32 A447A 3IK15GN-AW2 3GN<sub>□</sub>S 3IK15GN-CW2 **25~180** 42 A447B

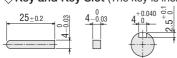
be included by entering  ${\bf J},\,{\bf U}$  or  ${\bf E}$  in the box ( ${\color{red} \blacksquare}$ ) within

within the model name.



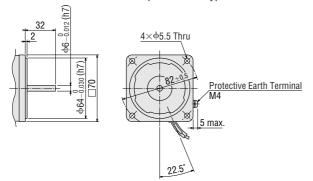
Detail Drawing of Protective Earth Terminal

♦ Key and Key Slot (The key is included with the gearhead)



#### ♦ Shaft Section of Round Shaft Type

The mass and motor's dimensions (excluding the shaft section) are the same as those of the pinion shaft type.



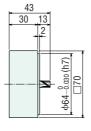
#### 

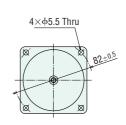
Can be connected to **GN** pinion shaft type.

#### **3GN10XS**

Mass: 0.3 kg

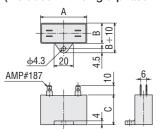
**CAD** A009





#### ♦Capacitor

(Included with single-phase motors)

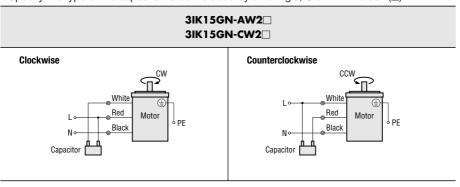


#### 

	del	Capacitor	Α	В	С	Mass	Capacitor
Pinion Shaft Type	Round Shaft Type	Model		_	*	(g)	Cap
3IK15GN-AW2J	3IK15A-AW2J	CH55FAUL2	38	21	31	40	
3IK15GN-AW2U	3IK15A-AW2U	CH45FAUL2	37	18	27	30	Included
3IK15GN-CW2J	3IK15A-CW2J	CH15BFAUL	38	21	31	35	IIIciuaea
3IK15GN-CW2E	3IK15A-CW2E	CH10BFAUL	37	18	27	30	

## Connection Diagrams

- The direction of motor rotation is as viewed from the shaft end of the motor. CW represents the clockwise direction, while CCW represents the counterclockwise direction.
- Connection diagrams are also valid for the equivalent round shaft type.
- Specify the type of the capacitor to be included by entering J, U or E in the box (□) within the model name.



PE: Protective Earth

Note:

 $Change \ the \ direction \ of \ single-phase \ motor \ rotation \ only \ after \ bringing \ the \ motor \ to \ a \ stop.$ 

(RoHS)
Induction Motors

25 W

Frame Size: 

■80 mm





(Gearhead sold separately)

Right-angle gearheads (hollow shaft or solid shaft) can be combined.

Right-Angle Gearheads → Page 108





## ■Specifications - Continuous Rating RoHS

C 7 US	



(	(
_	- 3

	Model Upper Model Name: P Lower Model Name ():	inion Shaft Type	Output Power	Voltage	Frequency	Current	Starting Torque	Rated Torque	Rated Speed	Capacitor
	Lead Wire Type Dimension ①	Terminal Box Type Dimension ②	W	VAC	Hz	А	mN∙m	mN∙m	r/min	μF
(TP)	4IK25GN-AW2J	4IK25GN-AW2TJ	25	Single-Phase 100	50	0.51	130	205	1200	8.0
	(4IK25A-AW2J)	(4IK25A-AW2TJ)	20	Sillyle-Filase 100	60	0.52	120	170	1450	0.0
TP	4IK25GN-AW2U (4IK25A-AW2U)	4IK25GN-AW2TU (4IK25A-AW2TU)	25	Single-Phase 110 Single-Phase 115	60	0.46	120	170	1450	6.5
(TP)	4IK25GN-CW2J	4IK25GN-CW2TJ	25	Cingle Dhoos 200	50	0.26	120	205	1200	2.0
	(4IK25A-CW2J)	(4IK25A-CW2TJ)	20	Single-Phase 200	60	0.20	120	170	1450	2.0
				Single-Phase 220	50	0.27	110	205	1200	
(TP)	4IK25GN-CW2E	4IK25GN-CW2TE	25	Sillyle-Filase 220	60	0.23	110	170	1450	1.5
	(4IK25A-CW2E)	(4IK25A-CW2TE)	23	Single-Phase 230	50	0.27	120	205	1200	1.5
				Sillyle-Filase 250	60	0.23	120	170	1450	
				Three-Phase 200	50	0.23	240	190	1300	
(TP)	4IK25GN-SW2	4IK25GN-SW2T	25	Tillee-Filase 200	60	0.21	160	160	1550	
	(4IK25A-SW2)	(4IK25A-SW2T)	20	Three-Phase 220	60	0.21	160	160	1600	_
				Three-Phase 230	60	0.22	160	160	1600	
TP	_	4IK25GN-UT4* (4IK25A-UT4*)	25	Three-Phase 400	50	0.12	240	190	1300	_

The **J**, **U** and **E** at the end of the model name indicate that the unit includes a capacitor. These letters are not listed on the motor nameplate. When the motor is approved under various safety standards, the model name on the nameplate is the approved model name.

#### Note:

A three-phase 400 VAC motor cannot be used with an inverter. Using them together may lead to deterioration of the motor wiring insulation and damage the products.

(m): Contains a built-in thermal protector. If a motor overheats for any reason, the thermal protector is opened and the motor stops.

When the motor temperature drops, the thermal protector closes and the motor restarts. Be sure to turn the motor off before inspecting.

#### Product Line

#### ● Motor (RoHS)

Type	Mo	del
туре	Pinion Shaft Type	Round Shaft Type
	4IK25GN-AW2J	4IK25A-AW2J
	4IK25GN-AW2U	4IK25A-AW2U
Lead Wire	4IK25GN-CW2J	4IK25A-CW2J
	4IK25GN-CW2E	4IK25A-CW2E
	4IK25GN-SW2	4IK25A-SW2
	4IK25GN-AW2TJ	4IK25A-AW2TJ
	4IK25GN-AW2TU	4IK25A-AW2TU
Terminal Box	4IK25GN-CW2TJ	4IK25A-CW2TJ
Terrilliai Dux	4IK25GN-CW2TE	4IK25A-CW2TE
	4IK25GN-SW2T	4IK25A-SW2T
	4IK25GN-UT4	4IK25A-UT4

#### Gearhead/Right-Angle Gearhead (Sold Separately) (RoHS)

Type	Gearhead Model	Gear Ratio
Long Life/Low Noise/ Parallel Shaft	4GN□S	3, 3.6, 5, 6, 7.5, 9, 12.5, 15, 18, 25, 30, 36, 50, 60, 75, 90, 100, 120, 150, 180
	4GN10XS (Decima	al gearhead)
Right-Angle/ Hollow Shaft	4GN□RH	3, 3.6, 5, 6, 7.5, 9, 12.5, 15, 18, 25, 30, 36, 50, 60, 75, 90, 100, 120, 150, 180
Right-Angle/ Solid Shaft	4GN□RA	3, 3.6, 5, 6, 7.5, 9, 12.5, 15, 18, 25, 30, 36, 50, 60, 75, 90, 100, 120, 150, 180

<sup>■</sup> Enter the gear ratio in the box (□) within the model name.

<sup>\*</sup> Conforms to EN/IEC standards only. Bears the CE Marking.

#### ■Gearmotor – Torque Table

- •Gearheads and decimal gearheads are sold separately.
- ●Enter the code that represents the terminal box type "T" in the box (□) within the model name.
- ■Enter the gear ratio in the box (□) within the model name.
- •A colored background indicates gear shaft rotation in the same direction as the motor shaft, while the others rotate in the opposite direction.
- The speed is calculated by dividing the motor's synchronous speed (50 Hz: 1500 r/min, 60 Hz: 1800 r/min) by the gear ratio. The actual speed is 2 20% less than the displayed value, depending on the size of the load.
- ●To reduce the speed beyond the gear ratio in the table, attach a decimal gearhead (gear ratio: 10) between the gearhead and the motor. In that case, the permissible torque is 8 N·m. When a gearhead of 1/25~1/36 is connected, the value for permissible torque is 6 N·m.

<b>♦</b> 50 Hz																				Uni	it = N·m
Model	Speed r/min	500	416	300	250	200	166	120	100	83	60	50	41	30	25	20	16	15	12.5	10	8.3
Motor/ Gearhead	Gear Ratio	3	3.6	5	6	7.5	9	12.5	15	18	25	30	36	50	60	75	90	100	120	150	180
4IK25GN-AW2□J 4IK25GN-CW2□J 4IK25GN-CW2□E	<b>4GN</b> □S	0.50	0.60	0.83	1.0	1.2	1.5	2.1	2.5	3.0	3.7	4.5	5.4	6.8	8	8	8	8	8	8	8
4IK25GN-SW2□ 4IK25GN-UT4	/ 4GN□S	0.46	0.55	0.77	0.92	1.2	1.4	1.9	2.3	2.8	3.5	4.2	5.0	6.3	7.5	8	8	8	8	8	8
<b>♦60 Hz</b>																				Uni	it = N·m
Model	Speed r/min	600	500	360	300	240	200	144	120	100	72	60	50	36	30	24	20	18	15	12	10
Motor/ Gearhead	Gear Ratio	3	3.6	5	6	7.5	9	12.5	15	18	25	30	36	50	60	75	90	100	120	150	180

1.2

22.5

0.97 | 1.2 | 1.6 | 1.9

2.1

2.5 | 3.1 | 3.7 | 4.5 | 5.6 | 6.7

2.3

2.9 | 3.5 | 4.2 | 5.3 | 6.3 | 7.9 | 8 | 8

1.7

## Permissible Overhung Load and Permissible Thrust Load

0.65 0.78

Motor (Round shaft type) → Page 107 Gearhead → Page 107

#### Permissible Load Inertia J for Gearhead

4GN□S

4GN□S

0.41

0.39 0.47

0.50 | 0.69 | 0.83 | 1.0

→ Page 107

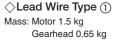
4IK25GN-AW2J 4IK25GN-AW2U

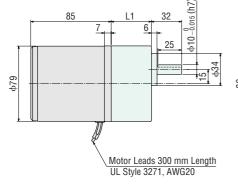
4IK25GN-CW2J 4IK25GN-CW2E

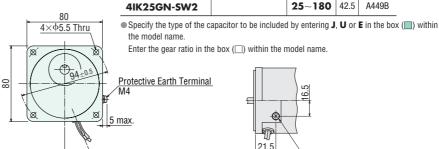
4IK25GN-SW2

#### Dimensions (Unit = mm)

Mounting screws are included with gearheads.







Detail Drawing of Protective Earth Terminal

Protective Earth Terminal

Motor Model	Gearhead Model	Gear Ratio	L1	CAD
4IK25GN-AW2 4IK25GN-CW2	4GN□S	3~18	32	A449A
4IK25GN-CW2	4GN⊔5	<b>25</b> ~180	42.5	A449B

8

8

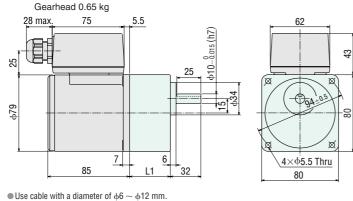
8

8 8

8

 $\Diamond$ Terminal Box Type @





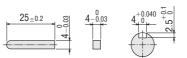
Motor Model	Gearhead Model	Gear Ratio	L1	CAD
4IK25GN-AW2T□ 4IK25GN-CW2T□	4GN⊟S	3~18	32	A451A
4IK25GN-SW2T 4IK25GN-UT4	46N_5	<b>25</b> ~180	42.5	A451B

 $\blacksquare$  Specify the type of the capacitor to be included by entering  ${\bf J},\,{\bf U}$  or  ${\bf E}$  in the box ( ) within the model name.

Enter the gear ratio in the box (
) within the model name.

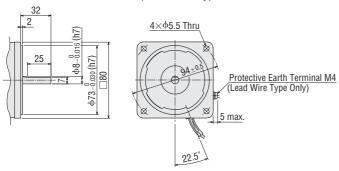
#### 

(The key is included with the gearhead)



#### ♦ Shaft Section of Round Shaft Type

The mass and motor's dimensions (excluding the shaft section) are the same as those of the pinion shaft type.



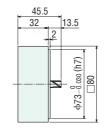
#### 

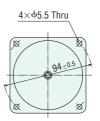
Can be connected to **GN** pinion shaft type.

#### 4GN10XS

Mass: 0.4 kg

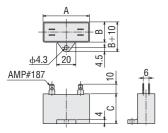
#### **CAD** A013





# ♦Capacitor

(Included with single-phase motors)

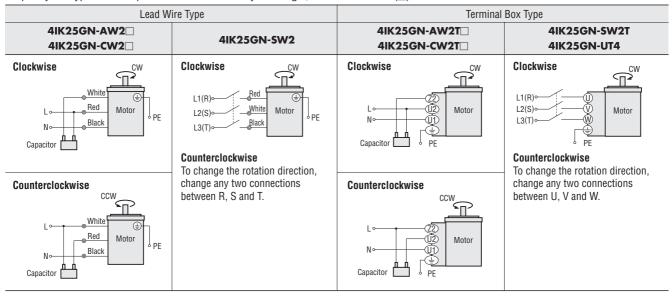


#### 

Upper Model Name Lower Model Name	e: Pinion Shaft Type ( ): Round Shaft Type	Capacitor Model	Α	В	С	Mass (g)	Capacitor Cap			
Lead Wire Type	Terminal Box Type									
4IK25GN-AW2J (4IK25A-AW2J)	4IK25GN-AW2TJ (4IK25A-AW2TJ)	CH80CFAUL2	48	21	31	45				
4IK25GN-AW2U (4IK25A-AW2U)	4IK25GN-AW2TU (4IK25A-AW2TU)	CH65CFAUL2	48	19	29	40	Included			
4IK25GN-CW2J (4IK25A-CW2J)	4IK25GN-CW2TJ (4IK25A-CW2TJ)	CH20BFAUL	48	19	29	35	Iliciadea			
4IK25GN-CW2E (4IK25A-CW2E)	CH15BFAUL	38	21	31	35					
	Upper Model Name Lower Model Name Lead Wire Type  4IK25GN-AW2J (4IK25A-AW2J)  4IK25GN-AW2U (4IK25A-AW2U)  4IK25GN-CW2J (4IK25A-CW2J)  4IK25GN-CW2E	4IK25GN-AW2J 4IK25GN-AW2TJ (4IK25A-AW2TJ) (4IK25A-AW2TJ) 4IK25GN-AW2U (4IK25A-AW2TU) (4IK25A-AW2TU) 4IK25GN-CW2J 4IK25GN-CW2TJ (4IK25A-CW2TJ) 4IK25GN-CW2E 4IK25GN-CW2TE	Upper Model Name: Pinion Shaft Type							

#### Connection Diagrams

- The direction of motor rotation is as viewed from the shaft end of the motor. CW represents the clockwise direction, while CCW represents the counterclockwise direction.
- •Connection diagrams are also valid for the equivalent round shaft type.
- ●Specify the type of the capacitor to be included by entering **J**, **U** or **E** in the box (□) within the model name.



PE: Protective Earth

Note:

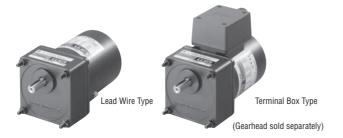
Change the direction of single-phase motor rotation only after bringing the motor to a stop.

(RoHS)
Induction Motors

40 W

Frame Size: 

□90 mm



Right-angle gearheads (hollow shaft or solid shaft) can be combined.

Right-Angle Gearheads → Page 108





# ■Specifications – Continuous Rating RoHS

<b>. 71</b> ° us	<b>(W)</b>
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Mode Upper Model Name: I Lower Model Name ( ):	Pinion Shaft Type	Output Power	Voltage	Frequency	Current	Starting Torque	Rated Torque	Rated Speed	Capacitor	
Lead Wire Type Dimension ①	Terminal Box Type Dimension ②	W	VAC	Hz	A	mN∙m	mN∙m	r/min	μF	
5IK40GN-AW2J	5IK40GN-AW2TJ	40	Single-Phase 100	50	0.76	200	315	1250	11	
(5IK40A-AW2J)	(5IK40A-AW2TJ)	40	Sillyle-Filase 100	60	0.74	200	260	1500	''	
5IK40GN-AW2U	5IK40GN-AW2TU	40	Single-Phase 110	60	0.68	200	260	1500	9.0	
(5IK40A-AW2U)	(5IK40A-AW2TU)	40	Single-Phase 115	00	0.67	200	200	1500	9.0	
5IK40GN-CW2J	5IK40GN-CW2TJ	40	Single-Phase 200	50	0.39	200	315	1250	3.0	
(5IK40A-CW2J)	(5IK40A-CW2TJ)	40	Sillyle-Filase 200	60	0.40	200	260	1500	3.0	
			Single-Phase 220	50	0.39		315	1250		
5IK40GN-CW2E	5IK40GN-CW2TE	40	Sillyle-Filase 220	60	0.35	200	260	1500	2.3	
(5IK40A-CW2E)	(5IK40A-CW2TE)	40	Cinala Dhaga 220	50	0.39	200	300	1300	2.3	
			Single-Phase 230	60	0.34		260	1500		
			Three-Phase 200	50	0.32	400	300	1300		
5IK40GN-SW2	5IK40GN-SW2T	40	Tillee-Filase 200	60	0.30	260	260	1550		
(5IK40A-SW2)	(5IK40A-SW2T)	40	Three-Phase 220	60	0.30	260	260	1600	_	
			Three-Phase 230	60	0.31	260	260	1600		
<b>TP</b> –	5IK40GN-UT4* (5IK40A-UT4*)	40	Three-Phase 400	50	0.16	500	315	1250	-	

<sup>●</sup> The J, U and E at the end of the model name indicate that the unit includes a capacitor. These letters are not listed on the motor nameplate.

#### Note:

A three-phase 400 VAC motor cannot be used with an inverter. Using them together may lead to deterioration of the motor wiring insulation and damage the products.

(TP): Contains a built-in thermal protector. If a motor overheats for any reason, the thermal protector is opened and the motor stops.

When the motor temperature drops, the thermal protector closes and the motor restarts. Be sure to turn the motor off before inspecting.

#### **Product Line**

#### ● Motor (RoHS)

Type	Mo	odel
туре	Pinion Shaft Type	Round Shaft Type
	5IK40GN-AW2J	5IK40A-AW2J
	5IK40GN-AW2U	5IK40A-AW2U
Lead Wire	5IK40GN-CW2J	5IK40A-CW2J
	5IK40GN-CW2E	5IK40A-CW2E
	5IK40GN-SW2	5IK40A-SW2
	5IK40GN-AW2TJ	5IK40A-AW2TJ
	5IK40GN-AW2TU	5IK40A-AW2TU
Terminal Box	5IK40GN-CW2TJ	5IK40A-CW2TJ
Terriniai dux	5IK40GN-CW2TE	5IK40A-CW2TE
	5IK40GN-SW2T	5IK40A-SW2T
	5IK40GN-UT4	5IK40A-UT4

#### Gearhead/Right-Angle Gearhead (Sold Separately) (RoHS)

Type	Gearhead Model	Gear Ratio
Long Life/Low Noise/ Parallel Shaft	5GN□S	3, 3.6, 5, 6, 7.5, 9, 12.5, 15, 18, 25, 30, 36, 50, 60, 75, 90, 100, 120, 150, 180
	5GN 10XS (Decima	al gearhead)
Right-Angle/ Hollow Shaft	5GN□RH	3, 3.6, 5, 6, 7.5, 9, 12.5, 15, 18, 25, 30, 36, 50, 60, 75, 90, 100, 120, 150, 180
Right-Angle/ Solid Shaft	5GN□RA	3, 3.6, 5, 6, 7.5, 9, 12.5, 15, 18, 25, 30, 36, 50, 60, 75, 90, 100, 120, 150, 180

 $<sup>\</sup>bullet$  Enter the gear ratio in the box (  $\square$  ) within the model name.

When the motor is approved under various safety standards, the model name on the nameplate is the approved model name.

<sup>\*</sup>Conforms to EN/IEC standards only. Bears the CE Marking.

#### ■Gearmotor – Torque Table

- •Gearheads and decimal gearheads are sold separately.
- ●Enter the code that represents the terminal box type "T" in the box (□) within the model name.
- ■Enter the gear ratio in the box (□) within the model name.
- •A colored background indicates gear shaft rotation in the same direction as the motor shaft, while the others rotate in the opposite direction.
- The speed is calculated by dividing the motor's synchronous speed (50 Hz: 1500 r/min, 60 Hz: 1800 r/min) by the gear ratio.
- The actual speed is 2 20% less than the displayed value, depending on the size of the load.
- ■To reduce the speed beyond the gear ratio in the table, attach a decimal gearhead (gear ratio: 10) between the gearhead and the motor. In that case, the permissible torque is 10 N·m.

♦ 50 Hz														t = N·m							
Model	Speed r/min	500	416	300	250	200	166	120	100	83	60	50	41	30	25	20	16	15	12.5	10	8.3
Motor/ Gearhead	Gear Ratio	3	3.6	5	6	7.5	9	12.5	15	18	25	30	36	50	60	75	90	100	120	150	180
5IK40GN-AW2_J 5IK40GN-CW2_J 5IK40GN-CW2_E (Single-phase 220 VAC)	5GN□S	0.77	0.92	1.3	1.5	1.9	2.3	3.2	3.8	4.6	5.7	6.9	8.3	10	10	10	10	10	10	10	10
5IK40GN-CW2  (Single-phase 230 VAC)  5IK40GN-SW2	5GN□S	0.73	0.87	1.2	1.5	1.8	2.2	3.0	3.6	4.4	5.5	6.6	7.9	9.9	10	10	10	10	10	10	10
5IK40GN-UT4	/ 5GN□S	0.77	0.92	1.3	1.5	1.9	2.3	3.2	3.8	4.6	5.7	6.9	8.3	10	10	10	10	10	10	10	10

<b>♦60 Hz</b>	<u>♦60 Hz</u> Un															Uni	it = N·m				
Model	Speed r/min	600	500	360	300	240	200	144	120	100	72	60	50	36	30	24	20	18	15	12	10
Motor/ Gearhead	Gear Ratio	3	3.6	5	6	7.5	9	12.5	15	18	25	30	36	50	60	75	90	100	120	150	180
5IK40GN-AW2  5IK40GN-AW2  U  5IK40GN-CW2  J  5IK40GN-CW2  E  5IK40GN-SW2	5GN□S	0.63	0.76	1.1	1.3	1.6	1.9	2.6	3.2	3.8	4.7	5.7	6.8	8.6	10	10	10	10	10	10	10

## Permissible Overhung Load and Permissible Thrust Load

Motor (Round shaft type) → Page 107 Gearhead → Page 107

#### Permissible Load Inertia J for Gearhead

→ Page 107

#### Dimensions (Unit = mm)

Mounting screws are included with gearheads.

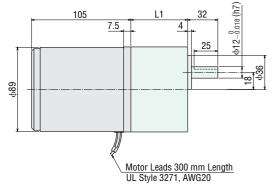
♦ Lead Wire Type ①
Mass: Motor 2.5 kg

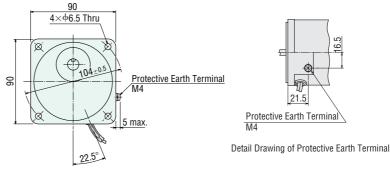
Gearhead 1.5 kg

Motor Model	Gearhead Model	Gear Ratio	L1	CAD
5IK40GN-AW2	FON T	3~18	42	A452A
5IK40GN-CW2  5IK40GN-SW2	5GN <b>□</b> S	25~180	60	A452B

Specify the type of the capacitor to be included by entering J, U or E in the box () within the model name.

Enter the gear ratio in the box ( $\square$ ) within the model name.



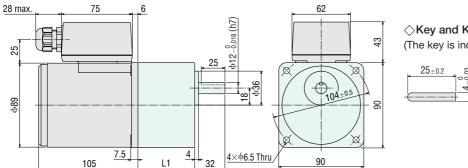


Mass: Motor 2.6 kg Gearhead 1.5 kg

Motor Model	Gearhead Model	Gear Ratio	L1	CAD
5IK40GN-AW2T 5IK40GN-CW2T	5GN□S	3~18	42	A454A
5IK40GN-SW2T 5IK40GN-UT4	3GN_3	<b>25</b> ~180	60	A454B

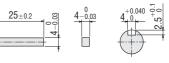
 $<sup>\</sup>bullet$  Specify the type of the capacitor to be included by entering  ${\bf J},\,{\bf U}$  or  ${\bf E}$  in the box ( ) within the model name

Enter the gear ratio in the box  $(\Box)$  within the model name.



#### 

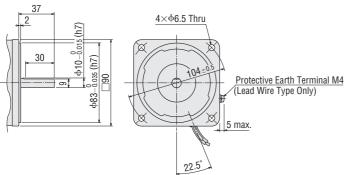
(The key is included with the gearhead)



 $\bullet$  Use cable with a diameter of  $\varphi 6 \sim \varphi 12$  mm.

#### ♦ Shaft Section of Round Shaft Type

The mass and motor's dimensions (excluding the shaft section) are the same as those of the pinion shaft type.

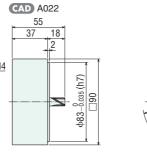


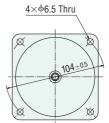
#### 

Can be connected to **GN** pinion shaft type.

#### **5GN10XS**

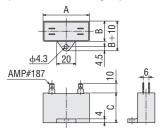
Mass: 0.6 kg





#### 

(Included with single-phase motors)

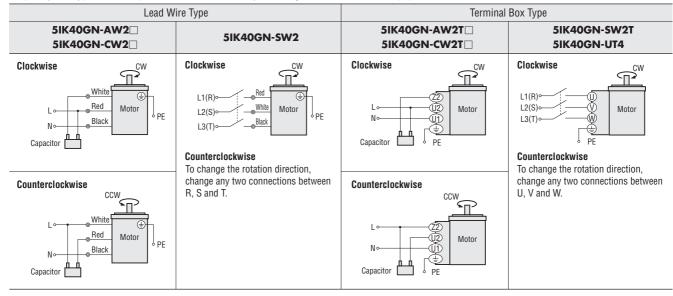


#### 

Upper Model Name	odel e: Pinion Shaft Type ( ): Round Shaft Type	Capacitor Model	Α	В	С	Mass (g)	Capacitor Cap
Lead Wire Type	Terminal Box Type						
5IK40GN-AW2J (5IK40A-AW2J)	5IK40GN-AW2TJ (5IK40A-AW2TJ)	CH110CFAUL2	58	21	31	50	
5IK40GN-AW2U (5IK40A-AW2U)					31.5	45	Included
5IK40GN-CW2J (5IK40A-CW2J)	5IK40GN-CW2TJ (5IK40A-CW2TJ)	CH30BFAUL	58	21	31	50	iliciuded
5IK40GN-CW2E (5IK40A-CW2E)	CH23BFAUL	48	21	31	40		

#### Connection Diagrams

- The direction of motor rotation is as viewed from the shaft end of the motor. CW represents the clockwise direction, while CCW represents the counterclockwise direction.
- Connection diagrams are also valid for the equivalent round shaft type.
- Specify the type of the capacitor to be included by entering J, U or E in the box (□) within the model name.



PE: Protective Earth

Note

Change the direction of single-phase motor rotation only after bringing the motor to a stop.

Induction Motors

# **60 W**

Frame Size: **□90** mm





(Gearhead sold separately)

Right-angle gearheads (hollow shaft or solid shaft) can be combined.

Right-Angle Gearheads → Page 108





# ■Specifications – Continuous Rating (RoHS)

<b>. 71</b> °us	(W)	C	(
	$\sim$	_	-

Mode Upper Model Name: F Lower Model Name ():	Pinion Shaft Type	Output Power	Voltage	Frequency	Current	Starting Torque	Rated Torque	Rated Speed	Capacitor
Lead Wire Type Dimension ①	Terminal Box Type Dimension ②	W	VAC	Hz	A	mN∙m	mN∙m	r/min	μF
5IK60GE-AW2J	5IK60GE-AW2TJ	60	Single-Phase 100	50	1.20	320	490	1200	20
(5IK60A-AW2J)	(5IK60A-AW2TJ)	00	Sillyle-Filase 100	60	1.19	320	405	1450	20
5IK60GE-AW2U	5IK60GE-AW2TU	60	Single-Phase 110	60	1.09	320	405	1450	18
(5IK60A-AW2U)	(5IK60A-AW2TU)	60	Single-Phase 115	00	1.10	320	405	1450	10
5IK60GE-CW2J	5IK60GE-CW2TJ	60	Cinalo Dhoos 200	50	0.57	320	490	1200	5.0
(5IK60A-CW2J)	(5IK60A-CW2TJ)	60	Single-Phase 200	60	0.65	320	405	1450	5.0
			Cingle Dhoos 220	50	0.55		490	1200	
5IK60GE-CW2E	5IK60GE-CW2TE	60	Single-Phase 220	60	0.54	320	405	1450	4.0
(5IK60A-CW2E)	(5IK60A-CW2TE)	60	Cinala Dhana 000	50	0.57	320	490	1200	4.0
			Single-Phase 230	60	0.54		405	1450	
			Three Dhace 200	50	0.50	600	450	1300	
5IK60GE-SW2	5IK60GE-SW2T	60	Three-Phase 200	60	0.43	500	380	1550	
(5IK60A-SW2)	(5IK60A-SW2T)	00	Three-Phase 220	60	0.45	500	380	1600	_
			Three-Phase 230	60	0.46	500	380	1600	
<b>TP</b> –	5IK60GE-UT4F* (5IK60A-UT4F*)	60	Three-Phase 400	50	0.25	550	470	1250	-

<sup>•</sup> The J, U and E at the end of the model name indicate that the unit includes a capacitor. These letters are not listed on the motor nameplate.
When the motor is approved under various safety standards, the model name on the nameplate is the approved model name.

#### Note:

A three-phase 400 VAC motor cannot be used with an inverter. Using them together may lead to deterioration of the motor wiring insulation and damage the products.

(TP): Contains a built-in thermal protector. If a motor overheats for any reason, the thermal protector is opened and the motor stops.

When the motor temperature drops, the thermal protector closes and the motor restarts. Be sure to turn the motor off before inspecting.

#### Product Line

#### ● Motor (RoHS)

Tuno	N	lodel
Type	Pinion Shaft Type	Round Shaft Type
	5IK60GE-AW2J	5IK60A-AW2J
	5IK60GE-AW2U	5IK60A-AW2U
Lead Wire	5IK60GE-CW2J	5IK60A-CW2J
	5IK60GE-CW2E	5IK60A-CW2E
	5IK60GE-SW2	5IK60A-SW2
	5IK60GE-AW2TJ	5IK60A-AW2TJ
	5IK60GE-AW2TU	5IK60A-AW2TU
Terminal Box	5IK60GE-CW2TJ	5IK60A-CW2TJ
Terrilliai box	5IK60GE-CW2TE	5IK60A-CW2TE
	5IK60GE-SW2T	5IK60A-SW2T
	5IK60GE-UT4F	5IK60A-UT4F

#### • Gearhead/Right-Angle Gearhead (Sold Separately) (RoHS)

Type	Gearhead Model	Gear Ratio
Long Life/ Parallel Shaft	5GE□S	3, 3.6, 5, 6, 7.5, 9, 12.5, 15, 18, 25, 30, 36, 50, 60, 75, 90, 100, 120, 150, 180
	5GE10XS (Decima	I gearhead)
Right-Angle/ Hollow Shaft	5GE□RH	3, 3.6, 5, 6, 7.5, 9, 12.5, 15, 18, 25, 30, 36, 50, 60, 75, 90, 100, 120, 150, 180
Right-Angle/ Solid Shaft	5GE□RA	3, 3.6, 5, 6, 7.5, 9, 12.5, 15, 18, 25, 30, 36, 50, 60, 75, 90, 100, 120, 150, 180

 $<sup>\</sup>bullet$  Enter the gear ratio in the box (  $\square$  ) within the model name.

<sup>\*</sup>Conforms to EN/IEC standards only. Bears the CE Marking.

#### ■Gearmotor – Torque Table

- •Gearheads and decimal gearheads are sold separately.
- ●Enter the code that represents the terminal box type "**T**" in the box (□) within the model name.
- ●Enter the gear ratio in the box (□) within the model name.
- •A colored background indicates gear shaft rotation in the same direction as the motor shaft, while the others rotate in the opposite direction.
- The speed is calculated by dividing the motor's synchronous speed (50 Hz: 1500 r/min, 60 Hz: 1800 r/min) by the gear ratio.
- The actual speed is 2 20% less than the displayed value, depending on the size of the load.
- ■To reduce the speed beyond the gear ratio in the table, attach a decimal gearhead (gear ratio: 10) between the gearhead and the motor. In that case, the permissible torque is 20 N·m.

<>50 Hz																				Uni	t = N·m
Model	Speed r/min	500	416	300	250	200	166	120	100	83	60	50	41	30	25	20	16	15	12.5	10	8.3
Motor/ Gearhead	Gear Ratio	3	3.6	5	6	7.5	9	12.5	15	18	25	30	36	50	60	75	90	100	120	150	180
5IK60GE-AW2J 5IK60GE-CW2J 5IK60GE-CW2E	5GE□S	1.2	1.4	2.0	2.4	3.0	3.6	4.5	5.4	6.4	8.1	9.7	11.6	16.2	19.4	20	20	20	20	20	20
5IK60GE-SW2■	5GE□S	1.1	1.3	1.8	2.2	2.7	3.3	4.1	4.9	5.9	7.4	8.9	10.7	14.9	17.8	19.9	20	20	20	20	20
5IK60GE-UT4F	5GE□S	1.1	1.4	1.9	2.3	2.9	3.4	4.3	5.1	6.2	7.8	9.3	11	16	19	20	20	20	20	20	20

<b>♦60 Hz</b>																				Uni	t = N·m
Model	Speed r/min	600	500	360	300	240	200	144	120	100	72	60	50	36	30	24	20	18	15	12	10
Motor/ Gearhead	Gear Ratio	3	3.6	5	6	7.5	9	12.5	15	18	25	30	36	50	60	75	90	100	120	150	180
5IK60GE-AW2_U 5IK60GE-AW2_U 5IK60GE-CW2_J 5IK60GE-CW2_E	<b>5GE</b> □S	0.98	1.2	1.6	2.0	2.5	3.0	3.7	4.4	5.3	6.7	8.0	9.6	13.4	16.0	17.9	20	20	20	20	20
5IK60GE-SW2	5GE□S	0.92	1.1	1.5	1.8	2.3	2.8	3.5	4.2	5.0	6.3	7.5	9.0	12.5	15.0	16.8	20	20	20	20	20

## ■Permissible Overhung Load and Permissible Thrust Load

Motor (Round shaft type) → Page 107 Gearhead → Page 107

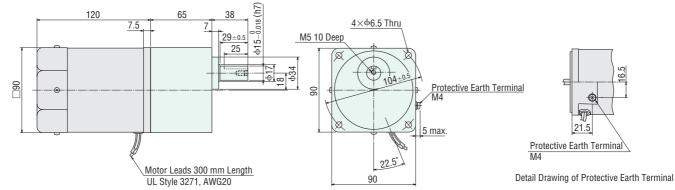
#### Permissible Load Inertia J for Gearhead

→ Page 107

#### Dimensions (Unit = mm)

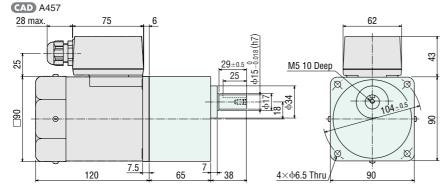
Mounting screws are included with gearheads.

**CAD** A455



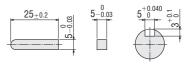
 $\Diamond$ Terminal Box Type @

Mass: Motor 2.8 kg Gearhead 1.5 kg



#### 

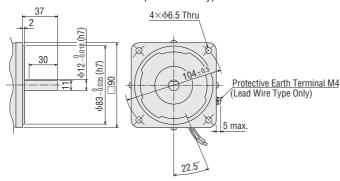
(The key is included with the gearhead)



• Use cable with a diameter of  $\phi 6 \sim \phi 12$  mm.

#### ♦ Shaft Section of Round Shaft Type

The mass and motor's dimensions (excluding the shaft section) are the same as those of the pinion shaft type.



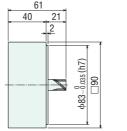
#### 

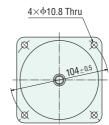
Can be connected to **GE** pinion shaft type.

#### 5GE10XS

Mass: 0.6 kg

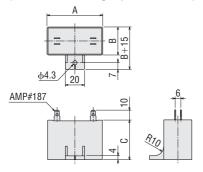
**CAD** A029





## 

(Included with single-phase motors)

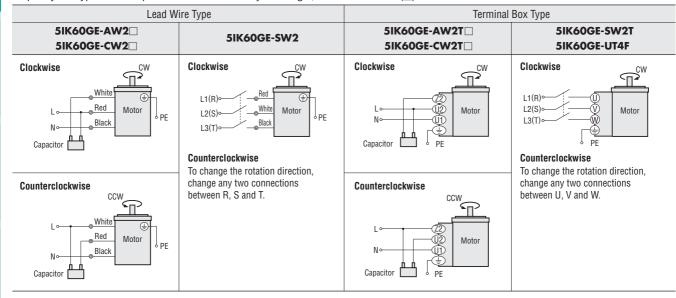


#### 

Upper Model Name	Upper Model Name: Pinion Shaft Type Lower Model Name ( ): Round Shaft Type				С	Mass (g)	Capacitor Cap
	Terminal Box Type						
5IK60GE-AW2J (5IK60A-AW2J)	5IK60GE-AW2TJ (5IK60A-AW2TJ)	CH200CFAUL2	58	29	41	95	
5IK60GE-AW2U (5IK60A-AW2U)	5IK60GE-AW2TU (5IK60A-AW2TU)	CH180CFAUL2	58	29	41	95	Included
5IK60GE-CW2J (5IK60A-CW2J)	5IK60GE-CW2TJ (5IK60A-CW2TJ)	CH50BFAUL	58	29	41	85	iliciuded
5IK60GE-CW2E (5IK60A-CW2E)	5IK60GE-CW2TE (5IK60A-CW2TE)	CH40BFAUL	58	23.5	37	70	

## ■Connection Diagrams

- The direction of motor rotation is as viewed from the shaft end of the motor. CW represents the clockwise direction, while CCW represents the counterclockwise direction.
- Connection diagrams are also valid for the equivalent round shaft type.
- Specify the type of the capacitor to be included by entering J, U or E in the box (□) within the model name.



PE: Protective Earth

Note:

Change the direction of single-phase motor rotation only after bringing the motor to a stop.

RoHS Induction Motors

90 W

Frame Size: 

□90 mm





Right-angle gearheads (hollow shaft or solid shaft) can be combined.

Right-Angle Gearheads → Page 108





## ■Specifications - Continuous Rating RoHS



•			• •	_				•	
Mode Upper Model Name: Lower Model Name ()	Pinion Shaft Type	Output Voltage Power		Frequency	Current	Starting Torque	Rated Torque	Rated Speed	Capacitor
Lead Wire Type Dimension ①	Terminal Box Type Dimension ②	W	VAC	Hz	Α	mN•m	mN∙m	r/min	μF
5IK90GE-AW2J	5IK90GE-AW2TJ	90	Single-Phase 100	50	1.64	450	700	1250	28
(5IK90A-AW2J)	(5IK90A-AW2TJ)	90	Siligie-Filase 100	60	1.67	450	585	1500	20
5IK90GE-AW2U	5IK90GE-AW2TU	90	Single-Phase 110	60	1.45	450	585	1500	20
(5IK90A-AW2U)	(5IK90A-AW2TU)	90	Single-Phase 115	00	1.44	450	565	1500	20
5IK90GE-CW2J	5IK90GE-CW2TJ	90	Single-Phase 200	50	0.80	450	730	1200	7.0
(5IK90A-CW2J)	(5IK90A-CW2TJ)	90	Siligie-Filase 200	60	0.93	450	605	1450	7.0
			Single-Phase 220	50	0.74		730	1200	
5IK90GE-CW2E	5IK90GE-CW2TE	90	Siligie-Pliase 220	60	0.82	450	605	1450	6.0
(5IK90A-CW2E)	(5IK90A-CW2TE)	90	Single-Phase 230	50	0.76	450	730	1200	0.0
			Sillyle-Filase 230	60	0.81		605	1450	
			Three Dhage 200	50	0.64	850	680	1300	
5IK90GE-SW2	5IK90GE-SW2T	00	Three-Phase 200	60	0.59	700	570	1550	
(5IK90A-SW2)	(5IK90A-SW2T)	90 Three-Phase 220		60	0.60	700	570	1600	_
			Three-Phase 230	60	0.61	700	570	1600	
<b>TP</b> –	5IK90GE-UT4F* (5IK90A-UT4F*)	90	Three-Phase 400	50	0.35	850	700	1250	-

<sup>•</sup> The **J**, **U** and **E** at the end of the model name indicate that the unit includes a capacitor. These letters are not listed on the motor nameplate. When the motor is approved under various safety standards, the model name on the nameplate is the approved model name.

#### Note

A three-phase 400 VAC motor cannot be used with an inverter. Using them together may lead to deterioration of the motor wiring insulation and damage the products.

(D): Contains a built-in thermal protector. If a motor overheats for any reason, the thermal protector is opened and the motor stops.

When the motor temperature drops, the thermal protector closes and the motor restarts. Be sure to turn the motor off before inspecting.

#### Product Line

#### ● Motor (RoHS)

Type	Mo	del
туре	Pinion Shaft Type	Round Shaft Type
	5IK90GE-AW2J	5IK90A-AW2J
	5IK90GE-AW2U	5IK90A-AW2U
Lead Wire	5IK90GE-CW2J	5IK90A-CW2J
	5IK90GE-CW2E	5IK90A-CW2E
	5IK90GE-SW2	5IK90A-SW2
	5IK90GE-AW2TJ	5IK90A-AW2TJ
	5IK90GE-AW2TU	5IK90A-AW2TU
Terminal Box	5IK90GE-CW2TJ	5IK90A-CW2TJ
Terrilliai bux	5IK90GE-CW2TE	5IK90A-CW2TE
	5IK90GE-SW2T	5IK90A-SW2T
	5IK90GE-UT4F	5IK90A-UT4F

#### Gearhead/Right-Angle Gearhead (Sold Separately) (RoHS)

Type	Gearhead Model	Gear Ratio
Long Life/ Parallel Shaft	5GE□S	3, 3.6, 5, 6, 7.5, 9, 12.5, 15, 18, 25, 30, 36, 50, 60, 75, 90, 100, 120, 150, 180
	5GE10XS (Decima	l gearhead)
Right-Angle/ Hollow Shaft	5GE□RH	3, 3.6, 5, 6, 7.5, 9, 12.5, 15, 18, 25, 30, 36, 50, 60, 75, 90, 100, 120, 150, 180
Right-Angle/ Solid Shaft	5GE□RA	3, 3.6, 5, 6, 7.5, 9, 12.5, 15, 18, 25, 30, 36, 50, 60, 75, 90, 100, 120, 150, 180

<sup>■</sup> Enter the gear ratio in the box (□) within the model name.

<sup>\*</sup>Conforms to EN/IEC standards only. Bears the CE Marking.

#### Gearmotor – Torque Table

- Gearheads and decimal gearheads are sold separately.
- ●Enter the code that represents the terminal box type "**T**" in the box (□) within the model name.
- ■Enter the gear ratio in the box (□) within the model name.
- •A colored background indicates gear shaft rotation in the same direction as the motor shaft, while the others rotate in the opposite direction.
- The speed is calculated by dividing the motor's synchronous speed (50 Hz: 1500 r/min, 60 Hz: 1800 r/min) by the gear ratio. The actual speed is 2 20% less than the displayed value, depending on the size of the load.
- ■To reduce the speed beyond the gear ratio in the table, attach a decimal gearhead (gear ratio: 10) between the gearhead and the motor. In that case, the permissible torque is 20 N·m.

♦ 50 HZ																				UIII	it = iv·m
Model	Speed r/min	500	416	300	250	200	166	120	100	83	60	50	41	30	25	20	16	15	12.5	10	8.3
Motor/ Gearhead	Gear Ratio	3	3.6	5	6	7.5	9	12.5	15	18	25	30	36	50	60	75	90	100	120	150	180
5IK90GE-AW2_J	5GE□S	1.7	2.0	2.8	3.4	4.3	5.1	6.4	7.7	9.2	11.6	13.9	16.6	20	20	20	20	20	20	20	20
5IK90GE-CW2J 5IK90GE-CW2E	5GE□S	1.8	2.1	3.0	3.5	4.4	5.3	6.7	8.0	9.6	12.0	14.5	17.3	20	20	20	20	20	20	20	20
5IK90GE-SW2	5GE□S	1.7	2.0	2.8	3.3	4.1	5.0	6.2	7.4	8.9	11.2	13.5	16.2	20	20	20	20	20	20	20	20
5IK90GE-UT4F	/ 5GE□S	1.7	2.0	2.8	3.4	4.3	5.1	6.4	7.7	9.2	12	14	17	20	20	20	20	20	20	20	20

<>60 Hz																				Uni	it = N·m
Model	Speed r/min	600	500	360	300	240	200	144	120	100	72	60	50	36	30	24	20	18	15	12	10
Motor/ Gearhead	Gear Ratio	3	3.6	5	6	7.5	9	12.5	15	18	25	30	36	50	60	75	90	100	120	150	180
5IK90GE-AW2□J 5IK90GE-AW2□U	/ 5GE□S	1.4	1.7	2.4	2.8	3.6	4.3	5.3	6.4	7.7	9.7	11.6	13.9	19.3	20	20	20	20	20	20	20
5IK90GE-CW2J 5IK90GE-CW2E	/ 5GE□S	1.5	1.8	2.5	2.9	3.7	4.4	5.5	6.6	7.9	10.0	12.0	14.4	20	20	20	20	20	20	20	20
5IK90GE-SW2■	/ 5GE□S	1.4	1.7	2.3	2.8	3.5	4.2	5.2	6.2	7.5	9.4	11.3	13.5	18.8	20	20	20	20	20	20	20

## Permissible Overhung Load and Permissible Thrust Load

Motor (Round shaft type) → Page 107 Gearhead → Page 107

#### Permissible Load Inertia J for Gearhead

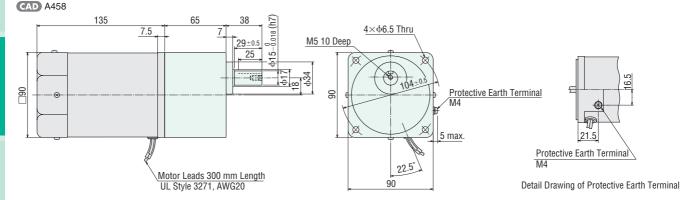
→ Page 107

#### ■ Dimensions (Unit = mm)

Mounting screws are included with gearheads.

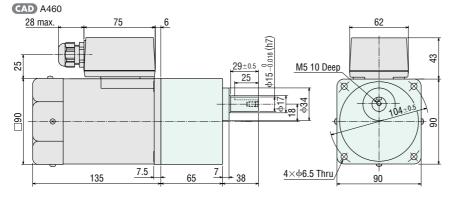
 $\diamondsuit$ Lead Wire Type 1

Mass: Motor 3.2 kg Gearhead 1.5 kg



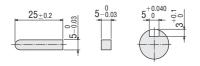
♦ Terminal Box Type ②

Mass: Motor 3.3 kg Gearhead 1.5 kg



#### 

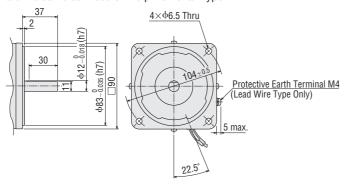
(The key is included with the gearhead)



• Use cable with a diameter of  $\phi 6 \sim \phi 12$  mm.

#### ♦ Shaft Section of Round Shaft Type

The mass and motor's dimensions (excluding the shaft section) are the same as those of the pinion shaft type.



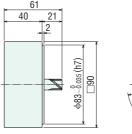
#### 

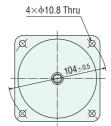
Can be connected to **GE** pinion shaft type.

#### 5GE10XS

Mass: 0.6 kg

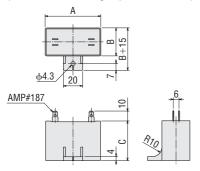
**CAD** A029





#### 

(Included with single-phase motors)

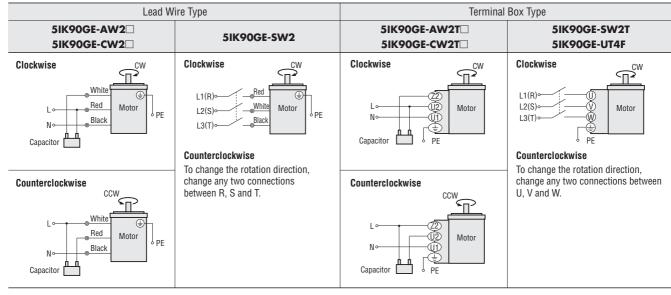


#### $\diamondsuit$ Capacitor Dimensions (mm)

Upper Model Name	del e: Pinion Shaft Type ( ): Round Shaft Type Terminal Box Type	Capacitor Model	А	В	С	Mass (g)	Capacitor Cap		
5IK90GE-AW2J (5IK90A-AW2J)	5IK90GE-AW2TJ (5IK90A-AW2TJ)	CH280CFAUL2	58	35	50	140			
5IK90GE-AW2U (5IK90A-AW2U)	5IK90GE-AW2TU (5IK90A-AW2TU)	CH200CFAUL2	58	29	41	95	Included		
5IK90GE-CW2J (5IK90A-CW2J)	5IK90GE-CW2TJ (5IK90A-CW2TJ)	CH70BFAUL	58	35	50	130	Included		
5IK90GE-CW2E (5IK90A-CW2E)	5IK90GE-CW2TE (5IK90A-CW2TE)	CH60BFAUL	58	29	41	85			

#### Connection Diagrams

- The direction of motor rotation is as viewed from the shaft end of the motor. CW represents the clockwise direction, while CCW represents the counterclockwise direction.
- Connection diagrams are also valid for the equivalent round shaft type.
- Specify the type of the capacitor to be included by entering J, U or E in the box (□) within the model name.



PE: Protective Earth

Note

Change the direction of single-phase motor rotation only after bringing the motor to a stop.

RoHS

# **Induction Motors 2-Pole, High-Speed Type**

 $40\,W{\sim}150\,W$ 

Frame Size: 

■80 mm · ■90 mm





# ■Specifications – Continuous Rating

	Model	Output Power	Voltage	Frequency	Current	Starting Torque	Rated Torque	Rated Speed	Capacitor
	Round Shaft Type	w	VAC	Hz	А	mN·m	mN·m	r/min	μF
_				50	0.77		160	2400	
P	4IK40A-BW2J	40	Single-Phase 100	60	0.73	90	135	2900	9.0
P	4IK40A-BW2U	40	Single-Phase 110 Single-Phase 115	60	0.68	90	135	2900	7.5
P	4IK40A-DW2J	40	Single-Phase 200	50	0.39	90	160	2400	2.3
<u> </u>	4IK4UA-DW2J	40	Siligie-Filase 200	60	0.37	90	135	2900	2.3
		36	Single-Phase 220	50	0.30		145	2400	
	AIVADA DWZE	30	Sillyle-Filase 220	60	0.31	90	120	2900	1.0
TP)	4IK40A-DW3E	40	Single-Phase 230	50	0.33	90	160	2400	1.8
		40	Siligie-Pliase 230	60	0.32		135	2900	
P)	IK60A-BW2J	60	Single-Phase 100	50	1.09	160	230	2500	14
<b>P</b> )	4IKOUA-BWZJ	60	Single-Phase 100	60	1.25		190	3000	
P	4IK60A-BW2U	60	Single-Phase 110 Single-Phase 115	60	0.98 0.97	160	190	3000	10
			0. 1 0. 000	50	0.54	400	230	2500	3.0
P	4IK60A-DW2J 60	60	Single-Phase 200	60	0.57	160	190	3000	
		55	0'I Pl 000	50	0.44	160	210	2500	2.5
			Single-Phase 220	60	0.51		180	3000	
(P)	4IK60A-DW3E		0' I - Di 000	50	0.47		230	2500	
		60	Single-Phase 230	60	0.52		190	3000	
			0	50	1.01		220	2650	16
[P	5IK60A-BW2J	60	Single-Phase 100	60	1.03	140	185	3200	
[P	5IK60A-BW2U	60	Single-Phase 110 Single-Phase 115	60	0.94 0.93	140	185	3200	14
_				50	0.51		220	2650	4.0
IP)	5IK60A-DW2J	60	Single-Phase 200	60	0.52	140	185	3200	
				50			220	2650	
			Single-Phase 220	60	0.46	120	185	3200	
Ð	5IK60A-DW3E	60		50			220	2650	3.0
			Single-Phase 230	60	0.45	140	185	3200	
				50	0.47	270	220	2650	
_	5IK60A-TW2		Three-Phase 200	60	0.40	230	185	3200	
[P]		IK60A-TW2	60						

<sup>60</sup> **P**: Contains a built-in thermal protector. If a motor overheats for any reason, the thermal protector is opened and the motor stops. When the motor temperature drops, the thermal protector closes and the motor restarts. Be sure to turn the motor off before inspecting.

0.44

230

185

3200

Three-Phase 230

●90 W, 150 W (RoHS) C €

	,								_
	Model	Output Power	Voltage	Frequency	Current	Starting Torque	Rated Torque	Rated Speed	Capacitor
	Round Shaft Type	W	VAC	Hz	Α	mN·m	mN·m	r/min	μF
	FILCOA BLACAL	00	0'I- Pl 400	50	1.57	240	330	2650	28
TP)	5IK90A-BW2J	90	Single-Phase 100	60	1.85		280	3200	
ÎP)	5IK90A-BW2U	90	Single-Phase 110	60	1.61	240	280	3200	25
<u> </u>	JIK70A-BW20	30	Single-Phase 115	00	1.57	240	200		23
ĪΡ	5IK90A-DW2J	90	Single-Phase 200	50	0.76	240	330	2650	7.0
<u> </u>	JIK70A-DW2J	30	Olligie-i flase 200	60	0.90	240	280	3200	7.0
			Single-Phase 220	50	0.70		330 280	2650	
ÎP)	5IK90A-DW3E	90	Olligie-i flase 220	60	0.84	240		3200	6.0
	SIK9UA-DW3E	90	Single-Phase 230	50	0.69	] 240	330	2650	
				60	0.84		280	3200	
	5IK90A-TW2	90	Three-Phase 200	50	0.63	500	340	2600	_
ſΡ			0	60	0.55	400	285	3100	
			Three-Phase 220	60	0.57	400	285	3200	
			Three-Phase 230	60	0.59	400	285	3200	
ĨP)	5IK150A-BW2J	150	Single-Phase 100	50	2.39	380	560	2650	40
	SIK I SUA-BW ZJ		Sillyie-Filase 100	60	2.49	300	460	3200	
ΓP)	5IK150A-BW2U	150	Single-Phase 110 60 2.1	2.12	380	460	3200	30	
<u> </u>	JIK I JUA-BW 20	130	Single-Phase 115	00	2.09	300	400	3200	30
ſΡ	5IK150A-DW2J	150	Single-Phase 200	50	1.16	380	560	2650	10
	JIK I JOA-DW2J	130	Olligio i riaso 200	60	1.26	300	460	3200	
		140	Single-Phase 220	50	0.98		510	2650	8.0
ÎP)	5IK150A-DW3E	1	Olligic i flasc 220	60	1.07	380	420	3200	
<u></u>	SIKTOOA DITOL	150	Single-Phase 230	50	1.04	] 500	560	2650	
		100	Omgio i nado 200	60	1.13		460	3200	
			Three-Phase 200	50	1.11	680	550	2650	
ÎP)	5IK150A-TW2	150		60	0.93	570	460	3100	_
<u> </u>	5IK150A-TW2T	130	Three-Phase 220	60	0.97	570	460	3150	
			Three-Phase 230	60	1.01	570	460	3200	

<sup>(</sup>IP): Contains a built-in thermal protector. If a motor overheats for any reason, the thermal protector is opened and the motor stops.

When the motor temperature drops, the thermal protector closes and the motor restarts. Be sure to turn the motor off before inspecting.

### **■**Product Line

### ● Motor (RoHS)

Output Power	Power Supply Voltage	Model
	Single-Phase 100 VAC	4IK40A-BW2J
40 W	Single-Phase 110/115 VAC	4IK40A-BW2U
40 W	Single-Phase 200 VAC	4IK40A-DW2J
	Single-Phase 220/230 VAC	4IK40A-DW3E
	Single-Phase 100 VAC	4IK60A-BW2J
	Single-Phase 110/115 VAC	4IK60A-BW2U
	Single-Phase 200 VAC	4IK60A-DW2J
	Single-Phase 220/230 VAC	4IK60A-DW3E
60 W	Single-Phase 100 VAC	5IK60A-BW2J
	Single-Phase 110/115 VAC	5IK60A-BW2U
	Single-Phase 200 VAC	5IK60A-DW2J
	Single-Phase 220/230 VAC	5IK60A-DW3E
	Three-Phase 200/220/230 VAC	5IK60A-TW2

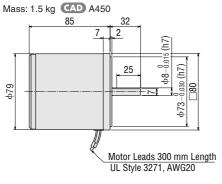
Output Power	Power Supply Voltage	Model
	Single-Phase 100 VAC	5IK90A-BW2J
	Single-Phase 110/115 VAC	5IK90A-BW2U
90 W	Single-Phase 200 VAC	5IK90A-DW2J
	Single-Phase 220/230 VAC	5IK90A-DW3E
	Three-Phase 200/220/230 VAC	5IK90A-TW2
	Single-Phase 100 VAC	5IK150A-BW2J
	Single-Phase 110/115 VAC	5IK150A-BW2U
150 W	Single-Phase 200 VAC	5IK150A-DW2J
130 W	Single-Phase 220/230 VAC	5IK150A-DW3E
	Three-Phase 200/220/230 VAC	5IK150A-TW2
	Three-Phase 200/220/230 VAC	5IK150A-TW2T

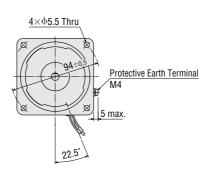
### ■Dimensions (Unit = mm)

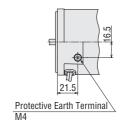
### **40 W**

♦Motor

### 4IK40A-BW2J, 4IK40A-BW2U, 4IK40A-DW2J, 4IK40A-DW3E





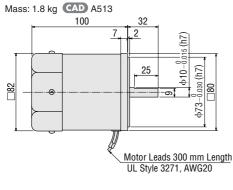


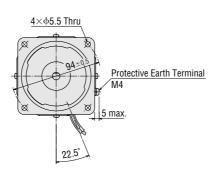
Detail Drawing of Protective Earth Terminal

### ●60 W

♦Motor

### 4IK60A-BW2J, 4IK60A-BW2U, 4IK60A-DW2J, 4IK60A-DW3E



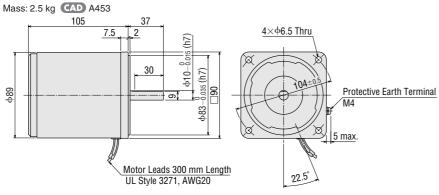




Detail Drawing of Protective Earth Terminal

### ♦Motor

### 5IK60A-BW2J, 5IK60A-BW2U, 5IK60A-DW2J, 5IK60A-DW3E, 5IK60A-TW2





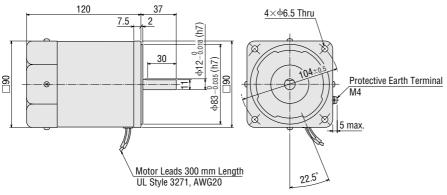
Detail Drawing of Protective Earth Terminal

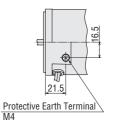
### 90 W

♦Motor

### 5IK90A-BW2J, 5IK90A-BW2U, 5IK90A-DW2J, 5IK90A-DW3E, 5IK90A-TW2

Mass: 2.7 kg CAD A456



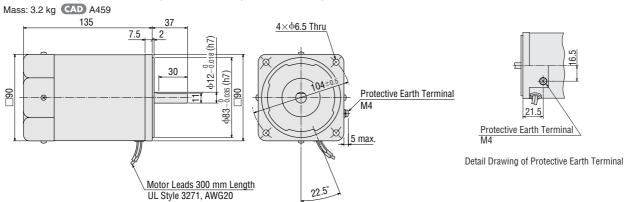


Detail Drawing of Protective Earth Terminal

### ●150 W

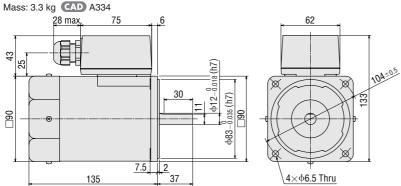
### ♦Motor

### ŠIK150A-BW2J, 5IK150A-BW2U, 5IK150A-DW2J, 5IK150A-DW3E, 5IK150A-TW2



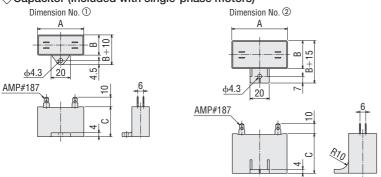
## ♦Motor

### 5IK150A-TW2T



 $\bullet$  Use cable with a diameter of  $\varphi 6 \sim \varphi 12$  mm.

### $\Diamond$ Capacitor (Included with single-phase motors)

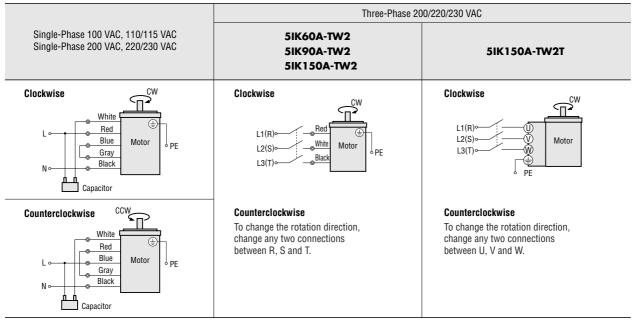


### 

	isions (mm)						
Model	Capacitor Model	Α	В	С	Mass (g)	Dimension No.	Capacitor Cap
4IK40A-BW2J	CH90CFAUL2	48	22.5	31.5	45	1	
4IK40A-BW2U	CH75CFAUL2	48	21	31	45	1	
4IK40A-DW2J	CH23BFAUL	48	21	31	40	1	
4IK40A-DW3E	CH18BFAUL	38	21	31	35	1	
4IK60A-BW2J	CH140CFAUL2	58	22	35	61	1	
4IK60A-BW2U	CH100CFAUL2	58	21	31	50	1	
4IK60A-DW2J	CH30BFAUL	58	21	31	50	1)	
4IK60A-DW3E	CH25BFAUL	48	21	31	45	1	
5IK60A-BW2J	CH160CFAUL2	58	23.5	37	75	2	
5IK60A-BW2U	CH140CFAUL2	58	22	35	61	1	Included
5IK60A-DW2J	CH40BFAUL	58	23.5	37	70	2	iliciuaea
5IK60A-DW3E	CH30BFAUL	58	21	31	50	1)	
5IK90A-BW2J	CH280CFAUL2	58	35	50	140	2	
5IK90A-BW2U	CH250CFAUL2	58	35	50	140	2	
5IK90A-DW2J	CH70BFAUL	58	35	50	130	2	
5IK90A-DW3E	CH60BFAUL	58	29	41	85	2	
5IK150A-BW2J	CH400CFAUL2	58	41	58	180	2	
5IK150A-BW2U	CH300CFAUL2	58	35	50	140	2	
5IK150A-DW2J	CH100BFAUL	58	35	50	132	2	
5IK150A-DW3E	CH80BFAUL	58	35	50	130	2	

### **■**Connection Diagrams

•The direction of motor rotation is as viewed from the shaft end of the motor. CW represents the clockwise direction, while CCW represents the counterclockwise direction.



PE: Protective Earth

### Note:

Change the direction of single-phase motor rotation only after bringing the motor to a stop.

If an attempt is made to change the direction of rotation while the motor is rotating, motor may ignore reversing command or change its direction of rotation after some delay.

# RoHS RoHS-Compliant Reversible Motors





### Features

### Optimal for Bi-Directional Operation

These are 30 minutes rated motors that can change directions instantaneously. They are designed for applications where reversal of direction is frequently required.

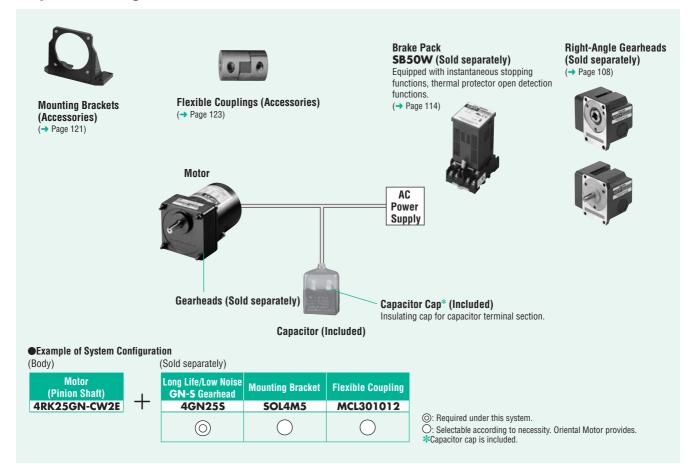
\*30 minutes rating: The motors may be operated continuously for 30 minutes, but depending on operating conditions (intermittent operation, etc), they can be operated for more than 30 minutes

### Safety Standards and CE Marking

Standards	Certification Body	Standards File No.	CE Marking	
UL 1004 UL 2111	UL	E64199 (1 W∼6 W Type)		
CSA C22.2 No.100 CSA C22.2 No.77	UL	E64197 (15 W~90 W Type)		
EN 60950-1 EN 60034-1 EN 60034-5 IEC 60664-1		Conform to EN/IEC Standards		
GB 12350	CQC	2005010401150787 (Single-Phase 1 W Type) CQC 2003010401091525 (Single-Phase 6 W Type) 2003010401091522 (Single-Phase 15 W~90 W Type)		

<sup>•</sup> When the motor is approved under various safety standards, the model name on the nameplate is the approved model name.

### System Configuration



• The system configuration shown above is an example. Other configurations are available.

### Product Number Code

### Motor

# 5 R K 40 GN - CW 2 T E

① M	lotor Frame Size	<b>0</b> : 42 mm <b>2</b> : 60 mm <b>3</b> : 70 mm <b>4</b> : 80 mm <b>5</b> : 90 mm
② M	lotor Type	R: Reversible Motor
3 Se	eries	K: K Series
4 0	utput Power (W)	(Example) <b>40</b> : 40 W
⑤ M	lotor Shaft Type	GN: GN Type Pinion Shaft GE: GE Type Pinion Shaft A: Round Shaft
6 Po	ower Supply Voltage	AW: Single-Phase 100 VAC, 110/115 VAC CW: Single-Phase 200 VAC, 220/230 VAC
7 2	, 3: RoHS-Compliant	
8 T,	, <b>B</b> : Terminal Box Type	
9 In	cluded Capacitor	J: For Single-Phase 100 VAC, 200 VAC U: For Single-Phase 110/115 VAC E: For Single-Phase 220/230 VAC

<sup>•</sup> The **J**, **U** and **E** at the end of the model name indicate that the unit includes a capacitor. These letters are not listed on the motor nameplate. When the motor is approved under various safety standards, the model name on the nameplate is the approved model name.

(Example) Model: 5RK40GN-CW2E → Motor nameplate and product approved under various safety standards: 5RK40GN-CW2

### Gearhead

# 5 GN 50 S

·		$\odot$
1	Gearhead Frame Size	<b>0</b> : 42 mm <b>2</b> : 60 mm <b>3</b> : 70 mm <b>4</b> : 80 mm <b>5</b> : 90 mm
2	Type of Pinion	GN: GN Type Pinion GE: GE Type Pinion
3	Gear Ratio	(Example) 50: Gear Ratio of 1:50 10X denotes the decimal gearhead of gear ratio 1:10
•	<b>GN</b> Type Pinion	S: Long Life/Low Noise GN-S Gearhead, RoHS-Compliant RH: Right-Angle/Hollow Shaft Gearhead, RoHS-Compliant RA: Right-Angle/Solid Shaft Gearhead, RoHS-Compliant
4	<b>GE</b> Type Pinion	S: Long Life GE-S Gearhead, RoHS-Compliant RH: Right-Angle/Hollow Shaft Gearhead, RoHS-Compliant RA: Right-Angle/Solid Shaft Gearhead, RoHS-Compliant

<sup>\*</sup> GN-K gearhead of frame size 42 mm complies to RoHS directive.

# ■General Specifications of Motors

### ●1 W Type

Item	Specifications
Insulation Resistance	$100~M\Omega$ or more when 500 VDC megger is applied between the windings and the frame after rated motor operation under normal ambient temperature and humidity.
Dielectric Strength	Sufficient to withstand 1.5 kV at 50 Hz or 60 Hz applied between the windings and the frame for 1 minute after rated motor operation under normal ambient temperature and humidity.
Temperature Rise	Temperature rise of windings are 75°C or less measured by the resistance change method after rated motor operation under normal ambient temperature and humidity, with connecting a gearhead or equivalent heat radiation plate*.
Insulation Class	UL/CSA standards: Class A (105°C), EN standards: Class E (120°C)
Overheat Protection	Impedance protected
Ambient Temperature	-10°C~+40°C (nonfreezing)
Ambient Humidity	85% or less (noncondensing)
Degree of Protection	IP20

### ●6 W~90 W Type

Item	Specifications					
Insulation Resistance	$100~M\Omega$ or more when 500 VDC megger is applied between the windings and the frame after rated motor operation under normal ambient temperature and humidity.					
Dielectric Strength	Sufficient to withstand 1.5 kV at 50 Hz or 60 Hz applied between the windings and the frame for 1 minute after rated motor operation under normal ambient temperature and humidity.					
Temperature Rise	Temperature rise of windings are 80°C or less measured by the resistance change method after rated motor operation under normal ambient temperature and humidity, with connecting a gearhead or equivalent heat radiation plate*.  However, a heat radiation plate that is 200×200 mm with a thickness of 5 mm is necessary even when the gearhead is connected for the 90 W type.					
Insulation Class	Class B (130°C)					
Overheat Protection	6 W type has impedance protection. All others have built-in thermal protector (automatic return type) Operating temperature; open: $130^{\circ}\text{C} \pm 5^{\circ}\text{C}$ , close: $82^{\circ}\text{C} \pm 15^{\circ}\text{C}$					
Ambient Temperature	Single-phase 100 VAC, Single-phase 200 VAC: $-10^{\circ}\text{C} \sim +50^{\circ}\text{C}$ (nonfreezing) Other voltage: $-10^{\circ}\text{C} \sim +40^{\circ}\text{C}$ (nonfreezing)					
Ambient Humidity	85% or less (noncondensing)					
Degree of Protection	Lead Wire Type: IP20 Terminal Box Type: 6 W Type IP65 (excluding the installation surface of the round shaft type) 25 W, 40 W, 60 W, 90 W Type IP40					

### \* Heat radiation plate (Material: Aluminum)

* Heat radiation plate (Material. Aluminum)		
Motor Type	Size (mm)	Thickness (mm)
1 W Type	80×80	
6 W Type	115×115	
15 W Type	125×125	5
25 W Type	135×135	3
40 W Type	165×165	
60 W Type	200×200	
90 W Type	200×200	10

RoHS

### **Reversible Motors**

1 W

Frame Size: **□42** mm



(Gearhead sold separately)

### ■ Specifications – 30 Minutes Rating (RoHS)

Mode Lead Wire		Output Power	Voltage	Frequency	Current	Starting Torque	Rated Torque	Rated Speed	Capacitor
Pinion Shaft Type	Round Shaft Type	W	VAC	Hz	Α	mN·m	mN·m	r/min	μF
ZP) ORK1GN-AW2J	ORK1A-AW2J	1	Single-Phase 100	50	0.120	8	10	1000	1.8
ZP UKKIGN-AWZJ	UKK I A-AVV 2J	'	Sillyle-Filase 100	60	0.125	0	8	1200	1.0
(ZP) ORK1GN-AW3U	ODK 1 V - V/V/311	1	Single-Phase 110	60	0.090	8	8	1200	1.2
ZP UKKI GIV-AVV3U	OKK IA-AW30	'	Single-Phase 115	00	0.095	0	0	1200	1.2
(ZP) ORK1GN-CW2J	ORK1A-CW2J	1	Single-Phase 200	50	0.066	8	10	1000	0.45
ZP ORK1GN-CW2J ORK1A-CW2J		'	Sillyle-Filase 200	60	0.069	0	8	1200	0.45

<sup>•</sup> Values shown for rated torque and starting torque are measured for operation without the friction brake installed.

### Product Line

### ● Motor ® HS

Type	Mo	del
туре	Pinion Shaft Type	Round Shaft Type
	ORK1GN-AW2J	ORK1A-AW2J
Lead Wire	ORK1GN-AW3U	ORK1A-AW3U
	ORK1GN-CW2J	ORK1A-CW2J

### Gearhead (Sold Separately) (RoHS)

Туре	Gearhead Model	Gear Ratio
Parallel Shaft	0GN□K	3, 3.6, 5, 6, 7.5, 9, 12.5, 15, 18, 25, 30, 36, 50, 60, 75, 90, 100, 120, 150, 180

<sup>●</sup> Enter the gear ratio in the box (□) within the model name.

### ■Gearmotor – Torque Table

- •Gearheads are sold separately. Decimal gearheads are not available.
- $\bullet Enter$  the gear ratio in the box (  $\Box )$  within the model name.
- •A colored background indicates gear shaft rotation in the same direction as the motor shaft, while the others rotate in the opposite direction.
- The speed is calculated by dividing the motor's synchronous speed (50 Hz: 1500 r/min, 60 Hz: 1800 r/min) by the gear ratio. The actual speed is 2 33% less than the displayed value, depending on the size of the load.

<>50 Hz																				Unit	t = N·m
Model	Speed r/min	500	416	300	250	200	166	120	100	83	60	50	41	30	25	20	16	15	12.5	10	8.3
Motor/ Gearhead	Gear Ratio	3	3.6	5	6	7.5	9	12.5	15	18	25	30	36	50	60	75	90	100	120	150	180
ORK1GN-AW2J ORK1GN-CW2J	/ OGN□K	0.024	0.029	0.041	0.049	0.061	0.073	0.091	0.11	0.13	0.17	0.2	0.24	0.33	0.4	0.44	0.53	0.59	0.71	0.89	1
^ 60 H=																				11-2	- N

<>60 Hz																				Uni	it = N·m
Model	Speed r/min	600	500	360	300	240	200	144	120	100	72	60	50	36	30	24	20	18	15	12	10
Motor/ Gearhead	Gear Ratio	3	3.6	5	6	7.5	9	12.5	15	18	25	30	36	50	60	75	90	100	120	150	180
ORK1GN-AW2J ORK1GN-AW3U ORK1GN-CW2J	<b>OGN</b> □K	0.019	0.023	0.032	0.039	0.049	0.058	0.073	0.088	0.11	0.13	0.16	0.19	0.26	0.32	0.35	0.42	0.47	0.57	0.71	0.85

<sup>•</sup> The J and U at the end of the model name indicate that the unit includes a capacitor. These letters are not listed on the motor nameplate.

When the motor is approved under various safety standards, the model name on the nameplate is the approved model name.

**ZP**: Impedance protected

### Permissible Overhung Load and Permissible Thrust Load

Motor (Round shaft type) → Page 107 Gearhead → Page 107

### Permissible Load Inertia J for Gearhead

→ Page 107

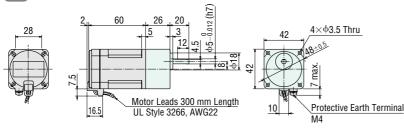
### Dimensions (Unit = mm)

Mounting screws are included with gearheads.

### 

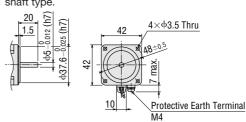
Mass: Motor 0.3 kg Gearhead 0.2 kg

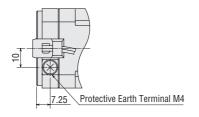
**CAD** A441



### $\diamondsuit$ Shaft Section of Round Shaft Type

The mass and motor's dimensions (excluding the shaft section) are the same as those of the pinion shaft type.





Detail Drawing of Protective Earth Terminal

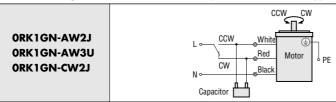
### 

Mo	del	Capacitor	Α	D	0	Mass	Capacitor
Pinion Shaft Type	Round Shaft Type	Model	А	D	U	(g)	Cap
ORK1GN-AW2J	ORK1A-AW2J	CH18FAUL	31	14.5	23.5	18	
ORK1GN-AW3U	ORK1A-AW3U	CH12FAUL	31	14.5	23.5	18	Included
ORK1GN-CW2J	ORK1A-CW2J	CH045BFAUL	31	17	27	24	

# Capacitor (Included with the motors) A A A AMP#187 A A AMP#187

### ■Connection Diagrams

- The direction of motor rotation is as viewed from the shaft end of the motor. CW represents the clockwise direction, while CCW represents the counterclockwise direction.
- Connection diagrams are also valid for the equivalent round shaft type.



### Clockwise:

To rotate the motor in a clockwise (CW) direction, turn the switch to CW.

### Counterclockwise:

To rotate the motor in a counterclockwise (CCW) direction, turn the switch to CCW.

PE: Protective Earth

Note:

Connect a CR circuit to the forward/reverse select switch to protect the contact.

**EPCR1201-2** is available as an optional surge suppressor. → Page 123

RoHS

### **Reversible Motors**

**6W** 

Frame Size: **□60** mm





(Gearhead sold separately)

# ■Specifications – 30 Minutes Rating (ROHS)

<b>, 511</b> us	(I)	(	$\epsilon$

				_						
	Mode Upper Model Name: F Lower Model Name ():	inion Shaft Type	Output Power	Voltage	Frequency	Current	Starting Torque	Rated Torque	Rated Speed	Capacitor
	Lead Wire Type Dimension ①	Terminal Box Type Dimension ②	W	VAC	Hz	А	mN·m	mN·m	r/min	μF
(ZP)	2RK6GN-AW2J	2RK6GN-AW2BJ	6	Cinala Dhana 100	50	0.257	50	49	1150	4.5
ZP	(2RK6A-AW2J)	(2RK6A-AW2BJ)	ь	Single-Phase 100	60	0.307	45	41	1400	4.5
(ZP)	2RK6GN-AW2U	2RK6GN-AW2BU	6	Single-Phase 110	60	0.251	45	41	1450	3.5
ZP	(2RK6A-AW2U)	(2RK6A-AW2BU)	О	Single-Phase 115	00	0.256	45	41	1450	3.5
ZP)	2RK6GN-CW2J	2RK6GN-CW2BJ	6	Single-Phase 200	50	0.120	50	49	1150	1.0
ZP	(2RK6A-CW2J)	(2RK6A-CW2BJ)	O	Siligie-Pliase 200	60	0.138	45	41	1400	1.0
				Single-Phase 220	50	0.113	45	49	1150	
(ZP)	2RK6GN-CW2E	2RK6GN-CW2BE	6	Sillyle-rilase 220	60	0.117	45	41	1450	0.8
ZP	(2RK6A-CW2E)	(2RK6A-CW2BE)	6	Single-Phase 230	50	0.117	50	49	1200	0.0
				Sillyic-Filase 230	60	0.120	45	41	1450	

 $<sup>\</sup>blacksquare \ \, \text{Values shown for rated torque and starting torque are measured for operation without the friction brake installed}.$ 

**ZP**: Impedance protected

### Product Line

### ● Motor (RoHS)

Tuno	Mo	odel
Type	Pinion Shaft Type	Round Shaft Type
	2RK6GN-AW2J	2RK6A-AW2J
Lead Wire	2RK6GN-AW2U	2RK6A-AW2U
Leau wire	2RK6GN-CW2J	2RK6A-CW2J
	2RK6GN-CW2E	2RK6A-CW2E
	2RK6GN-AW2BJ	2RK6A-AW2BJ
Farmain al Dan	2RK6GN-AW2BU	2RK6A-AW2BU
Terminal Box	2RK6GN-CW2BJ	2RK6A-CW2BJ
	2RK6GN-CW2BE	2RK6A-CW2BE

### Gearhead (Sold Separately) RoHS

Туре	Gearhead Model	Gear Ratio
Long Life/Low Noise/ Parallel Shaft	2GN□5	3, 3.6, 5, 6, 7.5, 9, 12.5, 15, 18, 25, 30, 36, 50, 60, 75, 90, 100, 120, 150, 180
	2GN10XS (Decim	al gearhead)

■ Enter the gear ratio in the box (□) within the model name.

The J, U and E at the end of the model name indicate that the unit includes a capacitor. These letters are not listed on the motor nameplate.

When the motor is approved under various safety standards, the model name on the nameplate is the approved model name.

### Gearmotor – Torque Table

- •Gearheads and decimal gearheads are sold separately.
- ●Enter the code that represents the terminal box type "B" in the box (□) within the model name.
- ■Enter the gear ratio in the box (□) within the model name.
- •A colored background indicates gear shaft rotation in the same direction as the motor shaft, while the others rotate in the opposite direction.
- The speed is calculated by dividing the motor's synchronous speed (50 Hz: 1500 r/min, 60 Hz: 1800 r/min) by the gear ratio.
- The actual speed is 2 20% less than the displayed value, depending on the size of the load.
- •To reduce the speed beyond the gear ratio in the table, attach a decimal gearhead (gear ratio: 10) between the gearhead and the motor. In that case, the permissible torque is 3 N·m.

♦ 50 Hz																				Uni	it = N·m
Model	Speed r/min	500	416	300	250	200	166	120	100	83	60	50	41	30	25	20	16	15	12.5	10	8.3
Motor/ Gearhead	Gear Ratio	3	3.6	5	6	7.5	9	12.5	15	18	25	30	36	50	60	75	90	100	120	150	180
2RK6GN-AW2_J 2RK6GN-CW2_J 2RK6GN-CW2_E	<b>2GN</b> □S	0.12	0.14	0.20	0.24	0.30	0.36	0.50	0.60	0.71	0.89	1.1	1.3	1.6	1.9	2.4	2.9	3	3	3	3

<b>♦60 Hz</b>																				Uni	it = N•m
Model	Speed r/min	600	500	360	300	240	200	144	120	100	72	60	50	36	30	24	20	18	15	12	10
Motor/ Gearhead	Gear Ratio	3	3.6	5	6	7.5	9	12.5	15	18	25	30	36	50	60	75	90	100	120	150	180
2RK6GN-AW2JJ 2RK6GN-AW2JU 2RK6GN-CW2J 2RK6GN-CW2JE	2GN□S	0.10	0.12	0.17	0.20	0.25	0.30	0.42	0.50	0.60	0.75	0.90	1.1	1.4	1.6	2.0	2.4	2.7	3	3	3

### Permissible Overhung Load and Permissible Thrust Load

Motor (Round shaft type) → Page 107 Gearhead → Page 107

### Permissible Load Inertia J for Gearhead

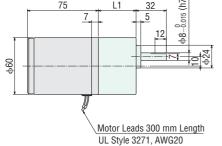
→ Page 107

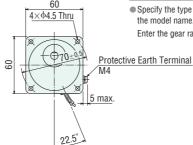
### **Dimensions** (Unit = mm)

Mounting screws are included with gearheads.

# ♦ Lead Wire Type ① Mass: Motor 0.7 kg

Gearhead 0.4 kg





Motor Model	Gearhead Model	Gear Ratio	L1	CAD
2RK6GN-AW2	2GN□S	3~18	30	A443A
2RK6GN-CW2   ■	ZGN_3	<b>25~180</b>	40	A443B

lacksquare Specify the type of the capacitor to be included by entering  ${f J}$ ,  ${f U}$  or  ${f E}$  in the box ( ${lacksquare}$ ) within the model name.

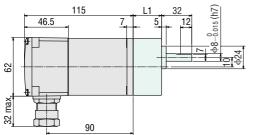
Enter the gear ratio in the box  $(\Box)$  within the model name.

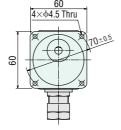


Detail Drawing of Protective Earth Terminal

### 

Mass: Motor 0.9 kg Gearhead 0.4 kg





Motor Model	Gearhead Model	Gear Ratio	L1	CAD
2RK6GN-AW2B	2GN□S	3~18	30	A445A
2RK6GN-CW2B	ZGIN_3	25~180	40	A445B

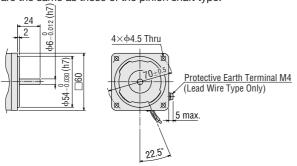
Specify the type of the capacitor to be included by entering J, U or E in the box
 within the model name.

Enter the gear ratio in the box  $(\Box)$  within the model name.

 $\bullet$  Use cable with a diameter of  $\varphi 8 \sim \varphi 12$  mm.

### ♦ Shaft Section of Round Shaft Type

The mass and motor's dimensions (excluding the shaft section) are the same as those of the pinion shaft type.

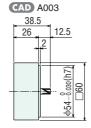


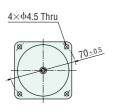
### 

Can be connected to  $\ensuremath{\mathbf{GN}}$  pinion shaft type.

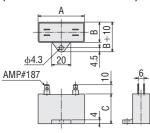
### 2GN10XS

Mass: 0.2 kg





### 



### 

Upper Model Name	del e: Pinion Shaft Type ( ): Round Shaft Type	Capacitor Model	Α	В	С	Mass (g)	Capacitor Cap
Lead Wire Type	Terminal Box Type						
2RK6GN-AW2J (2RK6A-AW2J)	2RK6GN-AW2BJ (2RK6A-AW2BJ)	CH45FAUL2	37	18	27	30	
2RK6GN-AW2U (2RK6A-AW2U)	2RK6GN-AW2BU (2RK6A-AW2BU)	CH35FAUL2	31	17	27	25	Included
2RK6GN-CW2J (2RK6A-CW2J)	2RK6GN-CW2BJ (2RK6A-CW2BJ)	CH10BFAUL	37	18	27	30	iliciadea
2RK6GN-CW2E (2RK6A-CW2E)	CH08BFAUL	31	17	27	20		

# ■Connection Diagrams

- The direction of motor rotation is as viewed from the shaft end of the motor. CW represents the clockwise direction, while CCW represents the counterclockwise direction.
- Connection diagrams are also valid for the equivalent round shaft type.
- ●Specify the type of the capacitor to be included by entering **J**, **U** or **E** in the box (□) within the model name.

Lead Wire Type	Terminal Box Type
2RK6GN-AW2□ 2RK6GN-CW2□	2RK6GN-AW2B□ 2RK6GN-CW2B□
CCW CW White Motor PE	CCW CW Motor Capacitor PE
Clockwise To rotate the motor in a clockwise (CW) direction, turn the switch to CW. Counterclockwise To rotate the motor in a counterclockwise (CCW) direction, turn the switch to CCW.	Clockwise To rotate the motor in a clockwise (CW) direction, turn the switch to CW.  Counterclockwise To rotate the motor in a counterclockwise (CCW) direction, turn the switch to CCW.

PE: Protective Earth

Note:

Connect a CR circuit to the forward/reverse select switch to protect the contact.

RoHS)
Reversible Motors
15 W

Frame Size: **□70** mm



# Specifications – 30 Minutes Rating (RoHS)



	Model Lead Wire Ty	ре	Output Power	Voltage	Frequency	Current	Starting Torque	Rated Torque	Rated Speed	Capacitor
	Pinion Shaft Type	Round Shaft Type	W	VAC	Hz	Α	mN·m	mN∙m	r/min	μF
(TP)	3RK15GN-AW2J	3RK15A-AW2J	15	Single-Phase 100	50	0.41	100	125	1200	7.5
<u> </u>	3KK13GH-AW23	3KK13A-AVV23	13	15 Single-Phase 100 F		0.50	100	105	1450	7.5
(TP)	3RK15GN-AW2U	3RK15A-AW2U	15	Single-Phase 110	60	0.41	100	105	1450	6.0
(IP)	3KK 13GN-AW20	JKK I JA-AWZU	15	Single-Phase 115	00	0.41	100	103	1430	0.0
(TP)	3RK15GN-CW2J	3RK15A-CW2J	15	Single-Phase 200	50	0.21	100	125	1200	1.8
(IP)	3KK 13GIN-CW2J	SKK I SA-CW 23	15	Siligie-Filase 200	60	0.24	100	105	1450	1.0
				Single-Phase 220	50	0.20		125	1200	
(TP)	3RK15GN-CW2E 3RK15A-CW2E		15	Siligie-Filase 220	60	0.21	100	105	1450	1.5
(IP)	SKK I SGIN-CWZE	JRR I JA-CWZE	10	Single-Phase 230	50	0.20	100	125	1200	1.0
				Siligie-Filase 230	60	0.21		105	1450	

<sup>•</sup> Values shown for rated torque and starting torque are measured for operation without the friction brake installed.

When the motor is approved under various safety standards, the model name on the nameplate is the approved model name.

When the motor temperature drops, the thermal protector closes and the motor restarts. Be sure to turn the motor off before inspecting.

### Product Line

### ● Motor (RoHS)

Mo	del
Pinion Shaft Type	Round Shaft Type
3RK15GN-AW2J	3RK15A-AW2J
3RK15GN-AW2U	3RK15A-AW2U
3RK15GN-CW2J	3RK15A-CW2J
3RK15GN-CW2E	3RK15A-CW2E
	Pinion Shaft Type  3RK15GN-AW2J  3RK15GN-AW2U  3RK15GN-CW2J

### Gearhead (Sold Separately) (RoHS)

Type	Gearhead Model	Gear Ratio								
Long Life/Low Noise/ Parallel Shaft	3GN□S	3, 3.6, 5, 6, 7.5, 9, 12.5, 15, 18, 25, 30, 36, 50, 60, 75, 90, 100, 120, 150, 180								
3GN10XS (Decimal gearhead)										

■ Enter the gear ratio in the box (□) within the model name.

<sup>●</sup> The J, U and E at the end of the model name indicate that the unit includes a capacitor. These letters are not listed on the motor nameplate.

<sup>(</sup>P): Contains a built-in thermal protector. If a motor overheats for any reason, the thermal protector is opened and the motor stops.

### ■Gearmotor – Torque Table

- •Gearheads and decimal gearheads are sold separately.
- ●Enter the gear ratio in the box (□) within the model name.
- •A colored background indicates gear shaft rotation in the same direction as the motor shaft, while the others rotate in the opposite direction.
- The speed is calculated by dividing the motor's synchronous speed (50 Hz: 1500 r/min, 60 Hz: 1800 r/min) by the gear ratio. The actual speed is 2 20% less than the displayed value, depending on the size of the load.
- To reduce the speed beyond the gear ratio in the table, attach a decimal gearhead (gear ratio: 10) between the gearhead and the motor. In that case, the permissible torque is 5 N·m.

<>50 HZ																				Uni	t = N•m
Model	Speed r/min	500	416	300	250	200	166	120	100	83	60	50	41	30	25	20	16	15	12.5	10	8.3
Motor/ Gearhead	Gear Ratio	3	3.6	5	6	7.5	9	12.5	15	18	25	30	36	50	60	75	90	100	120	150	180
3RK15GN-AW2J 3RK15GN-CW2J 3RK15GN-CW2E	/ 3GN□S	0.30	0.36	0.51	0.61	0.76	0.91	1.3	1.5	1.8	2.3	2.7	3.3	4.1	5	5	5	5	5	5	5

♦60 Hz																				Uni	t = N·m
Model	Speed r/min	600	500	360	300	240	200	144	120	100	72	60	50	36	30	24	20	18	15	12	10
Motor/ Gearhead	Gear Ratio	3	3.6	5	6	7.5	9	12.5	15	18	25	30	36	50	60	75	90	100	120	150	180
3RK15GN-AW2J 3RK15GN-AW2U 3RK15GN-CW2J 3RK15GN-CW2E	/ 3GN□S	0.26	0.31	0.43	0.51	0.64	0.77	1.1	1.3	1.5	1.9	2.3	2.8	3.5	4.2	5	5	5	5	5	5

### Permissible Overhung Load and Permissible Thrust Load

Motor (Round shaft type) → Page 107 Gearhead → Page 107

### Permissible Load Inertia J for Gearhead

→ Page 107

### **Dimensions** (Unit = mm)

Mounting screws are included with gearheads.

### 

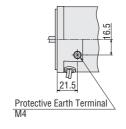
Mass: Motor 1.1 kg Gearhead 0.55 kg

	80	L1	32 (24) 5.005	70	the model name.
69ф	7 T	otor Leads	300 mm Length 71, AWG20	4×Φ5.5 Thru	Enter the gear ratio  Protective Earth Terminal M4  max.

	Motor Model	Gearhead Model	Gear Ratio	L1	CAD
3	RK15GN-AW2	3GN□S	3~18	32	A447A
3	RK15GN-CW2	3GI4□3	<b>25~180</b>	42	A447B

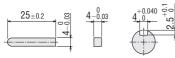
Specify the type of the capacitor to be included by entering J, U or E in the box ( ) within the model name.

Enter the gear ratio in the box ( $\square$ ) within the model name.



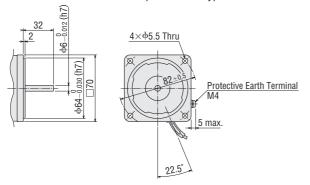
Detail Drawing of Protective Earth Terminal

### ⟨Key and Key Slot (The key is included with the gearhead)



### ♦ Shaft Section of Round Shaft Type

The mass and motor's dimensions (excluding the shaft section) are the same as those of the pinion shaft type.



### 

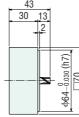
Can be connected to **GN** pinion shaft type.

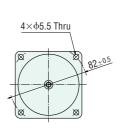
### **3GN10XS**

Mass: 0.3 kg

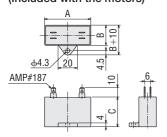
CAD A009

43





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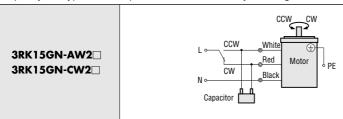


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• •	` '						
Mo	odel	Capacitor	Α	В	C	Mass	Capacitor
Pinion Shaft Type	Round Shaft Type	Model	A	Б	U	(g)	Сар
3RK15GN-AW2J	3RK15A-AW2J	CH75CFAUL2	48	21	31	45	
3RK15GN-AW2U	3RK15A-AW2U	CH60CFAUL2	38	21	31	40	Included
3RK15GN-CW2J	3RK15A-CW2J	CH18BFAUL	38	21	31	35	included
3RK15GN-CW2E	3RK15A-CW2E	CH15BFAUL	38	21	31	35	

### **■**Connection Diagrams

- The direction of motor rotation is as viewed from the shaft end of the motor. CW represents the clockwise direction, while CCW represents the counterclockwise direction.
- Connection diagrams are also valid for the equivalent round shaft type.
- Specify the type of the capacitor to be included by entering J, U or E in the box (□) within the model name.



### Clockwise:

To rotate the motor in a clockwise (CW) direction, turn the switch to CW.

### Counterclockwise:

To rotate the motor in a counterclockwise (CCW) direction, turn the switch to CCW.

PE: Protective Earth

Note:

 $\label{lem:connect} \textbf{Connect a CR circuit to the forward/reverse select switch to protect the contact.}$ 

**EPCR1201-2** is available as an optional surge suppressor. → Page 123

(RoHS)

### **Reversible Motors**

# 25 W

Frame Size: 

■80 mm





(Gearhead sold separately)

Right-angle gearheads (hollow shaft or solid shaft) can be combined.

Right-Angle Gearheads → Page 108







# **AL**us @ ( **E**

■ Specifications – 30 Minutes Rating (RoHS)
---

•			<u> </u>											
Upper Model Name: Pi	Model pper Model Name: Pinion Shaft Type wer Model Name (): Round Shaft Type			Frequency	Current	Starting Torque	Rated Torque	Rated Speed	Capacitor					
Lead Wire Type Dimension (1)	Terminal Box Type Dimension ②	W	VAC	Hz	А	mN∙m	mN∙m	r/min	μF					
4RK25GN-AW2J	4RK25GN-AW2TJ	25	Cinala Dhana 100	50	0.59	160	205	1200	10					
(4RK25A-AW2J)	(4RK25A-AW2TJ)	25	Single-Phase 100	60	0.69	140	170	1450	10					
4RK25GN-AW2U	4RK25GN-AW2TU	25	Single-Phase 110	60	0.56	140	170	1450	0.0					
(4RK25A-AW2U)	(4RK25A-AW2TU)	25	Single-Phase 115	60	0.56	140	170	1450	8.0					
4RK25GN-CW2J	4RK25GN-CW2TJ	25	Cingle Phase 200	50	0.32	160	205	1200	2.0					
(4RK25A-CW2J)	(4RK25A-CW2TJ)	25	Single-Phase 200	60	0.40	140	170	1450	3.0					
			Single-Phase 220	50	0.29	140	205	1200						
4RK25GN-CW2E	4RK25GN-CW2TE	25	Sillyle-rilase 220	60	0.35	140	170	1450	2.5					
(4RK25A-CW2E)	(4RK25A-CW2TE)	25	Single-Phase 230	50	0.30	160	205	1200	2.5					
, ,			Sillyle-rilase 230	60	0.35	140	170	1450						

 $<sup>\</sup>blacksquare \ \, \text{Values shown for rated torque and starting torque are measured for operation without the friction brake installed}.$ 

### Product Line

### ● Motor (RoHS)

Tuno	Mo	del
Туре	Pinion Shaft Type	Round Shaft Type
	4RK25GN-AW2J	4RK25A-AW2J
Lood Wire	4RK25GN-AW2U	4RK25A-AW2U
Lead Wire	4RK25GN-CW2J	4RK25A-CW2J
	4RK25GN-CW2E	4RK25A-CW2E
	4RK25GN-AW2TJ	4RK25A-AW2TJ
Taurainal Dav	4RK25GN-AW2TU	4RK25A-AW2TU
Terminal Box	4RK25GN-CW2TJ	4RK25A-CW2TJ
	4RK25GN-CW2TE	4RK25A-CW2TE

### • Gearhead/Right-Angle Gearhead (Sold Separately) (RoHS)

Туре	Gearhead Model	Gear Ratio
Long Life/Low Noise/ Parallel Shaft	4GN□S	3, 3.6, 5, 6, 7.5, 9, 12.5, 15, 18, 25, 30, 36, 50, 60, 75, 90, 100, 120, 150, 180
	4GN10XS (Decima	al gearhead)
Right-Angle/ Hollow Shaft	4GN□RH	3, 3.6, 5, 6, 7.5, 9, 12.5, 15, 18, 25, 30, 36, 50, 60, 75, 90, 100, 120, 150, 180
Right-Angle/ Solid Shaft	4GN□RA	3, 3.6, 5, 6, 7.5, 9, 12.5, 15, 18, 25, 30, 36, 50, 60, 75, 90, 100, 120, 150, 180

lacksquare Enter the gear ratio in the box ( $\Box$ ) within the model name.

<sup>•</sup> The **J**, **U** and **E** at the end of the model name indicate that the unit includes a capacitor. These letters are not listed on the motor nameplate. When the motor is approved under various safety standards, the model name on the nameplate is the approved model name.

<sup>(</sup>IP): Contains a built-in thermal protector. If a motor overheats for any reason, the thermal protector is opened and the motor stops.

When the motor temperature drops, the thermal protector closes and the motor restarts. Be sure to turn the motor off before inspecting.

### ■Gearmotor – Torque Table

- •Gearheads and decimal gearheads are sold separately.
- ●Enter the code that represents the terminal box type "T" in the box (□) within the model name.
- ■Enter the gear ratio in the box (□) within the model name.
- •A colored background indicates gear shaft rotation in the same direction as the motor shaft, while the others rotate in the opposite direction.
- The speed is calculated by dividing the motor's synchronous speed (50 Hz: 1500 r/min, 60 Hz: 1800 r/min) by the gear ratio. The actual speed is 2 20% less than the displayed value, depending on the size of the load.
- ■To reduce the speed beyond the gear ratio in the table, attach a decimal gearhead (gear ratio: 10) between the gearhead and the motor. In that case, the permissible torque is 8 N·m. When a gearhead of 1/25~1/36 is connected, the value for permissible torque is 6 N·m.

<b>♦50 Hz</b>																				Uni	t = N·m
Model	Speed r/min	500	416	300	250	200	166	120	100	83	60	50	41	30	25	20	16	15	12.5	10	8.3
Motor/ Gearhead	Gear Ratio	3	3.6	5	6	7.5	9	12.5	15	18	25	30	36	50	60	75	90	100	120	150	180
4RK25GN-AW2J 4RK25GN-CW2J 4RK25GN-CW2E	dGN□S	0.50	0.60	0.83	1.0	1.2	1.5	2.1	2.5	3.0	3.7	4.5	5.4	6.8	8	8	8	8	8	8	8
♦ 60 Hz														t = N•m							
Model	Speed r/min	600	500	360	300	240	200	144	120	100	72	60	50	36	30	24	20	18	15	12	10
Motor/ Gearhead	Gear Ratio	3	3.6	5	6	7.5	9	12.5	15	18	25	30	36	50	60	75	90	100	120	150	180
4RK25GN-AW2_J 4RK25GN-AW2_U 4RK25GN-CW2_J	<b>4GN</b> □S	0.41	0.50	0.69	0.83	1.0	1.2	1.7	2.1	2.5	3.1	3.7	4.5	5.6	6.7	8	8	8	8	8	8

### Permissible Overhung Load and Permissible Thrust Load

Motor (Round shaft type) → Page 107 Gearhead → Page 107

### Permissible Load Inertia J for Gearhead

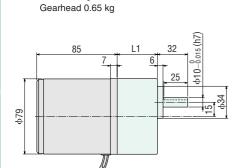
Motor Leads 300 mm Length UL Style 3271, AWG20

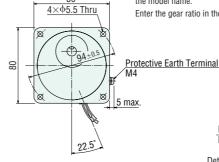
→ Page 107

### **Dimensions** (Unit = mm)

♦ Lead Wire Type ①
Mass: Motor 1.5 kg

Mounting screws are included with gearheads.





Motor Model	Gearhead Model	Gear Ratio	L1	CAD
4RK25GN-AW2■	4GN□S	3~18	32	A449A
4RK25GN-CW2■	4GN_5	<b>25~180</b>	42.5	A449B

Specify the type of the capacitor to be included by entering J, U or E in the box (
 within the model name.

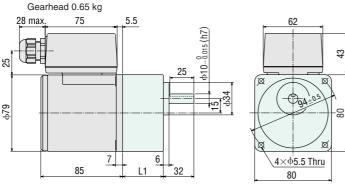
Enter the gear ratio in the box ((\_)) within the model name.



Detail Drawing of Protective Earth Terminal

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Mass: Motor 1.7 kg



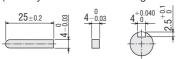
Motor Model	Gearhead Model	Gear Ratio	L1	CAD
4RK25GN-AW2T■	4GN□S	3~18	32	A451A
4RK25GN-CW2T	46N_3	<b>25~180</b>	42.5	A451B

Specify the type of the capacitor to be included by entering J, U or E in the box (
 within the model name.

Enter the gear ratio in the box  $(\Box)$  within the model name.

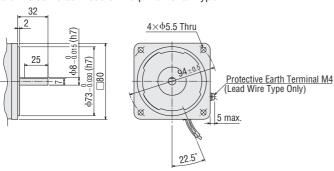
### 

(The key is included with the gearhead)



### ♦ Shaft Section of Round Shaft Type

The mass and motor's dimensions (excluding the shaft section) are the same as those of the pinion shaft type.



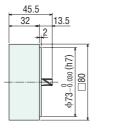
### ♦ Decimal Gearhead

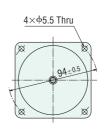
Can be connected to GN pinion shaft type.

### **4GN10XS**

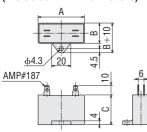
Mass: 0.4 kg

**CAD** A013





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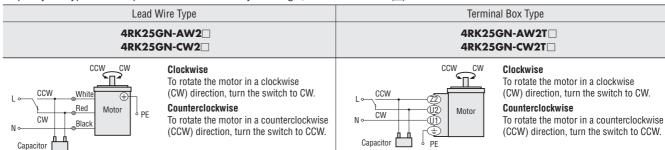


### 

Upper Model Name	odel e: Pinion Shaft Type ( ): Round Shaft Type	Capacitor Model	А	В	С	Mass (g)	Capacitor Cap			
Lead Wire Type	Terminal Box Type									
4RK25GN-AW2J (4RK25A-AW2J)	4RK25GN-AW2TJ (4RK25A-AW2TJ)	CH100CFAUL2	58	21	31	50				
4RK25GN-AW2U (4RK25A-AW2U)	4RK25GN-AW2TU (4RK25A-AW2TU)	CH80CFAUL2	48	21	31	45	leadered and			
4RK25GN-CW2J (4RK25A-CW2J)	4RK25GN-CW2TJ (4RK25A-CW2TJ)	CH30BFAUL	58	21	31	50	Included			
4RK25GN-CW2E (4RK25A-CW2E)	4RK25GN-CW2TE (4RK25A-CW2TE)	CH25BFAUL	48	21	31	45				

### Connection Diagrams

- The direction of motor rotation is as viewed from the shaft end of the motor. CW represents the clockwise direction, while CCW represents the counterclockwise direction.
- Connection diagrams are also valid for the equivalent round shaft type.
- ■Specify the type of the capacitor to be included by entering **J**, **U** or **E** in the box (□) within the model name.



PE: Protective Earth

Note:

Connect a CR circuit to the forward/reverse select switch to protect the contact.

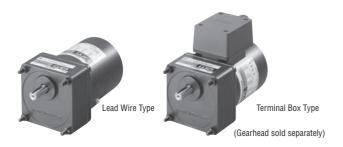
 $<sup>\</sup>bullet$  Use cable with a diameter of  $\varphi6\sim\varphi12$  mm.



### **Reversible Motors**

# 40 W

Frame Size: **□90** mm



Right-angle gearheads (hollow shaft or solid shaft) can be combined.

Right-Angle Gearheads → Page 108





## ■Specifications – 30 Minutes Rating (RoHS)



	Upper Model Name: P	21		Model er Model Name: Pinion Shaft Type Model Name (): Round Shaft Type Powe			Frequency	Current	Starting Torque	Rated Torque	Rated Speed	Capacitor
	Lead Wire Type Dimension ①	Terminal Box Type Dimension ②	W	VAC	Hz A mN·m		mN∙m	r/min	μF			
	5RK40GN-AW2J	5RK40GN-AW2TJ	40	Cingle Phase 100	50	0.91	300	315	1250	16		
TP	(5RK40A-AW2J)	(5RK40A-AW2TJ)	40	Single-Phase 100	60	1.09	260	270	1450	10		
(TP)	5RK40GN-AW2U	5RK40GN-AW2TU	40	Single-Phase 110	60	0.88	260	270	1450	12		
(IP)	(5RK40A-AW2U)	(5RK40A-AW2TU)	40	Single-Phase 115	00	0.87	200	270	1450	12		
	5RK40GN-CW2J	5RK40GN-CW2TJ	40	Cinala Dhaga 200	50	0.46	270	315	1250	4.0		
TP)	(5RK40A-CW2J)	(5RK40A-CW2TJ)	40	Single-Phase 200	60	0.55	260	260	1500	4.0		
				Cinala Dhaga 220	50	0.43	270	315	1250			
TD	5RK40GN-CW2E	5RK40GN-CW2TE	40	Single-Phase 220	60	0.48	260	260	1500	2.5		
TP	(5RK40A-CW2E)	(5RK40A-CW2TE)	40	Cingle Phone 220	50	0.43	270	315	1250	3.5		
				Single-Phase 230	60	0.48	260	260	1500			

<sup>•</sup> Values shown for rated torque and starting torque are measured for operation without the friction brake installed.

### Product Line

### ● Motor (RoHS)

Type	Mo	del						
туре	Pinion Shaft Type	Round Shaft Type						
	5RK40GN-AW2J	5RK40A-AW2J						
Lead Wire	5RK40GN-AW2U	5RK40A-AW2U						
	5RK40GN-CW2J	5RK40A-CW2J						
	5RK40GN-CW2E	5RK40A-CW2E						
	5RK40GN-AW2TJ	5RK40A-AW2TJ						
Terminal Box	5RK40GN-AW2TU	5RK40A-AW2TU						
Terriniai box	5RK40GN-CW2TJ	5RK40A-CW2TJ						
	5RK40GN-CW2TE	5RK40A-CW2TE						

### ● Gearhead/Right-Angle Gearhead (Sold Separately) ® (RoHS)

Туре	Gearhead Model	Gear Ratio							
Long Life/Low Noise/ Parallel Shaft	5GN□S	3, 3.6, 5, 6, 7.5, 9, 12.5, 15, 18, 25, 30, 36, 50, 60, 75, 90, 100, 120, 150, 180							
	5GN10XS (Decimal gearhead)								
Right-Angle/ Hollow Shaft	5GN□RH	3, 3.6, 5, 6, 7.5, 9, 12.5, 15, 18, 25, 30, 36, 50, 60, 75, 90, 100, 120, 150, 180							
Right-Angle/ Solid Shaft	5GN□RA	3, 3.6, 5, 6, 7.5, 9, 12.5, 15, 18, 25, 30, 36, 50, 60, 75, 90, 100, 120, 150, 180							

 $<sup>\</sup>bullet$  Enter the gear ratio in the box (  $\square$  ) within the model name.

<sup>•</sup> The **J**, **U** and **E** at the end of the model name indicate that the unit includes a capacitor. These letters are not listed on the motor nameplate. When the motor is approved under various safety standards, the model name on the nameplate is the approved model name.

<sup>(</sup>IP): Contains a built-in thermal protector. If a motor overheats for any reason, the thermal protector is opened and the motor stops.

When the motor temperature drops, the thermal protector closes and the motor restarts. Be sure to turn the motor off before inspecting.

High-Speed Type

### ■Gearmotor - Torque Table

- •Gearheads and decimal gearheads are sold separately.
- ●Enter the code that represents the terminal box type "T" in the box (□) within the model name.
- ■Enter the gear ratio in the box (□) within the model name.
- •A colored background indicates gear shaft rotation in the same direction as the motor shaft, while the others rotate in the opposite direction.
- The speed is calculated by dividing the motor's synchronous speed (50 Hz: 1500 r/min, 60 Hz: 1800 r/min) by the gear ratio. The actual speed is 2 20% less than the displayed value, depending on the size of the load.
- ■To reduce the speed beyond the gear ratio in the table, attach a decimal gearhead (gear ratio: 10) between the gearhead and the motor. In that case, the permissible torque is 10 N·m.

<b>♦50 Hz</b>																				Uni	it = N·m
Model	Speed r/min	500	416	300	250	200	166	120	100	83	60	50	41	30	25	20	16	15	12.5	10	8.3
Motor/ Gearhead	Gear Ratio	3	3.6	5	6	7.5	9	12.5	15	18	25	30	36	50	60	75	90	100	120	150	180
5RK40GN-AW2J 5RK40GN-CW2J 5RK40GN-CW2E	5GN□S	0.77	0.92	1.3	1.5	1.9	2.3	3.2	3.8	4.6	5.7	6.9	8.3	10	10	10	10	10	10	10	10

<b>♦60 Hz</b>	♦60 Hz															t = N·m					
Model	Speed r/min	600	500	360	300	240	200	144	120	100	72	60	50	36	30	24	20	18	15	12	10
Motor/ Gearhead	Gear Ratio	3	3.6	5	6	7.5	9	12.5	15	18	25	30	36	50	60	75	90	100	120	150	180
5RK40GN-AW2J 5RK40GN-AW2U	/ 5GN□S	0.66	0.79	1.1	1.3	1.6	2.0	2.7	3.3	3.9	4.9	5.9	7.1	8.9	10	10	10	10	10	10	10
5RK40GN-CW2□J 5RK40GN-CW2□E	/ 5GN□S	0.63	0.76	1.1	1.3	1.6	1.9	2.6	3.2	3.8	4.7	5.7	6.8	8.6	10	10	10	10	10	10	10

### Permissible Overhung Load and Permissible Thrust Load

Motor (Round shaft type) → Page 107 Gearhead → Page 107

### Permissible Load Inertia J for Gearhead

→ Page 107

### **Dimensions** (Unit = mm)

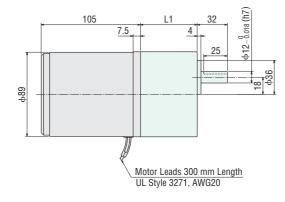
Mounting screws are included with gearheads.

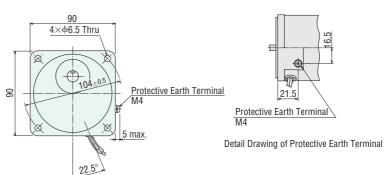
♦ Lead Wire Type ①
Mass: Motor 2.5 kg
Gearhead 1.5 kg

Motor Model	Gearhead Model	Gear Ratio	L1	CAD
5RK40GN-AW2	5GN□S	3~18	42	A452A
5RK40GN-CW2	3GN_3	25~180	60	A452B

Specify the type of the capacitor to be included by entering J, U or E in the box () within
the model name.

Enter the gear ratio in the box ( $\square$ ) within the model name.





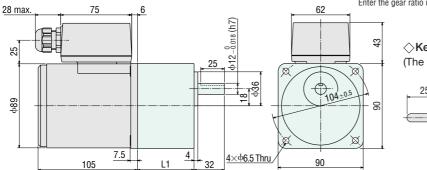
### $\lozenge$ Terminal Box Type @

Mass: Motor 2.6 kg Gearhead 1.5 kg

Motor Model	Gearhead Model	Gear Ratio	L1	CAD
5RK40GN-AW2T	5GN□S	3~18	42	A454A
5RK40GN-CW2T	3GN_3	<b>25~180</b>	60	A454B

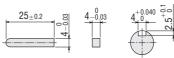
Specify the type of the capacitor to be included by entering J, U or E in the box () within
the model name.

Enter the gear ratio in the box  $(\Box)$  within the model name.



### 

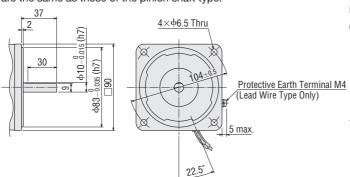
(The key is included with the gearhead)



 $lue{}$  Use cable with a diameter of  $\phi 6 \sim \phi 12$  mm.

### ♦ Shaft Section of Round Shaft Type

The mass and motor's dimensions (excluding the shaft section) are the same as those of the pinion shaft type.

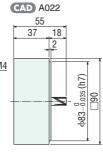


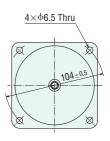
### 

Can be connected to  $\boldsymbol{GN}$  pinion shaft type.

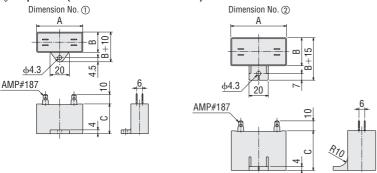
### **5GN10XS**

Mass: 0.6 kg





### 



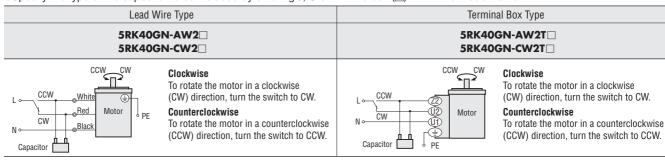
### 

Oupdonor Billion								
Upper Model Name	odel e: Pinion Shaft Type (): Round Shaft Type	Capacitor Model	А	В	С	Mass (g)	Dimension No.	Capacitor Cap
Lead Wire Type	31 31							
5RK40GN-AW2J (5RK40A-AW2J)	5RK40GN-AW2TJ (5RK40A-AW2TJ)	CH160CFAUL2	58	23.5	37	75	2	
5RK40GN-AW2U (5RK40A-AW2U)	5RK40GN-AW2TU (5RK40A-AW2TU)	CH120CFAUL2	58	22	35	60	①	Included
5RK40GN-CW2J (5RK40A-CW2J)	5RK40GN-CW2TJ (5RK40A-CW2TJ)	CH40BFAUL	58	23.5	37	70	2	mciaaea
5RK40GN-CW2E (5RK40A-CW2E)			58	22	35	55	①	

High-Speed Type

### ■Connection Diagrams

- The direction of motor rotation is as viewed from the shaft end of the motor. CW represents the clockwise direction, while CCW represents the counterclockwise direction.
- Connection diagrams are also valid for the equivalent round shaft type.
- Specify the type of the capacitor to be included by entering J, U or E in the box (□) within the model name.



PE: Protective Earth

Note:

Connect a CR circuit to the forward/reverse select switch to protect the contact.

**EPCR1201-2** is available as an optional surge suppressor. → Page 123



### **Reversible Motors**

# 60 W

Frame Size: **□90** mm





(Gearhead sold separately)

Right-angle gearheads (hollow shaft or solid shaft) can be combined.

Right-Angle Gearheads → Page 108





### Specifications – 30 Minutes Rating (RoHS)

c**™**us ⋘ €€





	Upper Model Name: Pinion Shaft Type Lower Model Name ( ): Round Shaft Type			Voltage	Frequency	Current	Starting Torque	Rated Torque	Rated Speed	Capacitor	
	Lead Wire Type Dimension ①	Terminal Box Type Dimension ②	W	VAC	Hz	А	mN∙m	mN∙m	r/min	μF	
TD	5RK60GE-AW2J	5RK60GE-AW2TJ	60	Cingle Phase 100	50	1.35	470	490	1200	25	
TP	(5RK60A-AW2J)	(5RK60A-AW2TJ)	60	Single-Phase 100	60	1.52	380	405	1450	25	
(TP)	5RK60GE-AW2U	5RK60GE-AW2TU	60	Single-Phase 110	60	1.27	380	405	1450	20	
	(5RK60A-AW2U)	(5RK60A-AW2TU)	00	Single-Phase 115	00	1.27	300	405	1450	20	
ŒD.	5RK60GE-CW2J	5RK60GE-CW2TJ	60	Cingle Phase 200	50	0.66	450	490	1200	6.0	
TP)	(5RK60A-CW2J)	(5RK60A-CW2TJ)	60	Single-Phase 200	60	0.79	380	405	1450	0.0	
				Single-Phase 220	50	0.61	420	490	1200		
(TP)	5RK60GE-CW2E	5RK60GE-CW2TE	60	Siligie-Pliase 220	60	0.67	380	405	1450		
(IP)	(D)	(5RK60A-CW2TE)	60	50	0.63	470	490	1200	5.0		
				60	0.66	380	405	1450			

<sup>•</sup> Values shown for rated torque and starting torque are measured for operation without the friction brake installed.

### Product Line

### ● Motor (RoHS)

Tuno	Mo	odel
Туре	Pinion Shaft Type	Round Shaft Type
	5RK60GE-AW2J	5RK60A-AW2J
Lead Wire	5RK60GE-AW2U	5RK60A-AW2U
Leau Wire	5RK60GE-CW2J	5RK60A-CW2J
	5RK60GE-CW2E	5RK60A-CW2E
	5RK60GE-AW2TJ	5RK60A-AW2TJ
Terminal Box	5RK60GE-AW2TU	5RK60A-AW2TU
reminial box	5RK60GE-CW2TJ	5RK60A-CW2TJ
	5RK60GE-CW2TE	5RK60A-CW2TE

### ● Gearhead/Right-Angle Gearhead (Sold Separately) ® (ROHS)

Туре		Gearhead Model	Gear Ratio
Long Life Parallel Sha	-	GE□S	3, 3.6, 5, 6, 7.5, 9, 12.5, 15, 18, 25, 30, 36, 50, 60, 75, 90, 100, 120, 150, 180
	5	GE10XS (Decima	ll gearhead)
Right-Angl Hollow Sha	-	iGE□RH	3, 3.6, 5, 6, 7.5, 9, 12.5, 15, 18, 25, 30, 36, 50, 60, 75, 90, 100, 120, 150, 180
Right-Angl Solid Shat		iGE□RA	3, 3.6, 5, 6, 7.5, 9, 12.5, 15, 18, 25, 30, 36, 50, 60, 75, 90, 100, 120, 150, 180

<sup>■</sup> Enter the gear ratio in the box (□) within the model name.

The J, U and E at the end of the model name indicate that the unit includes a capacitor. These letters are not listed on the motor nameplate. When the motor is approved under various safety standards, the model name on the nameplate is the approved model name.

<sup>(</sup>m): Contains a built-in thermal protector. If a motor overheats for any reason, the thermal protector is opened and the motor stops. When the motor temperature drops, the thermal protector closes and the motor restarts. Be sure to turn the motor off before inspecting.

### ■Gearmotor - Torque Table

- •Gearheads and decimal gearheads are sold separately.
- ●Enter the code that represents the terminal box type "T" in the box (□) within the model name.
- ■Enter the gear ratio in the box (□) within the model name.
- •A colored background indicates gear shaft rotation in the same direction as the motor shaft, while the others rotate in the opposite direction
- The speed is calculated by dividing the motor's synchronous speed (50 Hz: 1500 r/min, 60 Hz: 1800 r/min) by the gear ratio. The actual speed is 2 20% less than the displayed value, depending on the size of the load.
- To reduce the speed beyond the gear ratio in the table, attach a decimal gearhead (gear ratio: 10) between the gearhead and the motor. In that case, the permissible torque is 20 N·m.

<b>♦50 Hz</b>																				Uni	it = N·m
Model	Speed r/min	500	416	300	250	200	166	120	100	83	60	50	41	30	25	20	16	15	12.5	10	8.3
Motor/ Gearhead	Gear Ratio	3	3.6	5	6	7.5	9	12.5	15	18	25	30	36	50	60	75	90	100	120	150	180
5RK60GE-AW2J 5RK60GE-CW2J 5RK60GE-CW2E	5GE□S	1.2	1.4	2.0	2.4	3.0	3.6	4.5	5.4	6.4	8.1	9.7	11.6	16.2	19.4	20	20	20	20	20	20

<b>♦60 Hz</b>	♦ 60 Hz Unit = N															t = N·m					
Model	Speed r/min	600	500	360	300	240	200	144	120	100	72	60	50	36	30	24	20	18	15	12	10
Motor/ Gearhead	Gear Ratio	3	3.6	5	6	7.5	9	12.5	15	18	25	30	36	50	60	75	90	100	120	150	180
5RK60GE-AW2_J 5RK60GE-AW2_U 5RK60GE-CW2_J 5RK60GE-CW2_E	<b>5GE</b> □S	0.98	1.2	1.6	2.0	2.5	3.0	3.7	4.4	5.3	6.7	8.0	9.6	13.4	16.0	17.9	20	20	20	20	20

### Permissible Overhung Load and Permissible Thrust Load

Motor (Round shaft type) → Page 107 Gearhead → Page 107

### Permissible Load Inertia J for Gearhead

→ Page 107

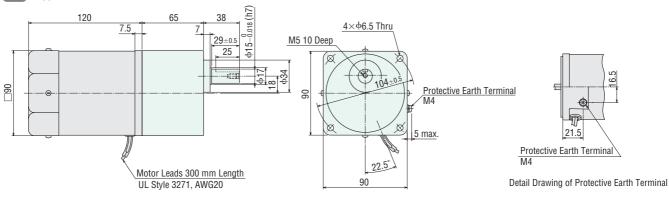
### **Dimensions** (Unit = mm)

Mounting screws are included with gearheads.

♦ Lead Wire Type ①

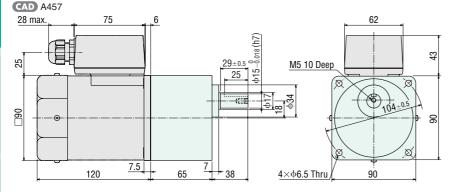
Mass: Motor 2.7 kg Gearhead 1.5 kg

**CAD** A455



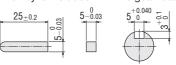
### 

Mass: Motor 2.8 kg Gearhead 1.5 kg



### 

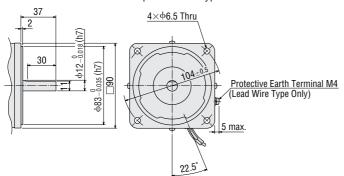
(The key is included with the gearhead)



• Use cable with a diameter of  $\phi 6 \sim \phi 12$  mm.

### ♦ Shaft Section of Round Shaft Type

The mass and motor's dimensions (excluding the shaft section) are the same as those of the pinion shaft type.

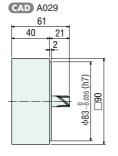


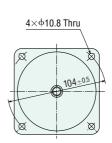
### 

Can be connected to **GE** pinion shaft type.

### 5GE10XS

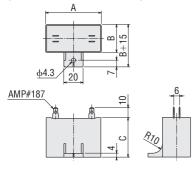
Mass: 0.6 kg





### 

(Included with the motors)



### 

Upper Model Name	odel e: Pinion Shaft Type ( ): Round Shaft Type	Capacitor Model	А	В	С	Mass (g)	Capacitor Cap
Lead Wire Type	Terminal Box Type						
5RK60GE-AW2J (5RK60A-AW2J)	5RK60GE-AW2TJ (5RK60A-AW2TJ)	CH250CFAUL2	58	35	50	140	
5RK60GE-AW2U (5RK60A-AW2U)	5RK60GE-AW2TU (5RK60A-AW2TU)	CH200CFAUL2	58	29	41	95	Included
5RK60GE-CW2J (5RK60A-CW2J)	5RK60GE-CW2TJ (5RK60A-CW2TJ)	CH60BFAUL	58	29	41	85	iliciadea
5RK60GE-CW2E (5RK60A-CW2E)	5RK60GE-CW2TE (5RK60A-CW2TE)	CH50BFAUL	58	29	41	85	

### **■**Connection Diagrams

- •The direction of motor rotation is as viewed from the shaft end of the motor. CW represents the clockwise direction, while CCW represents the counterclockwise direction.
- Connection diagrams are also valid for the equivalent round shaft type.
- Specify the type of the capacitor to be included by entering J, U or E in the box (□) within the model name.

Lead Wire Type	Terminal Box Type							
5RK60GE-AW2□ 5RK60GE-CW2□	5RK60GE-AW2T□ 5RK60GE-CW2T□							
CCW CW Clockwise To rotate the motor in a clockwise (CW) direction, turn the switch to CW.  Capacitor Black  Capacitor Cownerclockwise  To rotate the motor in a counterclockwise (CCW) direction, turn the switch to CCW.	Clockwise To rotate the motor in a clockwise (CW) direction, turn the switch to CW.  Counterclockwise To rotate the motor in a counterclockwise (CW) direction, turn the switch to CCW.							

PE: Protective Earth

Note:

Connect a CR circuit to the forward/reverse select switch to protect the contact.

(RoHS)

### **Reversible Motors**

# 90 W

Frame Size: **□90** mm





Right-angle gearheads (hollow shaft or solid shaft) can be combined.

Right-Angle Gearheads → Page 108





### ■ Specifications – 30 Minutes Rating (RoHS)



	Upper Model Name: Pinion Shaft Type Lower Model Name ( ): Round Shaft Type			Voltage	Frequency	Current	Starting Torque	Rated Torque	Rated Speed	Capacitor
	Lead Wire Type Dimension ①	Terminal Box Type Dimension ②	W	VAC	Hz	A	mN∙m	mN∙m	r/min	μF
(TP)	5RK90GE-AW2J	5RK90GE-AW2TJ	90	Single-Phase 100	50	1.85	630	700	1250	35
(IP)	(5RK90A-AW2J)	(5RK90A-AW2TJ)	90	Siligie-Pliase 100	60	2.16	590	585	1500	35
(TP)	5RK90GE-AW2U	5RK90GE-AW2TU	90	Single-Phase 110	60	1.87	590	585	1500	30
(IP)	(5RK90A-AW2U)	(5RK90A-AW2TU)	90	Single-Phase 115	00	1.86	590	363	1500	30
(TP)	5RK90GE-CW2J	5RK90GE-CW2TJ	90	Cinala Dhaga 200	50	0.91	600	730	1200	0.0
(IP)	(5RK90A-CW2J)	(5RK90A-CW2TJ)	90	Single-Phase 200	60	1.09	590	605	1450	8.0
				Cinala Dhaga 220	50	0.83	600	730	1200	
TD	5RK90GE-CW3E	5RK90GE-CW3TE	90	Single-Phase 220	60	0.96	590	605	1450	7.0
TP	(5RK90A-CW3E) (5RK90A-CW3TE)	90	Cingle Phone 220	50	0.83	600	730	1200	7.0	
				Single-Phase 230	60	0.95	590	605	1450	

Values shown for rated torque and starting torque are measured for operation without the friction brake installed.

### Product Line

### ● Motor (RoHS)

	_						
Tuno	Model						
Туре	Pinion Shaft Type	Round Shaft Type					
	5RK90GE-AW2J	5RK90A-AW2J					
Lead Wire	5RK90GE-AW2U	5RK90A-AW2U					
Leau Wire	5RK90GE-CW2J	5RK90A-CW2J					
	5RK90GE-CW3E	5RK90A-CW3E					
	5RK90GE-AW2TJ	5RK90A-AW2TJ					
Terminal Box	5RK90GE-AW2TU	5RK90A-AW2TU					
Terrilliai box	5RK90GE-CW2TJ	5RK90A-CW2TJ					
	5RK90GE-CW3TE	5RK90A-CW3TE					

### Gearhead/Right-Angle Gearhead (Sold Separately) (RoHS)

Туре	Gearhead Model	Gear Ratio						
Long Life/ Parallel Shaft	5GE□S	3, 3.6, 5, 6, 7.5, 9, 12.5, 15, 18, 25, 30, 36, 50, 60, 75, 90, 100, 120, 150, 180						
	5GE10XS (Decimal gearhead)							
Right-Angle/ Hollow Shaft	5GE□RH	3, 3.6, 5, 6, 7.5, 9, 12.5, 15, 18, 25, 30, 36, 50, 60, 75, 90, 100, 120, 150, 180						
Right-Angle/ Solid Shaft	5GE□RA	3, 3.6, 5, 6, 7.5, 9, 12.5, 15, 18, 25, 30, 36, 50, 60, 75, 90, 100, 120, 150, 180						

lacksquare Enter the gear ratio in the box ( $\Box$ ) within the model name.

<sup>•</sup> The **J**, **U** and **E** at the end of the model name indicate that the unit includes a capacitor. These letters are not listed on the motor nameplate. When the motor is approved under various safety standards, the model name on the nameplate is the approved model name.

<sup>(</sup>T): Contains a built-in thermal protector. If a motor overheats for any reason, the thermal protector is opened and the motor stops.

When the motor temperature drops, the thermal protector closes and the motor restarts. Be sure to turn the motor off before inspecting.

### ■Gearmotor – Torque Table

- •Gearheads and decimal gearheads are sold separately.
- ●Enter the code that represents the terminal box type "T" in the box (□) within the model name.
- ■Enter the gear ratio in the box (□) within the model name.
- •A colored background indicates gear shaft rotation in the same direction as the motor shaft, while the others rotate in the opposite direction.
- The speed is calculated by dividing the motor's synchronous speed (50 Hz: 1500 r/min, 60 Hz: 1800 r/min) by the gear ratio. The actual speed is 2 20% less than the displayed value, depending on the size of the load.
- ■To reduce the speed beyond the gear ratio in the table, attach a decimal gearhead (gear ratio: 10) between the gearhead and the motor. In that case, the permissible torque is 20 N·m.

<b>♦50 Hz</b>																				Uni	t = N·m
Model	Speed r/min	500	416	300	250	200	166	120	100	83	60	50	41	30	25	20	16	15	12.5	10	8.3
Motor/ Gearhead	Gear Ratio	3	3.6	5	6	7.5	9	12.5	15	18	25	30	36	50	60	75	90	100	120	150	180
5RK90GE-AW2  J	5GE□S	1.7	2.0	2.8	3.4	4.3	5.1	6.4	7.7	9.2	11.6	13.9	16.6	20	20	20	20	20	20	20	20
5RK90GE-CW2□J 5RK90GE-CW3□E	5GE□S	1.8	2.1	3.0	3.5	4.4	5.3	6.7	8.0	9.6	12.0	14.5	17.3	20	20	20	20	20	20	20	20
<b>♦60 Hz</b>																				Uni	t = N•m
Model	Speed r/min	600	500	360	300	240	200	144	120	100	72	60	50	36	30	24	20	18	15	12	10
Motor/ Gearhead	Gear Ratio	3	3.6	5	6	7.5	9	12.5	15	18	25	30	36	50	60	75	90	100	120	150	180
5RK90GE-AW2J 5RK90GE-AW2U	5GE□S	1.4	1.7	2.4	2.8	3.6	4.3	5.3	6.4	7.7	9.7	11.6	13.9	19.3	20	20	20	20	20	20	20

4.4

7.9 | 10.0 | 12.0 | 14.4 | 20

20

20

### Permissible Overhung Load and Permissible Thrust Load

1.8 | 2.5 | 2.9

Motor (Round shaft type) → Page 107 Gearhead → Page 107

### Permissible Load Inertia J for Gearhead

5GE□S

→ Page 107

5RK90GE-CW2IIJ

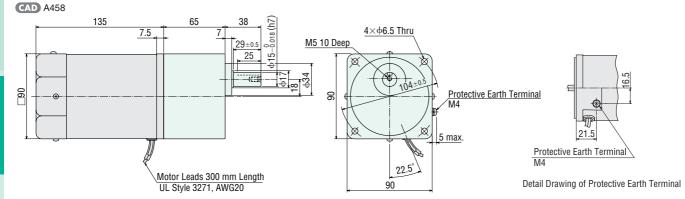
5RK90GE-CW3

### Dimensions (Unit = mm)

Mounting screws are included with gearheads.

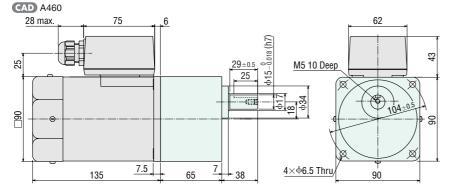
♦ Lead Wire Type ①
Mass: Motor 3.2 kg

Gearhead 1.5 kg

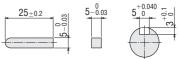


High-Speed Type

Mass: Motor 3.3 kg Gearhead 1.5 kg



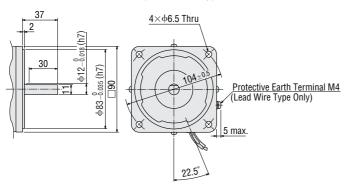
(The key is included with the gearhead)



 $\bullet$  Use cable with a diameter of  $\varphi 6 \sim \varphi 12$  mm.

### ♦ Shaft Section of Round Shaft Type

The mass and motor's dimensions (excluding the shaft section) are the same as those of the pinion shaft type.

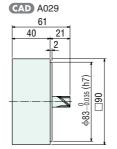


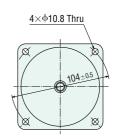
### 

Can be connected to **GE** pinion shaft type.

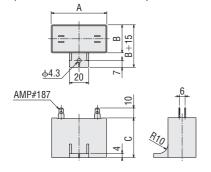
### 5GE10XS

Mass: 0.6 kg





### 

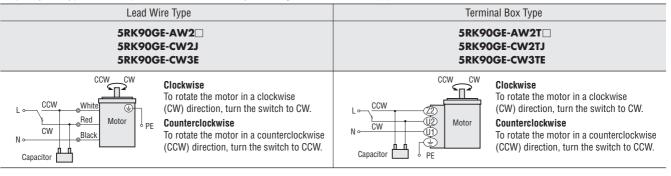


### 

Upper Model Name	Capacitor Model	А	В	С	Mass (g)	Capacitor Cap	
Lead Wire Type	Terminal Box Type						
5RK90GE-AW2J (5RK90A-AW2J)	5RK90GE-AW2TJ (5RK90A-AW2TJ)	CH350CFAUL2	58	41	58	180	
5RK90GE-AW2U (5RK90A-AW2U)	5RK90GE-AW2TU (5RK90A-AW2TU)	CH300CFAUL2	58	35	50	140	Included
5RK90GE-CW2J (5RK90A-CW2J)	5RK90GE-CW2TJ (5RK90A-CW2TJ)	CH80BFAUL	58	35	50	130	iliciuded
5RK90GE-CW3E (5RK90A-CW3E)	5RK90GE-CW3TE (5RK90A-CW3TE)	CH70BFAUL	58	35	50	130	

### Connection Diagrams

- The direction of motor rotation is as viewed from the shaft end of the motor. CW represents the clockwise direction, while CCW represents the counterclockwise direction.
- Connection diagrams are also valid for the equivalent round shaft type.
- Specify the type of the capacitor to be included by entering J or U in the box (☐) within the model name.



PE: Protective Earth

Note

Connect a CR circuit to the forward/reverse select switch to protect the contact.

**EPCR1201-2** is available as an optional surge suppressor. → Page 123

# RoHS RoHS-Compliant

# **Electromagnetic Brake Motors**





### Features

### Power Off Activated Type Electromagnetic Brake

These motors are directly coupled to an AC electromagnetic brake which is activated when power is not applied. When the power source is turned off, the motor stops instantaneously and holds the load. Since the electromagnetic brakes exert holding power even while the power is off, they are highly suitable for use as emergency brakes.

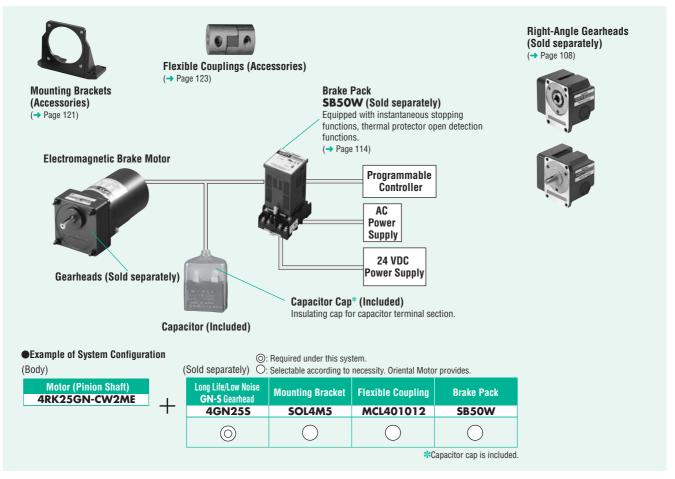
The holding brake force is, depending upon the size of the output, 30 mN·m~500 mN·m.

### ■Safety Standards and CE Marking

Standards	Certification Body	ertification Body Standards File No.					
UL 1004 UL 2111	UL	E64199 (6 W Type)					
CSA C22.2 No.100 CSA C22.2 No.77	UL	E64197 (15 W~90 W Type)					
EN 60950-1 EN 60034-1 EN 60034-5 IEC 60664-1		Conform to EN/IEC Standards	Low Voltage Directives				
GB 12350	CQC	2003010401091525 (Single-Phase 6 W) 2003010401091527 (Three-Phase 6 W) 2003010401091522 (Single-Phase 15 W~90 W Type) 2003010401091520 (Three-Phase 25 W~90 W Type)					

<sup>•</sup> When the motor is approved under various safety standards, the model name on the nameplate is the approved model name.

### System Configuration



<sup>•</sup> The system configuration shown above is an example. Other configurations are available.

### Product Number Code

Motor

# 5 R K 40 GN - CW 2 M E

<u>.</u>		<u> </u>
1	Motor Frame Size	2: 60 mm 3: 70 mm 4: 80 mm 5: 90 mm
2	Motor Type	I: Induction Motor R: Reversible Motor
3	Series	K: K Series
4	Output Power (W)	(Example) <b>40</b> : 40 W
(5)	Motor Shaft Type	GN: GN Type Pinion Shaft GE: GE Type Pinion Shaft A: Round Shaft
6	Power Supply Voltage	AW: Single-Phase 100 VAC, 110/115 VAC CW: Single-Phase 200 VAC, 220/230 VAC SW: Three-Phase 200/220/230 VAC
7	2: RoHS-Compliant	
8	M: Power Off Activated Elect	romagnetic Brake
9	Included Capacitor*	J: For Single-Phase 100 VAC, 200 VAC U: For Single-Phase 110/115 VAC E: For Single-Phase 220/230 VAC Blank: Three-Phase Type

\*For some products, type of capacitor varies. Refer to the pages where each product is listed.

RH: Right-Angle/Hollow Shaft Gearhead, RoHS-Compliant

• The J, U and E at the end of the model name indicate that the unit includes a capacitor. These letters are not listed on the motor nameplate.

When the motor is approved under various safety standards, the model name on the nameplate is the approved model name.

(Example) Model: **5RK40GN-CW2ME** → Motor nameplate and product approved under various safety standards: **5RK40GN-CW2M** 

Gearhead

# 5 GN 50 S

$\cup$	(2)	(3)	4)						
1	Gearhead Fra	ıme Size	2: 60 mm 3: 70 mm 4: 80 mm 5: 90 mm						
2	Type of Pinio	n	GN: GN Type Pinion GE: GE Type Pinion						
3	Gear Ratio		(Example) <b>50</b> : Gear Ratio of 1:50 <b>10X</b> denotes the decimal gearhead of gear ratio 1:10						
	S:   ong   ife/  ow Noise CN_S (seathead RoHS-Compliant								

RA: Right-Angle/Solid Shaft Gearhead, RoHS-Compliant

# ■General Specifications of Motors

Item	Specifications
Insulation Resistance	$100~\mathrm{M}\Omega$ or more when 500 VDC megger is applied between the windings and the frame after rated motor operation under normal ambient temperature and humidity.
Dielectric Strength	Sufficient to withstand 1.5 kV at 50 Hz or 60 Hz applied between the windings and the frame for 1 minute after rated motor operation under normal ambient temperature and humidity.
Temperature Rise	Temperature rise of windings are 80°C or less measured by the resistance change method after rated motor operation under normal ambient temperature and humidity, with connecting a gearhead or equivalent heat radiation plate*. (Three-phase type: 70°C or less)
Insulation Class	Class B (130°C)
Overheat Protection	6 W type has impedance protection.  All others have built-in thermal protector (automatic return type) Operating temperature; open: 130°C±5°C, close: 82°C±15°C
Ambient Temperature	Single-phase 100 VAC, Single-phase 200 VAC, Three-phase 200 VAC: $-10^{\circ}\text{C} \sim +50^{\circ}\text{C}$ (nonfreezing) Other voltage: $-10^{\circ}\text{C} \sim +40^{\circ}\text{C}$ (nonfreezing)
Ambient Humidity	85% or less (noncondensing)
Degree of Protection	6 W, 15 W, 25 W, 40 W Type: IP20 60 W, 90 W Type: IP40

\* Heat radiation plate (Material: Aluminum)

Size (mm)	Thickness (mm)
115×115	
125×125	
135×135	5
165×165	
200×200	
	115×115 125×125 135×135 165×165



# **Power Off Activated Type Electromagnetic Brake Motors**

**6W** 

Frame Size: **□60** mm



### Specifications

### ● Motor (RoHS)

This type of motor does not contain a built-in simple brake mechanism.

This type of motor does n	or contain a bant in	0									
Model	Rating	Output Power	Voltage	Frequency	Current	Starting Torque	Rated Torque	Rated Speed	Capacitor		
Pinion Shaft Type	Round Shaft Type		W	VAC	Hz	Α	mN∙m	mN∙m	r/min	μF	
ZP) 2RK6GN-AW2MJ	2RK6A-AW2MJ	30	6	Single-Phase 100	50	0.244	50	49	1150	4.5	
ZP ZRROGIN-AWZMJ	ZKKOA-AVV ZMIJ	minutes	0	Sillyle-Filase 100	60	0.295	45	41	1400	4.0	
ZP) 2RK6GN-AW2MU	2RK6A-AW2MU	30	6	Single-Phase 110	60	0.235	45	41	1450	3.5	
ZP ZRROGIN-AWZMO	2KKOA-AW2MU	minutes	U	Single-Phase 115	00	0.242	45	41	1450	3.3	
ZP) 2RK6GN-CW2MJ	2RK6A-CW2MJ	30	6	Single-Phase 200	50	0.113	50	49	1150	1.0	
ZP ZRROGN-CW ZMJ		minutes	Ü		60	0.131	45	41	1400		
				Single-Phase 220	50	0.107	50	49	1150		
ZP) 2RK6GN-CW2ME	2RK6A-CW2ME	30	6	Sillyle-Filase 220	60	0.109	45	41	1450	0.8	
ZP ZRROGN-CW ZME		minutes		Cinala Dhana 000	50	0.112	50	49	1200		
				Single-Phase 230	60	0.113	45	41	1450		
				Three-Phase 200	50	0.081	49	49	1200		
(ZP) 2IK6GN-SW2M	2IK6A-SW2M	Continuous	6	Tillee-Filase 200	60	0.072	41	41	1400		
ZP 2IK6GN-SW2M	ZIKOA-SW ZM	Continuous	О	Three-Phase 220	60	0.076	41	41	1500	_	
				Three-Phase 230	60	0.079	41	41	1500		

<sup>•</sup> The J, U and E at the end of the model name indicate that the unit includes a capacitor. These letters are not listed on the motor nameplate. When the motor is approved under various safety standards, the model name on the nameplate is the approved model name.

### Electromagnetic Brake (Power Off Activated Type)

Motor Model	Voltage VAC	Frequency Hz	Current A	Input W	Holding Brake Torque mN·m		
2RK6GN-AW2MJ	Single-Phase 100	50	0.03	3	30		
2RK6A-AW2MJ	Sillyle-Filase 100	60	0.03	3	30		
2RK6GN-AW2MU	Single-Phase 110	60	0.03	3	30		
2RK6A-AW2MU	Single-Phase 115	00	0.03	3	30		
2RK6GN-CW2MJ	Single-Phase 200	50	0.02	3	30		
2RK6A-CW2MJ	Sillyle-Filase 200	60	0.02	3	30		
	Single-Phase 220	50					
2RK6GN-CW2ME	Siligie-Pliase 220	60	0.02	3	30		
2RK6A-CW2ME	Cinala Dhana 000	50	0.02	3	30		
	Single-Phase 230	60					
	Single-Phase 200	50					
2IK6GN-SW2M	Sillyle-Filase 200	60	0.02	3	30		
2IK6A-SW2M	Single-Phase 220	60	0.02	3	ა0		
	Single-Phase 230	00					

### **■**Product Line

### ● Motor (RoHS)

_								
Model								
Pinion Shaft Type	Round Shaft Type							
2RK6GN-AW2MJ	2RK6A-AW2MJ							
2RK6GN-AW2MU	2RK6A-AW2MU							
2RK6GN-CW2MJ	2RK6A-CW2MJ							
2RK6GN-CW2ME	2RK6A-CW2ME							
2IK6GN-SW2M	2IK6A-SW2M							

### Gearhead (Sold Separately) (RoHS)

Туре	Gearhead Model	Gear Ratio						
Long Life/Low Noise/ Parallel Shaft	2GN□5	3, 3.6,5,6, 7.5, 9, 12.5, 15, 18, 25, 30, 36, 50, 60, 75, 90, 100, 120, 150, 180						
	2GN10XS (Decimal gearhead)							

<sup>●</sup> Enter the gear ratio in the box (□) within the model name.

**ZP**: Impedance protected

### ■Gearmotor - Torque Table

- •Gearheads and decimal gearheads are sold separately.
- ●Enter the gear ratio in the box (□) within the model name.
- •A colored background indicates gear shaft rotation in the same direction as the motor shaft, while the others rotate in the opposite direction.
- The speed is calculated by dividing the motor's synchronous speed (50 Hz: 1500 r/min, 60 Hz: 1800 r/min) by the gear ratio. The actual speed is 2 20% less than the displayed value, depending on the size of the load.
- To reduce the speed beyond the gear ratio in the table, attach a decimal gearhead (gear ratio: 10) between the gearhead and the motor. In that case, the permissible torque is 3 N·m.

♦50 Hz																				Unit	t = N·m
Model	Speed r/min	500	416	300	250	200	166	120	100	83	60	50	41	30	25	20	16	15	12.5	10	8.3
Motor/ Gearhead	Gear Ratio	3	3.6	5	6	7.5	9	12.5	15	18	25	30	36	50	60	75	90	100	120	150	180
2RK6GN-AW2MJ 2RK6GN-CW2MJ 2RK6GN-CW2ME 2IK6GN-SW2M	<b>2GN</b> □5	0.12	0.14	0.20	0.24	0.30	0.36	0.50	0.60	0.71	0.89	1.1	1.3	1.6	1.9	2.4	2.9	3	3	3	3

<b>♦60 Hz</b>																				Uni	it = N•m
Model	Speed r/min	600	500	360	300	240	200	144	120	100	72	60	50	36	30	24	20	18	15	12	10
Motor/ Gearhead	Gear Ratio	3	3.6	5	6	7.5	9	12.5	15	18	25	30	36	50	60	75	90	100	120	150	180
2RK6GN-AW2MJ 2RK6GN-AW2MU 2RK6GN-CW2MJ 2RK6GN-CW2ME 2IK6GN-SW2M	2GN□S	0.10	0.12	0.17	0.20	0.25	0.30	0.42	0.50	0.60	0.75	0.90	1.1	1.4	1.6	2.0	2.4	2.7	3	3	3

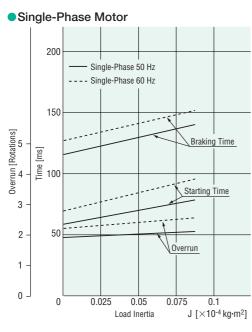
### ■Permissible Overhung Load and Permissible Thrust Load

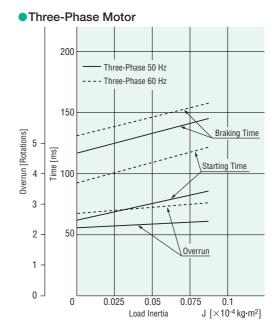
Motor (Round shaft type) → Page 107 Gearhead → Page 107

### Permissible Load Inertia J for Gearhead

→ Page 107

### ■Starting and Braking Characteristics (Reference Values)





### Dimensions (Unit = mm)

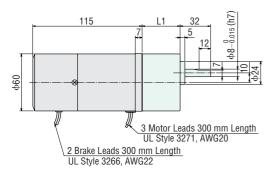
Mounting screws are included with gearheads.

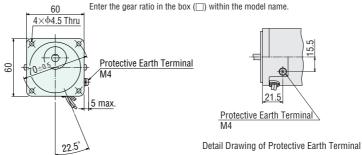
### 

Mass: Motor 0.9 kg Gearhead 0.4 kg

Motor Model	Gearhead Model	Gear Ratio	L1	CAD
2RK6GN-AW2M□ 2RK6GN-CW2M□	2GN□S	3~18	30	A462A
2IK6GN-SW2M	ZGN_3	<b>25</b> ~180	40	A462B

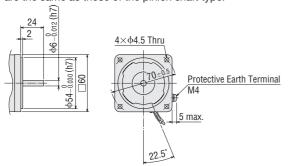
lacksquare Specify the type of the capacitor to be included by entering  $f J, \, f U$  or f E in the box (lacksquare) within the model name





### ♦ Shaft Section of Round Shaft Type

The mass and motor's dimensions (excluding the shaft section) are the same as those of the pinion shaft type.



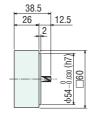
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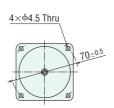
Can be connected to **GN** pinion shaft type.

### **2GN10XS**

Mass: 0.2 kg

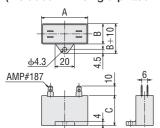
### **CAD** A003





### 

(Included with single-phase motors)

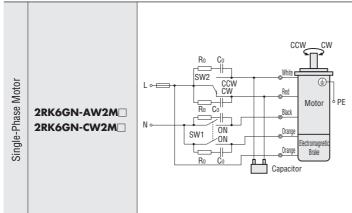


### 

Mo	del	Capacitor	Λ	В	С	Mass	Capacitor
Pinion Shaft Type	Round Shaft Type	Model	^	"	0	(g)	Cap
2RK6GN-AW2MJ	2RK6A-AW2MJ	CH45FAUL2	37	18	27	30	
2RK6GN-AW2MU	2RK6A-AW2MU	CH35FAUL2	31	17	27	25	Included
2RK6GN-CW2MJ	2RK6A-CW2MJ	CH10BFAUL	37	18	27	30	Iliciuded
2RK6GN-CW2ME	2RK6A-CW2ME	CH08BFAUL	31	17	27	20	

## Connection Diagrams

- The direction of motor rotation is as viewed from the shaft end of the motor. CW represents the clockwise direction, while CCW represents the counterclockwise direction.
- Connection diagrams are also valid for the equivalent round shaft type.
- ■Specify the type of the capacitor to be included by entering J, U or E in the box (□) within the model name.



SW1 operates both motor and electromagnetic brake action.
The motor will rotate when SW1 is switched simultaneously to ON.
When SW1 is switched simultaneously to OFF, the motor stops immediately with the electromagnetic brake and holds the load.

If you wish to release the brake while the motor is stopped, apply voltage between the two brake lead wires (orange).

#### Direction of Rotation

To rotate the motor in a clockwise (CW) direction, turn SW2 to CW. To rotate the motor in a counterclockwise (CCW) direction, turn SW2 to CCW.

0 11 1	Specifi	cations	
Switch	Single-Phase 100 VAC,	Single-Phase 200 VAC,	Note
No.	110/115 VAC Input	220/230 VAC Input	
SW1	125 VAC 3 A minimum	250 VAC 1.5 A minimum	Switched Simultaneously
SW2	(Inductive Load)	(Inductive Load)	_

2IK6GN-SW2M

L1(R)

L2(S)

R0 C0

Red

White

Horange

Grange

Electromagnetic

Brake

SW1 operates both motor and electromagnetic brake action.
The motor will rotate when SW1 is switched simultaneously to ON.
When SW1 is switched simultaneously to OFF, the motor stops immediately with the electromagnetic brake and holds the load.

If you wish to release the brake while the motor is stopped, apply voltage between the two brake lead wires (orange).

#### Direction of Rotation

To change the rotation direction, change any two connections between R, S and T.

Switch No.	Specifications	Note
SW1	250 VAC 1.5 A minimum	Switched Simultaneously
3441	(Inductive Load)	Switched Silliditalieously

PE: Protective Earth

 $\bullet$  Ro and Co indicate surge suppressor circuit. [Ro=5~200  $\Omega,$  Co=0.1~0.2  $\mu\text{F},$  200 WV  $\,$  (400 WV) ]

**EPCR1201-2** is available as an optional surge suppressor. → Page 123



# **Power Off Activated Type Electromagnetic Brake Motors**

15 W

Frame Size: **□70** mm



## Specifications

● Motor (RoHS)

This type of motor does not contain a built-in simple brake mechanism.

c <b>FU</b> °us	<b>(E</b>	
ated Speed	Capacitor	

This type of motor does not contain a balle in simple brake mechanism.											
Model		Rating Output Power Vo		Voltage	Frequency	Current	Starting Torque	Rated Torque	Rated Speed	Capacitor	
Pinion Shaft Type	Round Shaft Type		W	VAC	Hz	Α	mN∙m	mN·m	r/min	μF	
TP 3RK15GN-AW2MJ	3RK15A-AW2MJ	30	15	Single-Phase 100	50	0.40	100	125	1200	7.5	
JP 3RR I 3GIN-AW 2MJ	JKK I JA-AW ZMJ	minutes	15	Sillyle-Filase 100	60		100	105	1450	7.5	
TP 3RK15GN-AW2MU	3RK15A-AW2MU	30	15	Single-Phase 110	60	0.42	100	105	1450	6.0	
JP SKK156N-AWZMO	JKK I JA-AW ZMO	minutes	13	Single-Phase 115	00	0.41	100	103	1430	0.0	
TP 3RK15GN-CW2MJ	3RK15A-CW2MJ	30	15	Single-Phase 200	50	0.19	100	125	1200	1.8	
JP 3RR I 3GIN-CW2MJ	SKK I SA-CW ZMS	minutes	13	Siligie-Filase 200	60	0.24	100	105	1450	1.0	
				Single-Phase 220	50	0.18	100	125	1200		
TP 3RK15GN-CW2ME	RK15GN-CW2ME 3RK15A-CW2ME min		15	Siligie-Filase 220	60	0.20	100	105	1450	1.5	
IP SKK I SGIN-CW2ME			15	Single-Phase 230	50	0.19	100	125	1200		
				Jillyle-FildSe 230	60	0.20	100	105	1450		

<sup>•</sup> The J, U and E at the end of the model name indicate that the unit includes a capacitor. These letters are not listed on the motor nameplate. When the motor is approved under various safety standards, the model name on the nameplate is the approved model name.

#### Electromagnetic Brake (Power Off Activated Type)

Motor Model	Voltage VAC	Frequency Hz	Current A	Input W	Holding Brake Torque mN·m
3RK15GN-AW2MJ	Single-Phase 100	50	0.09	7	80
3RK15A-AW2MJ	Olligio i flasc 100	60	0.03	,	00
3RK15GN-AW2MU	NU Single-Phase 110		0.09	7	80
3RK15A-AW2MU	Single-Phase 115	60	0.09	,	00
3RK15GN-CW2MJ	Single-Phase 200	50	0.05	7	80
3RK15A-CW2MJ		60	0.05	,	00
	Single-Phase 220	Dhana 220 50			
3RK15GN-CW2ME	Sillyle-Filase 220	60	0.05	7	80
3RK15A-CW2ME	Single-Phase 230	50	0.05	/	OU
	Siligie-Filase 230	60			

#### Product Line

#### ● Motor (RoHS)

•	_									
Tuno	Model									
Туре	Pinion Shaft Type	Round Shaft Type								
	3RK15GN-AW2MJ	3RK15A-AW2MJ								
Lead Wire	3RK15GN-AW2MU	3RK15A-AW2MU								
Leau Wile	3RK15GN-CW2MJ	3RK15A-CW2MJ								
	3RK15GN-CW2ME	3RK15A-CW2ME								

#### Gearhead (Sold Separately) RoHS

Туре	Gearhead Model	Gear Ratio
Long Life/Low Noise/ Parallel Shaft	3GN□5	3, 3.6, 5, 6, 7.5, 9, 12.5, 15, 18, 25, 30, 36, 50, 60, 75, 90, 100, 120, 150, 180
	3GN10XS (Decima	al gearhead)

lacksquare Enter the gear ratio in the box ( $\Box$ ) within the model name.

<sup>(</sup>IP): Contains a built-in thermal protector. If a motor overheats for any reason, the thermal protector is opened and the motor stops. (The power supply to the electromagnetic brake is kept and the brake is released.) When the motor temperature drops, the thermal protector closes and the motor restarts. Be sure to turn the motor off before inspecting.

## ■Gearmotor - Torque Table

- •Gearheads and decimal gearheads are sold separately.
- ●Enter the gear ratio in the box (□) within the model name.
- •A colored background indicates gear shaft rotation in the same direction as the motor shaft, while the others rotate in the opposite direction.
- The speed is calculated by dividing the motor's synchronous speed (50 Hz: 1500 r/min, 60 Hz: 1800 r/min) by the gear ratio.

The actual speed is 2 - 20% less than the displayed value, depending on the size of the load.

■To reduce the speed beyond the gear ratio in the table, attach a decimal gearhead (gear ratio: 10) between the gearhead and the motor. In that case, the permissible torque is 5 N·m.

♦50 HZ																				UNI	it = iv·m
Model	Speed r/min	500	416	300	250	200	166	120	100	83	60	50	41	30	25	20	16	15	12.5	10	8.3
Motor/ Gearhead	Gear Ratio	3	3.6	5	6	7.5	9	12.5	15	18	25	30	36	50	60	75	90	100	120	150	180
3RK15GN-AW2MJ 3RK15GN-CW2MJ 3RK15GN-CW2ME	/ 3GN□S	0.30	0.36	0.51	0.61	0.76	0.91	1.3	1.5	1.8	2.3	2.7	3.3	4.1	5	5	5	5	5	5	5

<b>♦60 Hz</b>																				Uni	it = N•m
Model	Speed r/min	600	500	360	300	240	200	144	120	100	72	60	50	36	30	24	20	18	15	12	10
Motor/ Gearhead	Gear Ratio	3	3.6	5	6	7.5	9	12.5	15	18	25	30	36	50	60	75	90	100	120	150	180
3RK15GN-AW2MJ 3RK15GN-AW2MU 3RK15GN-CW2MJ 3RK15GN-CW2ME	/ 3GN□5	0.26	0.31	0.43	0.51	0.64	0.77	1.1	1.3	1.5	1.9	2.3	2.8	3.5	4.2	5	5	5	5	5	5

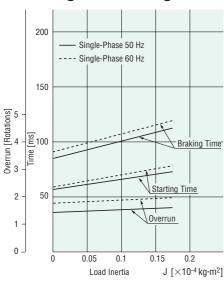
## Permissible Overhung Load and Permissible Thrust Load

Motor (Round shaft type) → Page 107 Gearhead → Page 107

## Permissible Load Inertia J for Gearhead

→ Page 107

## ■Starting and Braking Characteristics (Reference Values)



## Dimensions (Unit = mm)

Mounting screws are included with gearheads.

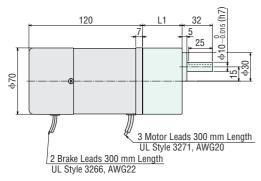
#### 

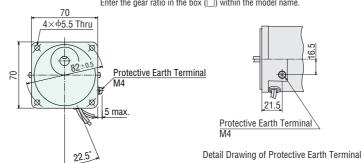
Mass: Motor 1.3 kg Gearhead 0.55 kg

Motor Model	Gearhead Model	Gear Ratio	L1	CAD
3RK15GN-AW2M■	3GN□S	3~18	32	A464A
3RK15GN-CW2M□		<b>25</b> ~180	42	A464B

● Specify the type of the capacitor to be included by entering **J**, **U** or **E** in the box (□) within

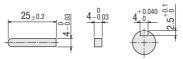
Enter the gear ratio in the box ( ) within the model name.





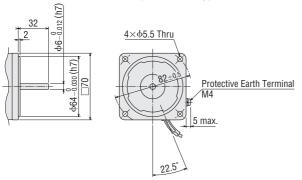
#### 

(The key is included with the gearhead)



#### ♦ Shaft Section of Round Shaft Type

The mass and motor's dimensions (excluding the shaft section) are the same as those of the pinion shaft type.

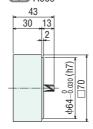


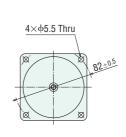
#### 

Can be connected to **GN** pinion shaft type.

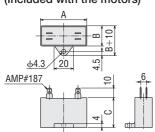
## 3GN10XS

Mass: 0.3 kg **CAD** A009





## (Included with the motors)

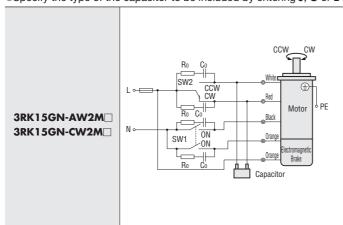


#### 

Mo Pinion Shaft Type	del Round Shaft Type	Capacitor Model	Α	В	С	Mass (g)	Capacitor Cap
Fillion Shart Type	noullu Shart Type	WIOGEI				(9)	σαρ
3RK15GN-AW2MJ	3RK15A-AW2MJ	CH75CFAUL2	48	21	31	45	
3RK15GN-AW2MU	3RK15A-AW2MU	CH60CFAUL2	38	21	31	40	Included
3RK15GN-CW2MJ	3RK15A-CW2MJ	CH18BFAUL	38	21	31	35	iliciuded
3RK15GN-CW2ME	3RK15A-CW2ME	CH15BFAUL	38	21	31	35	

## **■**Connection Diagrams

- •The direction of motor rotation is as viewed from the shaft end of the motor. CW represents the clockwise direction, while CCW represents the counterclockwise direction.
- Connection diagrams are also valid for the equivalent round shaft type.
- ■Specify the type of the capacitor to be included by entering **J**, **U** or **E** in the box (□) within the model name.



SW1 operates both motor and electromagnetic brake action.
The motor will rotate when SW1 is switched simultaneously to ON.
When SW1 is switched simultaneously to OFF, the motor stops immediately with the electromagnetic brake and holds the load.

If you wish to release the brake while the motor is stopped, apply voltage between the two brake lead wires (orange).

#### Direction of Rotation

To rotate the motor in a clockwise (CW) direction, turn SW2 to CW. To rotate the motor in a counterclockwise (CCW) direction, turn SW2 to CCW.

0 !! !	Specifi	cations	
Switch	Single-Phase 100 VAC,	Single-Phase 200 VAC,	Note
No.	110/115 VAC Input	220/230 VAC Input	
SW1	125 VAC 3 A minimum	250 VAC 1.5 A minimum	Switched Simultaneously
SW2	(Inductive Load)	(Inductive Load)	_

PE: Protective Earth

ullet Ro and Co indicate surge suppressor circuit. [Ro=5 $\sim$ 200  $\Omega$ , Co=0.1 $\sim$ 0.2  $\mu$ F, 200 WV (400 WV) ]

**EPCR1201-2** is available as an optional surge suppressor. → Page 123



## **Power Off Activated Type Electromagnetic Brake Motors**

25 W

Frame Size: **□80** mm



Right-angle gearheads (hollow shaft or solid shaft) can be combined.

Right-Angle Gearheads → Page 108





## Specifications

● Motor (RoHS)

This type of motor does not contain a built-in simple brake mechanism.

**™**us **(E** 



This type of motor does n	or contain a bane in	0	o. a	0011011101111						
Model		Rating	Output Power	Voltage	Frequency	Current	Starting Torque	Rated Torque	Rated Speed	Capacitor
Pinion Shaft Type	Round Shaft Type		W	VAC	Hz	Α	mN·m	mN·m	r/min	μF
TP 4RK25GN-AW2MJ	ADVOE A - AVAORA I	30	25	Single-Phase 100	50	0.55	160	205	1200	10
IP 4KKZJGIN-AWZMJ	4KK23A-AVV2MJ	minutes	20	Sillyle-Filase 100	60	0.64	140	170	1450	10
TP 4RK25GN-AW2MU	ADVOE A. AVAOALI	30	25	Single-Phase 110	60	0.54	140	170	1450	8.0
(F) 4KK25GN-AW2MO	4KKZ3A-AVV ZMU	minutes	25	Single-Phase 115	00	0.54	140	170	1430	0.0
		00		Single-Phase 200	50	0.27	160	205	1200	
TP 4RK25GN-CW2MJ	4RK25A-CW2MJ	30 minutes	25	Sillyle-Filase 200	60	0.34	140	170	1450	2.5
		IIIIIutes		Single-Phase 220	50	0.27	160	205	1200	
		00		Single-Phase 220	60	0.28	140	170	1450	
TP 4RK25GN-CW2ME	4RK25A-CW2ME	30 minutes	25	Cinalo Dhoos 220	50	0.25	160	205	1200	2.0
		minutes		Single-Phase 230	60	0.28	140	170	1450	
				Three Dhace 200	50	0.23	240	190	1300	
TP 4IK25GN-SW2M	AUVOE A CIMOM	0	0.5	Three-Phase 200	60	0.21	160	160	1550	
TP 4IK25GN-SW2M	4IK25A-SW2M	Continuous	25	Three-Phase 220	60	0.20	160	150	1000	_
			-	Three-Phase 230	60 -	0.21	160	150	1600	

The J, U and E at the end of the model name indicate that the unit includes a capacitor. These letters are not listed on the motor nameplate.

When the motor is approved under various safety standards, the model name on the nameplate is the approved model name.

(The power supply to the electromagnetic brake is kept and the brake is released.)

When the motor temperature drops, the thermal protector closes and the motor restarts. Be sure to turn the motor off before inspecting.

#### Electromagnetic Brake (Power Off Activated Type)

Motor Model	Voltage VAC	Frequency Hz	Current A	Input W	Holding Brake Torque mN·m
4RK25GN-AW2MJ	Single-Phase 100	50	0.09	6	100
4RK25A-AW2MJ	Sillyle-Filase 100	60	0.09	0	100
4RK25GN-AW2MU	Single-Phase 110	60	0.09	6	100
4RK25A-AW2MU	Single-Phase 115	00	0.09	0	100
ADKAECH CMAMI	Cingle Phone 200	50			
4RK25GN-CW2MJ 4RK25A-CW2MJ 4RK25GN-CW2ME 4RK25A-CW2ME	Single-Phase 200	60	0.05	7	100
	Single-Phase 220	50			
	Single-Phase 220	60			
	Single-Phase 230	50	0.05	7	100
	Siligie-Pliase 230	60			
	Cingle Phase 200	50			
4IK25GN-SW2M	Single-Phase 200	60	0.05	_	100
4IK25A-SW2M	Single-Phase 220	60	0.05	7	100
	Single-Phase 230	60			

#### Product Line

#### ● Motor (RoHS)

Model								
Pinion Shaft Type	Round Shaft Type							
4RK25GN-AW2MJ	4RK25A-AW2MJ							
4RK25GN-AW2MU	4RK25A-AW2MU							
4RK25GN-CW2MJ	4RK25A-CW2MJ							
4RK25GN-CW2ME	4RK25A-CW2ME							
4IK25GN-SW2M	4IK25A-SW2M							

#### • Gearhead/Right-Angle Gearhead (Sold Separately) RoHS

Туре	Gearhead Model	Gear Ratio							
Long Life/Low Noise/ Parallel Shaft	4GN□S	3, 3.6, 5, 6, 7.5, 9, 12.5, 15, 18, 25, 30, 36, 50, 60, 75, 90, 100, 120, 150, 180							
	4GN10XS (Decimal gearhead)								
Right-Angle/ Hollow Shaft	4GN□RH	3, 3.6, 5, 6, 7.5, 9, 12.5, 15, 18, 25, 30, 36, 50, 60, 75, 90, 100, 120, 150, 180							
Right-Angle/ Solid Shaft	4GN□RA	3, 3.6, 5, 6, 7.5, 9, 12.5, 15, 18, 25, 30, 36, 50, 60, 75, 90, 100, 120, 150, 180							

**IP**: Contains a built-in thermal protector. If a motor overheats for any reason, the thermal protector is opened and the motor stops.

## ■Gearmotor - Torque Table

- •Gearheads and decimal gearheads are sold separately.
- ●Enter the gear ratio in the box (□) within the model name.
- •A colored background indicates gear shaft rotation in the same direction as the motor shaft, while the others rotate in the opposite direction.
- The speed is calculated by dividing the motor's synchronous speed (50 Hz: 1500 r/min, 60 Hz: 1800 r/min) by the gear ratio. The actual speed is 2 20% less than the displayed value, depending on the size of the load.
- ■To reduce the speed beyond the gear ratio in the table, attach a decimal gearhead (gear ratio: 10) between the gearhead and the motor. In that case, the permissible torque is 8 N·m. When a gearhead of 1/25~1/36 is connected, the value for permissible torque is 6 N·m.

<>50 Hz																				Unit	: = N•m
Model	Speed r/min	500	416	300	250	200	166	120	100	83	60	50	41	30	25	20	16	15	12.5	10	8.3
Motor/ Gearhead	Gear Ratio	3	3.6	5	6	7.5	9	12.5	15	18	25	30	36	50	60	75	90	100	120	150	180
4RK25GN-AW2MJ 4RK25GN-CW2MJ 4RK25GN-CW2ME	∕ 4GN□S	0.50	0.60	0.83	1.0	1.2	1.5	2.1	2.5	3.0	3.7	4.5	5.4	6.8	8	8	8	8	8	8	8
4IK25GN-SW2M	/ 4GN□S	0.46	0.55	0.77	0.92	1.2	1.4	1.9	2.3	2.8	3.5	4.2	5.0	6.3	7.5	8	8	8	8	8	8

<b>♦60 Hz</b>																				Uni	it = N·m
Model	Speed r/min	600	500	360	300	240	200	144	120	100	72	60	50	36	30	24	20	18	15	12	10
Motor/ Gearhead	Gear Ratio	3	3.6	5	6	7.5	9	12.5	15	18	25	30	36	50	60	75	90	100	120	150	180
4RK25GN-AW2MJ 4RK25GN-AW2MU 4RK25GN-CW2MJ 4RK25GN-CW2ME	/ 4GN□S	0.41	0.50	0.69	0.83	1.0	1.2	1.7	2.1	2.5	3.1	3.7	4.5	5.6	6.7	8	8	8	8	8	8
4IK25GN-SW2M (200 VAC)	/ 4GN□S	0.39	0.47	0.65	0.78	0.97	1.2	1.6	1.9	2.3	2.9	3.5	4.2	5.3	6.3	7.9	8	8	8	8	8
4IK25GN-SW2M (220/230 VAC)	/ 4GN□S	0.36	0.44	0.61	0.73	0.91	1.1	1.5	1.8	2.2	2.7	3.3	3.9	5.0	5.9	7.4	8	8	8	8	8

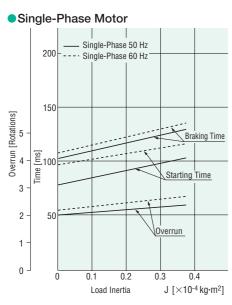
## Permissible Overhung Load and Permissible Thrust Load

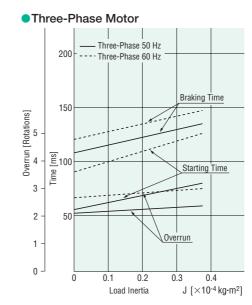
Motor (Round shaft type) → Page 107 Gearhead → Page 107

#### Permissible Load Inertia J for Gearhead

→ Page 107

## ■ Starting and Braking Characteristics (Reference Values)





## Dimensions (Unit = mm)

Mounting screws are included with gearheads.

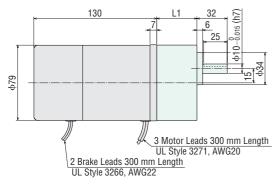
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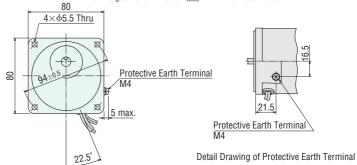
Mass: Motor 2.0 kg Gearhead 0.65 kg

Motor Model	Gearhead Model	Gear Ratio	L1	CAD
4RK25GN-AW2M□ 4RK25GN-CW2M□	4GN⊟S	3~18	32	A466A
4IK25GN-SW2M	4GN_5	<b>25</b> ~180	42.5	A466B

lacksquare Specify the type of the capacitor to be included by entering  ${f J}, {f U}$  or  ${f E}$  in the box ( ${lacksquare}$ ) within the model name.

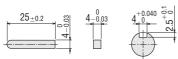
Enter the gear ratio in the box  $(\Box)$  within the model name.





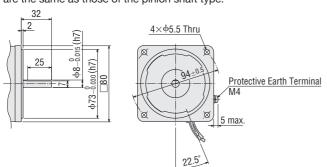
## $\diamondsuit$ Key and Key Slot

(The key is included with the gearhead)



#### ♦ Shaft Section of Round Shaft Type

The mass and motor's dimensions (excluding the shaft section) are the same as those of the pinion shaft type.



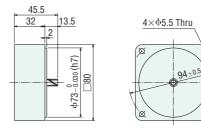
#### 

Can be connected to **GN** pinion shaft type.

#### 4GN10XS

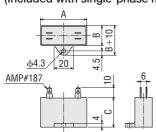
Mass: 0.4 kg

**CAD** A013



#### 

(Included with single-phase motors)

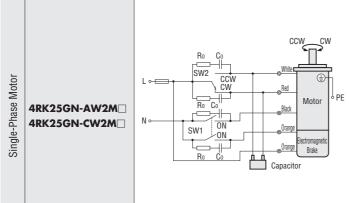


#### 

Mo Pinion Shaft Type	odel Round Shaft Type	Capacitor Model	Α	В	С	Mass (g)	Capacitor Cap
4RK25GN-AW2MJ	4RK25A-AW2MJ	CH100CFAUL2	58	21	31	50	
4RK25GN-AW2MU	4RK25A-AW2MU	CH80CFAUL2	48	21	31	45	Included
4RK25GN-CW2MJ	4RK25A-CW2MJ	CH25BFAUL	48	21	31	45	inciuaea
4RK25GN-CW2ME	4RK25A-CW2ME	CH20BFAUL	48	19	29	35	

## Connection Diagrams

- The direction of motor rotation is as viewed from the shaft end of the motor. CW represents the clockwise direction, while CCW represents the counterclockwise direction.
- Connection diagrams are also valid for the equivalent round shaft type.
- Specify the type of the capacitor to be included by entering **J**, **U** or **E** in the box (□) within the model name.



SW1 operates both motor and electromagnetic brake action. The motor will rotate when SW1 is switched simultaneously to ON. When SW1 is switched simultaneously to OFF, the motor stops immediately with the electromagnetic brake and holds the load.

If you wish to release the brake while the motor is stopped, apply voltage between the two brake lead wires (orange).

#### Direction of Rotation

To rotate the motor in a clockwise (CW) direction, turn SW2 to CW. To rotate the motor in a counterclockwise (CCW) direction, turn SW2 to CCW.

0	Specifi	cations	
Switch	Single-Phase 100 VAC,	Single-Phase 200 VAC,	Note
No.	110/115 VAC Input	220/230 VAC Input	
SW1	125 VAC 3 A minimum	250 VAC 1.5 A minimum	Switched Simultaneously
SW2	(Inductive Load)	(Inductive Load)	_

4IK25GN-SW2M

L1(R)

L2(S)

Ro Co

Red

White

Motor

Ro Co

Orange

Electromagnetic

Brake

SW1 operates both motor and electromagnetic brake action.
The motor will rotate when SW1 is switched simultaneously to ON.
When SW1 is switched simultaneously to OFF, the motor stops immediately with the electromagnetic brake and holds the load.

If you wish to release the brake while the motor is stopped, apply voltage between the two brake lead wires (orange).

#### Direction of Rotation

To change the rotation direction, change any two connections between R, S and T.

Switch No.	Specifications	Note
SW1	250 VAC 1.5 A minimum (Inductive Load)	Switched Simultaneously

PE: Protective Earth

ullet Ro and Co indicate surge suppressor circuit. [Ro=5 $\sim$ 200  $\Omega$ , Co=0.1 $\sim$ 0.2  $\mu$ F, 200 WV (400 WV) ]

EPCR1201-2 is available as an optional surge suppressor. → Page 123



## **Power Off Activated Type Electromagnetic Brake Motors**

40 W

Frame Size: **□90** mm



Right-angle gearheads (hollow shaft or solid shaft) can be combined.

Right-Angle Gearheads → Page 108





## Specifications

● Motor (RoHS)

This type of motor does not contain a built-in simple brake mechanism.

**₩** (10 €)



Node    Rating   Output   Power   W   Voltage   Frequency   Current   Starting   Torque   mN·m   m		
TP         5RK40GN-AW2MJ         5RK40A-AW2MJ         30 minutes         40 minutes         Single-Phase 100 minutes         50 0.85 300 315 1250 270 1450           TP         5RK40GN-AW2MJ         5RK40A-AW2MJ minutes         40 minutes         Single-Phase 110 2 200 270 270 270 270 270         60 0.81 260 270 270 270 270 270         1450 270 270 270 270 270 270 270 270 270 27	Capacitor	
TP         5RK40GN-AW2MJ         5RK40A-AW2MJ         40         Single-Phase 100         60         1.04         260         270         1450           TP         5RK40GN-AW2MJ         5RK40A-AW2MJ         30 minutes         40 minutes         Single-Phase 110 Single-Phase 115         60         0.81         260         270         1450           TP         5RK40GN-CW2MJ         5RK40A-CW2MJ         30 single-Phase 200         50 single-Phase 200         60 single-Phase 200         60 single-Phase 200         60 single-Phase 200         60 single-Phase 200         260 single-Phase 200         260 single-Phase 200	μF	
TP   5RK40GN-AW2MU   5RK40A-AW2MU   30   Minutes   40   Single-Phase 110   50   0.81   260   270   1450	16	
TP 5RK40GN-AW2MU 5RK40A-AW2MU minutes 40 Single-Phase 115 60 0.81 260 270 1450  Single-Phase 115 60 0.81 260 270 1450  Single-Phase 200 50 0.40 270 315 1250  Single-Phase 200 60 0.51 260 260 1500	10	
Minutes   Single-Phase 115   Single-Phase 115   Single-Phase 200   50   0.40   270   315   1250	12	
TP) 5RK40GN-CW2M1 5RK40A-CW2M1 30 40 Single-Phase 200 60 0.51 260 260 1500	12	
(TP) 5RK40GN-CW2MJ 5RK40A-CW2MJ		
	4.0	
Single-Phase 220 50 0.40 270 315 1250		
Single-Phase 220 60 0.43 260 260 1500		
TP 5RK40GN-CW2ME	3.5	
minutes   Single-Phase 230   60   0.43   260   260   1500		
Three-Phase 200 50 0.32 400 300 1300		
Three-Phase 220   0.30	_	
Three-Phase 230 60 0.31 260 260 1600		

- The J, U and E at the end of the model name indicate that the unit includes a capacitor. These letters are not listed on the motor nameplate. When the motor is approved under various safety standards, the model name on the nameplate is the approved model name.
- (I): Contains a built-in thermal protector. If a motor overheats for any reason, the thermal protector is opened and the motor stops. (The power supply to the electromagnetic brake is kept and the brake is released.) When the motor temperature drops, the thermal protector closes and the motor restarts. Be sure to turn the motor off before inspecting.

#### Electromagnetic Brake (Power Off Activated Type)

Motor Model	Voltage VAC	Frequency Hz	Current A	Input W	Holding Brake Torque mN·m
5RK40GN-AW2MJ	Single-Phase 100	50	0.09	6	200
5RK40A-AW2MJ	Sillyle-Filase 100	60	0.09	0	200
5RK40GN-AW2MU	Single-Phase 110	60	0.09	6	200
5RK40A-AW2MU	Single-Phase 115	00	0.09	0	200
5RK40GN-CW2MJ	Single-Phase 200	50			
5RK40GN-CW2MJ	Sillyle-Filase 200	60	0.05	7	200
SKR4UA-CW ZNIJ	Single-Phase 220	50			
5RK40GN-CW2ME	Single-Phase 220	60			
5RK40GN-CW2ME	Single-Phase 230	50	0.05	7	200
JKKTOA-CW ZML	Sillyle-Filase 250	60			
	Single-Phase 200	50			
5IK40GN-SW2M	Sillyle-Filase 200	60	0.05	7	200
5IK40A-SW2M	Single-Phase 220	60	0.05	'	200
	Single-Phase 230	00			

#### Product Line

● Motor (RoHS)

Model						
Pinion Shaft Type	Round Shaft Type					
5RK40GN-AW2MJ	5RK40A-AW2MJ					
5RK40GN-AW2MU	5RK40A-AW2MU					
5RK40GN-CW2MJ	5RK40A-CW2MJ					
5RK40GN-CW2ME	5RK40A-CW2ME					
5IK40GN-SW2M	5IK40A-SW2M					

#### • Gearhead/Right-Angle Gearhead (Sold Separately) RoHS

Туре	Gearhead Model	Gear Ratio					
Long Life/Low Noise/ Parallel Shaft	5GN□S	3, 3.6, 5, 6, 7.5, 9, 12.5, 15, 18, 25, 30, 36, 50, 60, 75, 90, 100, 120, 150, 180					
	5GN10XS (Decima	Decimal gearhead)					
Right-Angle/ Hollow Shaft	5GN□RH	3, 3.6, 5, 6, 7.5, 9, 12.5, 15, 18, 25, 30, 36, 50, 60, 75, 90, 100, 120, 150, 180					
Right-Angle/ Solid Shaft	5GN□RA	3, 3.6, 5, 6, 7.5, 9, 12.5, 15, 18, 25, 30, 36, 50, 60, 75, 90, 100, 120, 150, 180					

## ■Gearmotor - Torque Table

- •Gearheads and decimal gearheads are sold separately.
- ●Enter the gear ratio in the box (□) within the model name.
- •A colored background indicates gear shaft rotation in the same direction as the motor shaft, while the others rotate in the opposite direction.
- The speed is calculated by dividing the motor's synchronous speed (50 Hz: 1500 r/min, 60 Hz: 1800 r/min) by the gear ratio.
- The actual speed is 2 20% less than the displayed value, depending on the size of the load.

To reduce the speed beyond the gear ratio in the table, attach a decimal gearhead (gear ratio: 10) between the gearhead and the motor. In that case, the permissible torque is 10 N·m.

<b>⇔</b> 50 Hz																				Uni	t = N•m
Model	Speed r/min	500	416	300	250	200	166	120	100	83	60	50	41	30	25	20	16	15	12.5	10	8.3
Motor/ Gearhead	Gear Ratio	3	3.6	5	6	7.5	9	12.5	15	18	25	30	36	50	60	75	90	100	120	150	180
5RK40GN-AW2MJ 5RK40GN-CW2MJ 5RK40GN-CW2ME	/ 5GN□S	0.77	0.92	1.3	1.5	1.9	2.3	3.2	3.8	4.6	5.7	6.9	8.3	10	10	10	10	10	10	10	10
5IK40GN-SW2M	/ 5GN□S	0.73	0.87	1.2	1.5	1.8	2.2	3.0	3.6	4.4	5.5	6.6	7.9	9.9	10	10	10	10	10	10	10

<b>♦60 Hz</b>																				Uni	it = N·m
Model	Speed r/min	600	500	360	300	240	200	144	120	100	72	60	50	36	30	24	20	18	15	12	10
Motor/ Gearhead	Gear Ratio	3	3.6	5	6	7.5	9	12.5	15	18	25	30	36	50	60	75	90	100	120	150	180
5RK40GN-AW2MJ 5RK40GN-AW2MU	/ 5GN□S	0.66	0.79	1.1	1.3	1.6	2.0	2.7	3.3	3.9	4.9	5.9	7.1	8.9	10	10	10	10	10	10	10
5RK40GN-CW2MJ 5RK40GN-CW2ME 5IK40GN-SW2M	/ 5GN□S	0.63	0.76	1.1	1.3	1.6	1.9	2.6	3.2	3.8	4.7	5.7	6.8	8.6	10	10	10	10	10	10	10

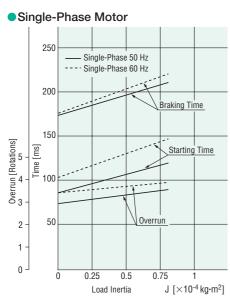
## ■Permissible Overhung Load and Permissible Thrust Load

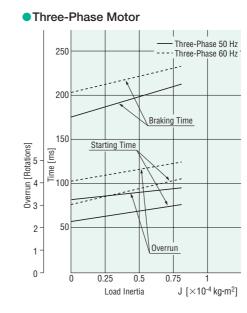
Motor (Round shaft type) → Page 107 Gearhead → Page 107

#### Permissible Load Inertia J for Gearhead

→ Page 107

## ■Starting and Braking Characteristics (Reference Values)





## Dimensions (Unit = mm)

Mounting screws are included with gearheads.

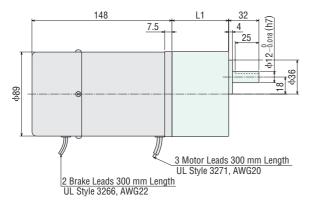
#### 

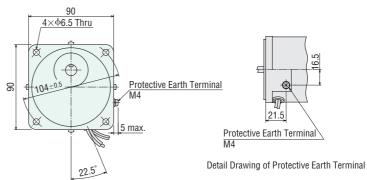
Mass: Motor 2.8 kg Gearhead 1.5 kg

Motor Model	Gearhead Model	Gear Ratio	L1	CAD
5RK40GN-AW2M 5RK40GN-CW2M	5GN□S	3~18	42	A468A
5IK40GN-SW2M	SGN_5	<b>25</b> ~180	60	A468B

● Specify the type of the capacitor to be included by entering **J**, **U** or **E** in the box (□) within the model name.

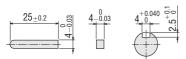
Enter the gear ratio in the box  $(\Box)$  within the model name.





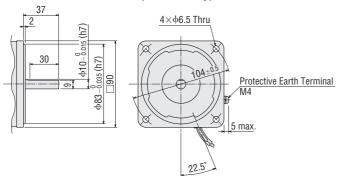
#### 

(The key is included with the gearhead)



#### ♦ Shaft Section of Round Shaft Type

The mass and motor's dimensions (excluding the shaft section) are the same as those of the pinion shaft type.

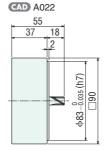


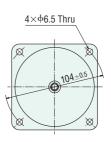
#### 

Can be connected to **GN** pinion shaft type.

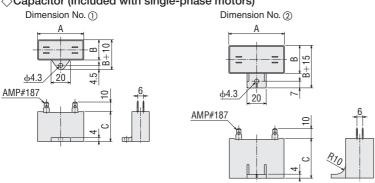
#### **5GN10XS**

Mass: 0.6 kg





#### 

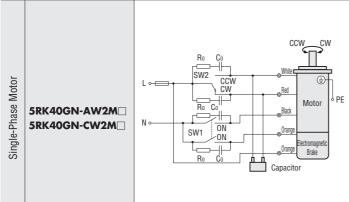


#### 

v '	, ,							
Mo	odel	Capacitor		В	C	Mass	Dimension	Capacitor
Pinion Shaft Type	Round Shaft Type	Model	A	D	U	(g)	No.	Cap
5RK40GN-AW2MJ	5RK40A-AW2MJ	CH160CFAUL2	58	23.5	37	75	2	
5RK40GN-AW2MU	5RK40A-AW2MU	CH120CFAUL2	58	22	35	60	1)	Included
5RK40GN-CW2MJ	5RK40A-CW2MJ	CH40BFAUL	58	23.5	37	70	2	included
5RK40GN-CW2ME	5RK40A-CW2ME	CH35BFAUL	58	22	35	55	(1)	

## Connection Diagrams

- The direction of motor rotation is as viewed from the shaft end of the motor. CW represents the clockwise direction, while CCW represents the counterclockwise direction.
- •Connection diagrams are also valid for the equivalent round shaft type.
- ●Specify the type of the capacitor to be included by entering **J**, **U** or **E** in the box (□) within the model name.



SW1 operates both motor and electromagnetic brake action.
The motor will rotate when SW1 is switched simultaneously to ON.
When SW1 is switched simultaneously to OFF, the motor stops immediately with the electromagnetic brake and holds the load.

If you wish to release the brake while the motor is stopped, apply voltage between the two brake lead wires (orange).

#### Direction of Rotation

To rotate the motor in a clockwise (CW) direction, turn SW2 to CW.

To rotate the motor in a counterclockwise (CCW) direction, turn SW2 to CCW.

	Specifi	cations	
Switch	Single-Phase 100 VAC,	Single-Phase 200 VAC,	Note
No.	110/115 VAC Input	220/230 VAC Input	
SW1	125 VAC 5 A minimum	250 VAC 5 A minimum	Switched Simultaneously
SW2	(Inductive Load)	(Inductive Load)	_

SIK40GN-SW2M

L1(R)

L2(S)

R0 C0

Red

White

Motor

SW1

Orange Electromagnetic
Brake

SW1 operates both motor and electromagnetic brake action.
The motor will rotate when SW1 is switched simultaneously to ON.
When SW1 is switched simultaneously to OFF, the motor stops immediately with the electromagnetic brake and holds the load.

If you wish to release the brake while the motor is stopped, apply voltage between the two brake lead wires (orange).

#### Direction of Rotation

To change the rotation direction, change any two connections between R, S and T.

Switch No.	Specifications	Note
SW1	250 VAC 5 A minimum	Switched Simultaneously
	(Inductive Load)	

PE: Protective Earth

 $\bullet$  Ro and Co indicate surge suppressor circuit. [Ro=5  $\sim$  200  $\Omega,$  Co=0.1  $\sim$  0.2  $\mu\text{F},$  200 WV (400 WV) ]

EPCR1201-2 is available as an optional surge suppressor. → Page 123



## **Power Off Activated Type Electromagnetic Brake Motors**

# **60 W**

Frame Size: **□90** mm



Right-angle gearheads (hollow shaft or solid shaft) can be combined.

Right-Angle Gearheads → Page 108





## Specifications

● Motor (RoHS)

This type of motor does not contain a built-in simple brake mechanism.

	, ,											
	Model		Rating	Output Power	Voltage	Frequency	Current	Starting Torque	Rated Torque	Rated Speed	Capacitor	
	Pinion Shaft Type	Round Shaft Type		W	VAC	Hz	Α	mN·m	mN·m	r/min	μF	
(TP)	5RK60GE-AW2MJ	5RK60A-AW2MJ	30	60	Single-Phase 100	50	1.30	470	490	1200	25	
	SKROUGE-AWZMJ	SKKOUA-AWZMIJ	minutes	00	Siligie-i liase 100	60	1.50	380	405	1450	23	
(TP)	5RK60GE-AW2MU	5RK60A-AW2MU	30	60	Single-Phase 110	60	1.24	380	405	1450	20	
(IP)	SKKOUGE-AW ZMU	SKKOUA-AWZMU	minutes	00	Single-Phase 115	00	1.24	300	403	1430	20	
			30		Single-Phase 200	50	0.61	450	490	1200	6.0	
TP	5RK60GE-CW2MJ	5RK60A-CW2MJ	minutes	60	Sillyle-Filase 200	60	0.74	380	405	1450		
			IIIIIutes		Single-Phase 220	50	0.61	470	490	1200		
			00		Single-Phase 220	60	0.61	380	405	1450		
TP	5RK60GE-CW2ME	5RK60A-CW2ME	30 minutes	60	Single-Phase 230	50	0.59	470	490	1200	5.0	
			IIIIIutes		Siligie-Filase 230	60	0.61	380	405	1450		
					Three-Phase 200	50	0.50	600	450	1300		
(TP)	5IK60GE-SW2M	5IK60A-SW2M	Continuous	Continuous CO	Tillee-Filase 200	60	0.43	500	380	1550		
(IP)	SINOUGE-SW ZM	5IK60A-SW2M Continuous 60		Continuous 60 Three-Pha	Three-Phase 220	- 60	0.45	500	380	1600	_	
					Three-Phase 230	00	0.46	500	300	1000		

<sup>•</sup> The J, U and E at the end of the model name indicate that the unit includes a capacitor. These letters are not listed on the motor nameplate. When the motor is approved under various safety standards, the model name on the nameplate is the approved model name.

When the motor temperature drops, the thermal protector closes and the motor restarts. Be sure to turn the motor off before inspecting.

#### Electromagnetic Brake (Power Off Activated Type)

Motor Model	Voltage VAC	Frequency Hz	Current A	Input W	Holding Brake Torque mN·m		
5RK60GE-AW2MJ	Single-Phase 100	50	0.13	10	500		
5RK60A-AW2MJ	Siligle-Filase 100	60	0.13	10	300		
5RK60GE-AW2MU	Single-Phase 110	60	0.13	10	500		
5RK60A-AW2MU	Single-Phase 115	00	0.13	10	300		
EDV40CE CWOM	Single-Phase 200	50					
5RK60GE-CW2MJ 5RK60A-CW2MJ	Siligie-Filase 200	60	0.07	10	500		
JRROUA-CW ZMJ	Single-Phase 220	50					
5RK60GE-CW2ME	Single-Phase 220	60					
5RK60GE-CW2ME	Single-Phase 230	50	0.07	10	500		
JKKOOA-CW ZML	Siligie-Filase 230	60					
	Single-Phase 200	50					
5IK60GE-SW2M	Siligie-Pliase 200	60	0.07	10	500		
5IK60A-SW2M	Single-Phase 220	60	0.07	10	300		
	Single-Phase 230	00					

#### Product Line

#### ● Motor (RoHS)

Model						
Pinion Shaft Type	Round Shaft Type					
5RK60GE-AW2MJ	5RK60A-AW2MJ					
5RK60GE-AW2MU	5RK60A-AW2MU					
5RK60GE-CW2MJ	5RK60A-CW2MJ					
5RK60GE-CW2ME	5RK60A-CW2ME					
5IK60GE-SW2M	5IK60A-SW2M					

#### • Gearhead/Right-Angle Gearhead (Sold Separately) RoHS

Туре	Gearhead Model	Gear Ratio
Long Life/ Parallel Shaft	5GE□S	3, 3.6, 5, 6, 7.5, 9, 12.5, 15, 18, 25, 30, 36, 50, 60, 75, 90, 100, 120, 150, 180
	5GE10XS (Decimal	l gearhead)
Right-Angle/ Hollow Shaft	5GE□RH	3, 3.6, 5, 6, 7.5, 9, 12.5, 15, 18, 25, 30, 36, 50, 60, 75, 90, 100, 120, 150, 180
Right-Angle/ Solid Shaft	5GE□RA	3, 3.6, 5, 6, 7.5, 9, 12.5, 15, 18, 25, 30, 36, 50, 60, 75, 90, 100, 120, 150, 180

<sup>(</sup>TP): Contains a built-in thermal protector. If a motor overheats for any reason, the thermal protector is opened and the motor stops. (The power supply to the electromagnetic brake is kept and the brake is released.)

## ■Gearmotor - Torque Table

- •Gearheads and decimal gearheads are sold separately.
- ●Enter the gear ratio in the box (□) within the model name.
- •A colored background indicates gear shaft rotation in the same direction as the motor shaft, while the others rotate in the opposite direction.
- The speed is calculated by dividing the motor's synchronous speed (50 Hz: 1500 r/min, 60 Hz: 1800 r/min) by the gear ratio.

The actual speed is 2 - 20% less than the displayed value, depending on the size of the load.

■To reduce the speed beyond the gear ratio in the table, attach a decimal gearhead (gear ratio: 10) between the gearhead and the motor. In that case, the permissible torque is 20 N·m.

♦ 50 Hz																				Uni	t = N·m
Model	Speed r/min	500	416	300	250	200	166	120	100	83	60	50	41	30	25	20	16	15	12.5	10	8.3
Motor/ Gearhead	Gear Ratio	3	3.6	5	6	7.5	9	12.5	15	18	25	30	36	50	60	75	90	100	120	150	180
5RK60GE-AW2MJ 5RK60GE-CW2MJ 5RK60GE-CW2ME	<b>5GE</b> □S	1.2	1.4	2.0	2.4	3.0	3.6	4.5	5.4	6.4	8.1	9.7	11.6	16.2	19.4	20	20	20	20	20	20
5IK60GE-SW2M	/ 5GE□S	1.1	1.3	1.8	2.2	2.7	3.3	4.1	4.9	5.9	7.4	8.9	10.7	14.9	17.8	19.9	20	20	20	20	20

<b>♦60 Hz</b>																				Uni	t = N·m
Model	Speed r/min	600	500	360	300	240	200	144	120	100	72	60	50	36	30	24	20	18	15	12	10
Motor/ Gearhead	Gear Ratio	3	3.6	5	6	7.5	9	12.5	15	18	25	30	36	50	60	75	90	100	120	150	180
5RK60GE-AW2MJ 5RK60GE-AW2MU 5RK60GE-CW2MJ 5RK60GE-CW2ME	<b>5GE</b> □S	0.98	1.2	1.6	2.0	2.5	3.0	3.7	4.4	5.3	6.7	8.0	9.6	13.4	16.0	17.9	20	20	20	20	20
5IK60GE-SW2M	5GE□S	0.92	1.1	1.5	1.8	2.3	2.8	3.5	4.2	5.0	6.3	7.5	9.0	12.5	15.0	16.8	20	20	20	20	20

## ■Permissible Overhung Load and Permissible Thrust Load

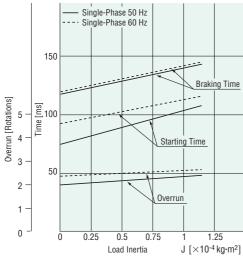
Motor (Round shaft type) → Page 107 Gearhead → Page 107

#### Permissible Load Inertia J for Gearhead

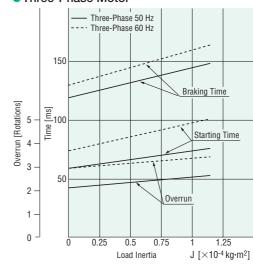
→ Page 107

## Starting and Braking Characteristics (Reference Values)





## Three-Phase Motor



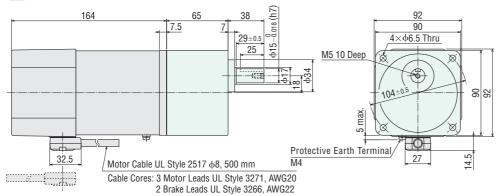
## Dimensions (Unit = mm)

Mounting screws are included with gearheads.

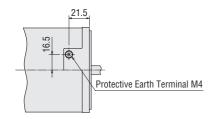
#### 

Mass: Motor 3.4 kg Gearhead 1.5 kg

**CAD** A470

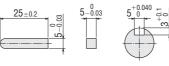


• Cable direction can be switched to the opposite direction.



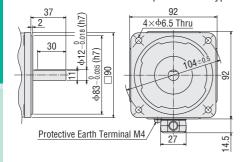
Detail Drawing of Protective Earth Terminal

## $\diamondsuit \mbox{Key}$ and $\mbox{Key}$ Slot (The key is included with the gearhead)



#### ♦ Shaft Section of Round Shaft Type

The mass and motor's dimensions (excluding the shaft section) are the same as those of the pinion shaft type.



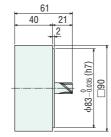
## 

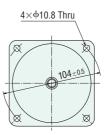
Can be connected to  $\boldsymbol{GE}$  pinion shaft type.

#### 5GE10XS

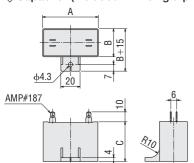
Mass: 0.6 kg

**CAD** A029





#### 

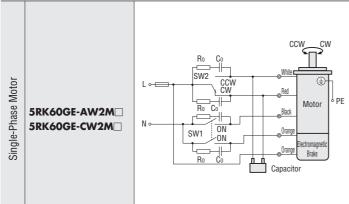


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Mo	del	Capacitor	Α	В	C	Mass	Capacitor
Pinion Shaft Type	Round Shaft Type	Model	A	Б	U	(g)	Cap
5RK60GE-AW2MJ	5RK60A-AW2MJ	CH250CFAUL2	58	35	50	140	
5RK60GE-AW2MU	5RK60A-AW2MU	CH200CFAUL2	58	29	41	95	Included
5RK60GE-CW2MJ	5RK60A-CW2MJ	CH60BFAUL	58	29	41	85	IIIciuueu
5RK60GE-CW2ME	5RK60A-CW2ME	CH50BFAUL	58	29	41	85	

## Connection Diagrams

- The direction of motor rotation is as viewed from the shaft end of the motor. CW represents the clockwise direction, while CCW represents the counterclockwise direction.
- Connection diagrams are also valid for the equivalent round shaft type.
- ■Specify the type of the capacitor to be included by entering **J**, **U** or **E** in the box (□) within the model name.



SW1 operates both motor and electromagnetic brake action. The motor will rotate when SW1 is switched simultaneously to ON. When SW1 is switched simultaneously to OFF, the motor stops immediately with the electromagnetic brake and holds the load.

If you wish to release the brake while the motor is stopped, apply voltage between the two brake lead wires (orange).

#### Direction of Rotation

To rotate the motor in a clockwise (CW) direction, turn SW2 to CW. To rotate the motor in a counterclockwise (CCW) direction, turn SW2 to CCW.

0	Specifi	cations	
Switch	Single-Phase 100 VAC,	Single-Phase 200 VAC,	Note
No.	110/115 VAC Input	220/230 VAC Input	
SW1	125 VAC 5 A minimum	250 VAC 5 A minimum	Switched Simultaneously
SW2	(Inductive Load)	(Inductive Load)	_

5IK60GE-SW2M

L1(R)

L2(S)

White Motor Orange Electromagnetic Brake

SW1 operates both motor and electromagnetic brake action.
The motor will rotate when SW1 is switched simultaneously to ON.
When SW1 is switched simultaneously to OFF, the motor stops immediately with the electromagnetic brake and holds the load.

If you wish to release the brake while the motor is stopped, apply voltage between the two brake lead wires (orange).

#### Direction of Rotation

To change the rotation direction, change any two connections between R, S and T.

Switch No.	Specifications	Note
SW1	250 VAC 5 A minimum	Switched Simultaneously
- SVV I	(Inductive Load)	Switched Simulaneously

PF: Protective Farth

 $\bullet$  Ro and Co indicate surge suppressor circuit. [Ro=5  $\sim$  200  $\Omega,$  Co=0.1  $\sim$  0.2  $\mu\text{F},$  200 WV  $\,$  (400 WV) ]

**EPCR1201-2** is available as an optional surge suppressor. → Page 123

15 W



# **Power Off Activated Type Electromagnetic Brake Motors**

# 90 W

Frame Size: **□90** mm



Right-angle gearheads (hollow shaft or solid shaft) can be combined.

Right-Angle Gearheads → Page 108





## Specifications

● Motor (RoHS)

This type of motor does not contain a built-in simple brake mechanism

**AU**us @ **( (** 

this type of motor does n	iot contain a built-ii	Simple	Diake III	echanism.					C US	
Model		Rating	Output Power	Voltage	Frequency	Current	Starting Torque	Rated Torque	Rated Speed	Capacitor
Pinion Shaft Type	Round Shaft Type		W	VAC	Hz	Α	mN∙m	mN·m	r/min	μF
TP 5RK90GE-AW2MJ	5RK90A-AW2MJ	30	90	Single-Phase 100	50	1.78	630	700	1250	35
JP SKR90GE-AWZINS	JKK70A-AVVZNIJ	minutes	30	Single-i nase roo	60	2.10	590	585	1500	
TP 5RK90GE-AW2MU	5RK90A-AW2MU	30	90	Single-Phase 110	60	1.81	590	585	1500	30
JP SRR90GE-AWZMO	JKK90A-AW ZMU	minutes	90	Single-Phase 115	00	1.01	390	363	1300	30
		00		Single-Phase 200	50	0.88	600	730	1200	
TP 5RK90GE-CW2MJ	5RK90A-CW2MJ	30 minutes	90	Sillyle-Filase 200	60	1.08	590	605	1450	8.0
		IIIIIutes		Single-Phase 220	50	0.83	600	730	1200	
		00		Single-Phase 220	60	0.96	590	605	1450	
TP 5RK90GE-CW2ME	5RK90A-CW2ME	30 minutes	90	Cinala Dhaga 220	50	0.82	600	730	1200	7.0
		IIIIIutes		Single-Phase 230	60	0.96	590	605	1450	
				Three Dhage 200	50	0.64	850	680	1300	
TR FIVOCCE SWOM	0GE-SW2M 5IK90A-SW2M	0	00	Three-Phase 200	60	0.59	700	570	1550	
TP 5IK90GE-SW2M		Continuous	90	Three-Phase 220	60	0.60	700	F70	1000	_
				Three-Phase 230	60	0.61	700	570	1600	

<sup>•</sup> The J, U and E at the end of the model name indicate that the unit includes a capacitor. These letters are not listed on the motor nameplate.
When the motor is approved under various safety standards, the model name on the nameplate is the approved model name.

#### Electromagnetic Brake (Power Off Activated Type)

•	•		. ,		
Motor Model	Voltage VAC	Frequency Hz	Current A	Input W	Holding Brake Torque mN·m
5RK90GE-AW2MJ	Single-Phase 100	50	0.13	10	500
5RK90A-AW2MJ	Olligio i flasc 100	60	0.10	10	000
5RK90GE-AW2MU	Single-Phase 110	60	0.13	10	500
5RK90A-AW2MU	Single-Phase 115	00	0.13	10	500
	Single-Phase 200	50			
5RK90GE-CW2MJ 5RK90A-CW2MJ	Sillyle-Filase 200	60	0.07	10	500
JRR90A-CW ZMJ	Single-Phase 220	50			
EDICOGOE GIAGOLIE	Single-Phase 220	60			
5RK90GE-CW2ME 5RK90A-CW2ME	Cinala Dhaga 220	50	0.07	10	500
SKK9UA-CW ZME	Single-Phase 230	60			
	Cingle Dhose 200	50			
5IK90GE-SW2M	Single-Phase 200	60	0.07	10	500
5IK90A-SW2M	Single-Phase 220	60	0.07	10	500
	Single-Phase 230	60			

<sup>(</sup>TP): Contains a built-in thermal protector. If a motor overheats for any reason, the thermal protector is opened and the motor stops.

(The power supply to the electromagnetic brake is kept and the brake is released.)

When the motor temperature drops, the thermal protector closes and the motor restarts. Be sure to turn the motor off before inspecting.

#### Product Line

#### ■ Motor (RoHS)

Mo	del
Pinion Shaft Type	Round Shaft Type
5RK90GE-AW2MJ	5RK90A-AW2MJ
5RK90GE-AW2MU	5RK90A-AW2MU
5RK90GE-CW2MJ	5RK90A-CW2MJ
5RK90GE-CW2ME	5RK90A-CW2ME
5IK90GE-SW2M	5IK90A-SW2M

#### • Gearhead/Right-Angle Gearhead (Sold Separately) RoHS

Type	Gearhead Model	Gear Ratio
Long Life/ Parallel Shaft	5GE□S	3, 3.6, 5, 6, 7.5, 9, 12.5, 15, 18, 25, 30, 36, 50, 60, 75, 90, 100, 120, 150, 180
	5GE10XS (Decima	gearhead)
Right-Angle/ Hollow Shaft	5GE□RH	3, 3.6, 5, 6, 7.5, 9, 12.5, 15, 18, 25, 30, 36, 50, 60, 75, 90, 100, 120, 150, 180
Right-Angle/ Solid Shaft	5GE□RA	3, 3.6, 5, 6, 7.5, 9, 12.5, 15, 18, 25, 30, 36, 50, 60, 75, 90, 100, 120, 150, 180

<sup>■</sup> Enter the gear ratio in the box (□) within the model name.

## ■Gearmotor – Torque Table

- •Gearheads and decimal gearheads are sold separately.
- $\bullet \text{Enter}$  the gear ratio in the box ( $\square$ ) within the model name.
- •A colored background indicates gear shaft rotation in the same direction as the motor shaft, while the others rotate in the opposite direction.
- The speed is calculated by dividing the motor's synchronous speed (50 Hz: 1500 r/min, 60 Hz: 1800 r/min) by the gear ratio. The actual speed is 2 20% less than the displayed value, depending on the size of the load.
- To reduce the speed beyond the gear ratio in the table, attach a decimal gearhead (gear ratio: 10) between the gearhead and the motor. In that case, the permissible torque is 20 N·m.

♦ 50 Hz

V00 112																				OIII	L — IV III
Model	Speed r/min	500	416	300	250	200	166	120	100	83	60	50	41	30	25	20	16	15	12.5	10	8.3
Motor/ Gearhead	Gear Ratio	3	3.6	5	6	7.5	9	12.5	15	18	25	30	36	50	60	75	90	100	120	150	180
5RK90GE-AW2MJ	<sup>/</sup> 5GE□S	1.7	2.0	2.8	3.4	4.3	5.1	6.4	7.7	9.2	11.6	13.9	16.6	20	20	20	20	20	20	20	20
5RK90GE-CW2MJ 5RK90GE-CW2ME	5GE□S	1.8	2.1	3.0	3.5	4.4	5.3	6.7	8.0	9.6	12.0	14.5	17.3	20	20	20	20	20	20	20	20
5IK90GE-SW2M	5GE□S	1.7	2.0	2.8	3.3	4.1	5.0	6.2	7.4	8.9	11.2	13.5	16.2	20	20	20	20	20	20	20	20

<b>♦60 Hz</b>																				Uni	t = N•m
Model	Speed r/min	600	500	360	300	240	200	144	120	100	72	60	50	36	30	24	20	18	15	12	10
Motor/ Gearhead	Gear Ratio	3	3.6	5	6	7.5	9	12.5	15	18	25	30	36	50	60	75	90	100	120	150	180
5RK90GE-AW2MJ 5RK90GE-AW2MU	/ 5GE□S	1.4	1.7	2.4	2.8	3.6	4.3	5.3	6.4	7.7	9.7	11.6	13.9	19.3	20	20	20	20	20	20	20
5RK90GE-CW2MJ 5RK90GE-CW2ME	/ 5GE□S	1.5	1.8	2.5	2.9	3.7	4.4	5.5	6.6	7.9	10.0	12.0	14.4	20	20	20	20	20	20	20	20
5IK90GE-SW2M	/ 5GE□S	1.4	1.7	2.3	2.8	3.5	4.2	5.2	6.2	7.5	9.4	11.3	13.5	18.8	20	20	20	20	20	20	20

## Permissible Overhung Load and Permissible Thrust Load

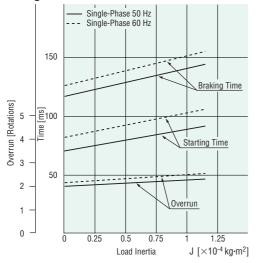
Motor (Round shaft type) → Page 107 Gearhead → Page 107

## Permissible Load Inertia J for Gearhead

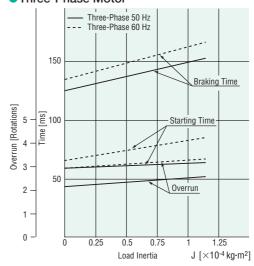
→ Page 107

## ■Starting and Braking Characteristics (Reference Values)

#### Single-Phase Motor



#### Three-Phase Motor



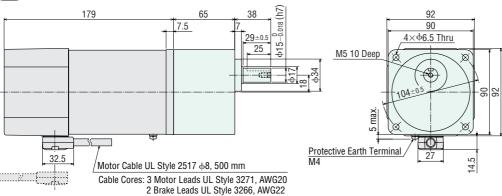
## Dimensions (Unit = mm)

Mounting screws are included with gearheads.

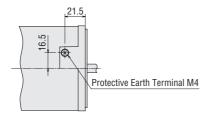
#### 

Mass: Motor 3.9 kg Gearhead 1.5 kg

**CAD** A472



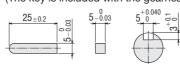
• Cable direction can be switched to the opposite direction.



Detail Drawing of Protective Earth Terminal

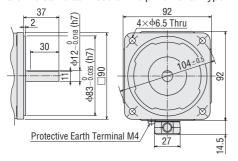
#### $\diamondsuit$ Key and Key Slot

(The key is included with the gearhead)



#### ♦ Shaft Section of Round Shaft Type

The mass and motor's dimensions (excluding the shaft section) are the same as those of the pinion shaft type.



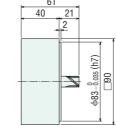
#### 

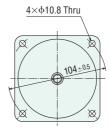
Can be connected to **GE** pinion shaft type.

#### 5GE10XS

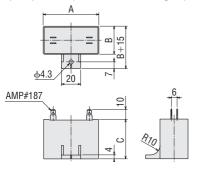
Mass: 0.6 kg

#### CAD A029





#### 



#### 

♦ Cupucitor Zimer								
Mo	del	Capacitor	A B		Capacitor A B C Mass		Mass	Capacitor
Pinion Shaft Type	Round Shaft Type	Model	Α	ь	U	(g)	Сар	
5RK90GE-AW2MJ	5RK90A-AW2MJ	CH350CFAUL2	58	41	58	180		
5RK90GE-AW2MU	5RK90A-AW2MU	CH300CFAUL2	58	35	50	140	Included	
5RK90GE-CW2MJ	5RK90A-CW2MJ	CH80BFAUL	58	35	50	130	IIICiuueu	
5RK90GE-CW2ME	5RK90A-CW2ME	CH70BFAUL	58	35	50	130		

## Connection Diagrams

The direction of motor rotation is as viewed from the shaft end of the motor. CW represents the clockwise direction, while CCW represents the counterclockwise direction.

•Connection diagrams are also valid for the equivalent round shaft type.

●Specify the type of the capacitor to be included by entering J, U or E in the box (□) within the model name.

SW1 operates both motor and electromagnetic brake action.
The motor will rotate when SW1 is switched simultaneously to ON.
When SW1 is switched simultaneously to OFF, the motor stops immediately with the electromagnetic brake and holds the load.

If you wish to release the brake while the motor is stopped, apply voltage between the two brake lead wires (orange).

#### Direction of Rotation

To rotate the motor in a clockwise (CW) direction, turn SW2 to CW. To rotate the motor in a counterclockwise (CCW) direction, turn SW2 to CCW.

	Specifi	Specifications			
Switch	Single-Phase 100 VAC,	Single-Phase 200 VAC,	Note		
No. 110/115 VAC Input		220/230 VAC Input			
SW1	125 VAC 5 A minimum	250 VAC 5 A minimum	Switched Simultaneously		
SW2	(Inductive Load)	(Inductive Load)	_		

SW1 operates both motor and electromagnetic brake action. The motor will rotate when SW1 is switched simultaneously to ON. When SW1 is switched simultaneously to OFF, the motor stops immediately with the electromagnetic brake and holds the load.

If you wish to release the brake while the motor is stopped, apply voltage between the two brake lead wires (orange).

#### Direction of Rotation

Moto

To change the rotation direction, change any two connections between R, S and T.

Switch No.	Specifications	Note
SW1	250 VAC 5 A minimum (Inductive Load)	Switched Simultaneously

PE: Protective Earth

Three-Phase Motor

5IK90GE-SW2M

L1(R)

L2(S)

L3(T)

# **Torque Motors**



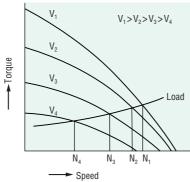


#### Features

The Speed Can Vary Widely, Depending on the Sloping

Characteristics.

Torque motors have a high starting torque and sloping characteristics, allowing easy speed control simply by changing the voltage of the power supply. (The motor torque changes approximately proportion to the square of the voltage.)



#### Suitable for Winding Applications

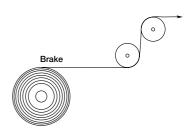
In an application where an object is released continuously at a constant speed and wound up with constant tension, the torque must be doubled and the speed must be halved if the diameter of the winding spool is doubled.

# Constant Tension Wind Up

#### Use as a Brake

By using the motor in the braking region of the speedtorque characteristics, it can serve as a brake.

Constant tension operation can be achieved by applying a DC voltage.

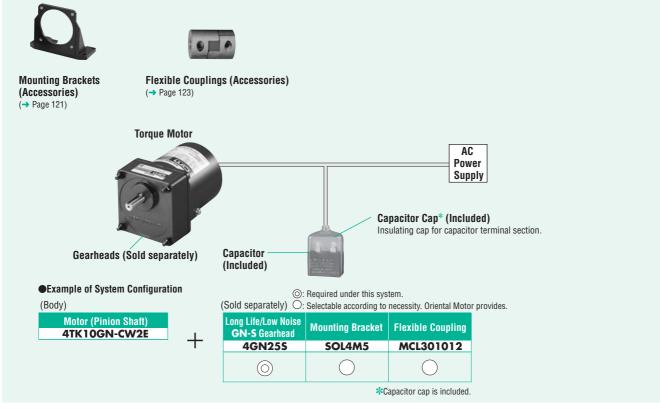


## Safety Standards and CE Marking

Standards	Certification Body	Standards File No.	CE Marking
UL 1004 UL 2111	UL	E64197	
CSA C22.2 No.100 CSA C22.2 No.77	UL	E04197	
EN 60950-1 EN 60034-1 EN 60034-5 IEC 60664-1		Conform to EN/IEC Standards	Low Voltage Directives
GB 12350	CQC	2005010401150784 (3 W~20 W)	

• When the motor is approved under various safety standards, the model name on the nameplate is the approved model name.

## System Configuration



<sup>•</sup> The system configuration shown above is an example. Other configurations are available. Decimal gearheads are also available.

## ■ Product Number Code

Motor

# 5 T K 20 GN - CW 2 E

1 2 3 4 5 6 7 8

1	Motor Frame Size	2: 60 mm 3: 70 mm 4: 80 mm 5: 90 mm			
2	Motor Type T: Torque Motors				
3	Series K: K Series				
4	Output Power (W) (Example) <b>20</b> : 20 W				
(5)	Motor Shaft Type	GN: GN Type Pinion Shaft A: Round Shaft			
6	Power Supply Voltage	AW: Single-Phase 100 VAC, 110/115 VAC CW: Single-Phase 200 VAC, 220/230 VAC			
7	2: RoHS-Compliant				
8	Included Capacitor	J: For Single-Phase 100 VAC, 200 VAC U: For Single-Phase 110/115 VAC E: For Single-Phase 220/230 VAC			

• The J, U and E at the end of the model name indicate that the unit includes a capacitor. These letters are not listed on the motor nameplate.

When the motor is approved under various safety standards, the model name on the nameplate is the approved model name.

(Example) Model: 5TK20GN-CW2E

→ Motor nameplate and product approved under various safety standards:

#### 5TK20GN-CW2

#### Gearhead

5 GN 50 S 1 2 3 4

1	Gearhead Frame Size	2: 60 mm 3: 70 mm 4: 80 mm 5: 90 mm
2	Type of Pinion	GN: GN Type Pinion
3	Gear Ratio	(Example) <b>50</b> : Gear Ratio of 1:50 <b>10X</b> denotes the decimal gearhead of gear ratio 1:10
4	GN Type Pinion	S: Long Life/Low Noise GN-S Gearhead, RoHS-Compliant

Note

A right-angle gearhead cannot be combined.

#### Product Line

## ● Motor RoHS

Output Dower	Mod	del			
Output Power	Pinion Shaft Type	Round Shaft Type			
	2TK3GN-AW2J	2TK3A-AW2J			
3 W	2TK3GN-AW2U	2TK3A-AW2U			
3 W	2TK3GN-CW2J	2TK3A-CW2J			
	2TK3GN-CW2E	2TK3A-CW2E			
	3TK6GN-AW2J	3TK6A-AW2J			
6 W	3TK6GN-AW2U	3TK6A-AW2U			
O VV	3TK6GN-CW2J	3TK6A-CW2J			
	3TK6GN-CW2E	3TK6A-CW2E			
	4TK10GN-AW2J	4TK10A-AW2J			
10 W	4TK10GN-AW2U	4TK10A-AW2U			
I U W	4TK10GN-CW2J	4TK10A-CW2J			
	4TK10GN-CW2E	4TK10A-CW2E			
	5TK20GN-AW2J	5TK20A-AW2J			
20 W	5TK20GN-AW2U	5TK20A-AW2U			
ZU W	5TK20GN-CW2J	5TK20A-CW2J			
	5TK20GN-CW2E	5TK20A-CW2E			

## Gearhead (Sold Separately) (RoHS)

Applicable Motor Output Power (Pinion Shaft Type)	Gearhead Model	Gear Ratio
3 W	2GN□S	3, 3.6, 5, 6, 7.5, 9, 12.5, 15, 18, 25, 30, 36, 50, 60, 75, 90, 100, 120, 150, 180
	2GN10XS (Decima	al gearhead)
6 W	3GN□S	3, 3.6, 5, 6, 7.5, 9, 12.5, 15, 18, 25, 30, 36, 50, 60, 75, 90, 100, 120, 150, 180
	3GN10XS (Decima	al gearhead)
10 W	4GN□S	3, 3.6, 5, 6, 7.5, 9, 12.5, 15, 18, 25, 30, 36, 50, 60, 75, 90, 100, 120, 150, 180
	4GN10XS (Decima	al gearhead)
20 W	5GN□S	3, 3.6, 5, 6, 7.5, 9, 12.5, 15, 18, 25, 30, 36, 50, 60, 75, 90, 100, 120, 150, 180
	5GN10XS (Decima	al gearhead)

lacksquare Enter the gear ratio in the box ( $\Box$ ) within the model name.

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## Specifications

## •3 W, 6 W, 10 W (RoHS)

			1		1	1			1									
Model		Rating at Locked Rotor	Voltage	Frequency	Starting Torque	Max. Output Power	Speed at Max. Output Power	Torque at Max. Output Power	Current at Max. Output Power	Input Power at Max. Output Power	Capacito							
Pinion Shaft Type	Round Shaft Type		VAC	Hz	mN·m	W	r/min	mN∙m	Α	W	μF							
				50	70	3	750	39	0.42	40								
<u> </u>		5 minutes	100	60	70	3.5	900	38	0.48	45								
TP 2TK3GN-AW2J	2TK3A-AW2J			50	18	0.8	750	10	0.21	10	7.0							
		Continuous	50	60	20	1	900	11	0.30	14								
			110						0.42									
TP) 2TK3GN-AW2U	2TK3A-AW2U	5 minutes	115	60	70	3.5	900	38	0.45		6.0							
		Continuous	60	60	25	1.2	900	13	0.26									
				50	70	3	750	39	0.210									
		5 minutes	200	60	70	3.5	900	38	0.230									
TP 2TK3GN-CW2J	2TK3A-CW2J			50	18	0.8	750	10	0.105		1.8							
		Continuous	100	60	20	1	900	11	0.150									
			220					• • • • • • • • • • • • • • • • • • • •	0.220									
			230	50	70	3	750	39	0.240									
		5 minutes	220						0.215		at Max. utput Power W							
P 2TK3GN-CW2E	2TK3A-CW2E		230	60	70	3.5	900	38	0.230		1.5							
			230	50	18	0.8	750	10	0.230									
		Continuous	115	60	25	1.2	900	13	0.033									
				50	140	6	750	78	0.130									
		5 minutes	100	60	140	7.5	900	82	0.63									
P 3TK6GN-AW2J	3TK6A-AW2J			50	40	1.6	750	21	0.03	11								
		Continuous	50		45	2												
			110	60	45		900	23	0.45									
P 3TK6GN-AW2U 3TK6A-AW2U	OTIVE A AVAIOU	5 minutes	110	60	150	8	900	87	0.60		0.0							
	0	115	00		0.0	000	00	0.65		9.0								
		Continuous	60	60	55	2.6	900	28	0.37									
		5 minutes	200	50	140	6	750	78	0.340									
TP) 3TK6GN-CW2J	3TK6A-CW2J	N-CW2J 3TK6A-CW2J			60	140	7.5	900	82	0.340		3.0						
_		Continuous	100	50	40	1.6	750	21	0.165									
			200	60	45	2	900	23	0.245									
			220	50	140	6	750	78	0.390									
		5 minutes	230						0.440									
TP) 3TK6GN-CW2E	3TK6A-CW2E		220	60	150	8	900	87	0.320		2.5							
			230				750	0.4	0.350									
		Continuous	Continuous	Continuous	Continuous	Continuous	Continuous	Continuous	Continuous	115	50	45	1.8	750	24	0.145		
				60	55	2.6	900	28	0.210									
		5 minutes	100	50	220	10	750	130	0.76									
TP) 4TK10GN-AW2J	4TK10A-AW2J			60	210	12	900	130	0.88		14							
		Continuous	50	50	60	2.3	750	30	0.40									
		,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,		60	65	2.8	900	30	0.54									
<u> </u>		5 minutes	110	60	210	12	900	130	0.74									
TP 4TK10GN-AW2U	4TK10A-AW2U		115						0.76		11							
		Continuous	60	60	70	3.3	900	35	0.45									
		5 minutes	200	50	220	10	750	130	0.38									
TP 4TK10GN-CW2J	4TK10A-CW2J	I ATKIOA CMO:		o minutes	200	60	210	12	900	130	0.43		3.5					
II) -IKIOON-CW2J		Continuous	100	50	60	2.3	750	30	0.19	19	0.0							
		Johnhad	100	60	65	2.8	900	30	0.27	25								
			220	50	220	10	750	130	0.41	80								
		5 minutes	230	30	220	10	130	130	0.45	90								
TP) 4TK10GN-CW2E	4TK10A-CW2E	Jillillutes	220	60	210	10	000	120	0.39	80	2.0							
IF 4IKIUUN-CWZE	-INIOA-CWZE		230	60	210	12	900	130	0.40	80	3.0							
		Continuous	115	50	65	2.8	750	35	0.18	20								
		Continuous	110	60	70	3.3	900	35	0.24	25								

<sup>•</sup> The J, U and E at the end of the model name indicate that the unit includes a capacitor. These letters are not listed on the motor nameplate.
When the motor is approved under various safety standards, the model name on the nameplate is the approved model name.

<sup>(</sup>TP): Contains a built-in thermal protector. If a motor overheats for any reason, the thermal protector is opened and the motor stops.

When the motor temperature drops, the thermal protector closes and the motor restarts. Be sure to turn the motor off before inspecting.

## ●20 W (RoHS)



Model		Rating at Locked Rotor	Voltage	Frequency	Starting Torque	Max. Output Power	Speed at Max. Output Power	Torque at Max. Output Power	Current at Max. Output Power	Input Power at Max. Output Power	Capacitor	
Pinion Shaft Type	Round Shaft Type		VAC	Hz	mN∙m	W	r/min	mN∙m	Α	· w	μF	
		5 minutes	100	50	350	20	750	260	1.00	90		
TP) 5TK20GN-AW2J	5TK20A-AW2J	3 IIIIIIules	100	60	300	20	900	220	1.18	115	18	
IP SIKZUGIN-AWZJ	JIKZUA-AWZJ	Continuous	50	50	80	4	750	50	0.50	25	10	
		Continuous	30	60	85	4	900	45	0.69	34		
		5 minutes	110	60	350	23	900	250	1.00	110		
TP 5TK20GN-AW2U	5TK20A-AW2U	-AW2U 5TK20A-AW2	115	115	00	330	2.0	300	230	1.02	115	14
			Continuous	60	60	100	5.5	900	60	0.58	34	
	5TK20A-CW2J	5TK20A-CW2J	5 minutes 2	200	50	350	20	750	260	0.57	105	
TP) 5TK20GN-CW2J			5TK20A-CW2J	200	60	300	20	900	220	0.55	105	4.5
IF SIKZOOI4-CWZS				Continuous	100	50	80	4	750	50	0.24	24
		Continuous	100	60	85	4	900	45	0.31	30		
			220	50	350	20	750	260	0.63	120		
(TP) 5TK20GN-CW2E   5TK20A-C\		5 minutes	230	30	330	20	750	200	0.68	130		
	5TK20A-CW2E		220	60	350	20	900	220	0.53	115	4.0	
IF JIKZUGIA-CWZE	JIRZUM-CVVZE		230	00	330	20	300 2	220	0.54	120	4.0	
		Continuous	115	50	85	4.5	750	60	0.26	29		
		Continuous	113	60	100	5.5	900	60	0.30	34		

<sup>•</sup> The J, U and E at the end of the model name indicate that the unit includes a capacitor. These letters are not listed on the motor nameplate.
When the motor is approved under various safety standards, the model name on the nameplate is the approved model name.

## **■**General Specifications

## **3** W, 6 W, 10 W, 20 W

Item	Specifications							
Insulation Resistance	$100 \text{ M}\Omega$ or more when $500 \text{ VDC}$ megger is applied between the windings and the frame after rated motor operation under normal ambient temperature and humidity.							
Dielectric Strength	fficient to withstand 1.5 kV at 50 Hz or 60 Hz applied between the windings and the frame for 1 minute after rated motor operation under normal ambient mperature and humidity.							
Temperature Rise	emperature rise of windings are 80°C or less measured by the resistance change method after rated motor operation under normal ambient temperature and humidity, ith connecting a gearhead or equivalent heat radiation plate*.							
Insulation Class	Class B (130°C)							
Overheat Protection	Built-in thermal protector (automatic return type)  3W type open: 130°C±5°C, close: 90°C±15°C  Other type open: 130°C±5°C, close: 82°C±15°C							
Ambient Temperature	Single-Phase 50 VAC, Single-Phase 100 VAC, Single-Phase 200 VAC: -10°C~+50°C (nonfreezing) Single-Phase 60 VAC, Single-Phase 110 VAC, Single-Phase 115 VAC, Single-Phase 220 VAC, Single-Phase 230 VAC: -10°C~+40°C (nonfreezing)							
Ambient Humidity	85% or less (noncondensing)							
Degree of Protection	IP20							

\*Heat radiation plate (Material: Aluminum)

Motor Type	Size (mm)	Thickness (mm)
3 W Type	115×115	
6 W Type	125×125	5
10 W Type	135×135	3
20 W Type	165×165	

<sup>(</sup>TP): Contains a built-in thermal protector. If a motor overheats for any reason, the thermal protector is opened and the motor stops.

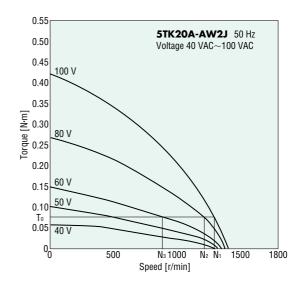
When the motor temperature drops, the thermal protector closes and the motor restarts. Be sure to turn the motor off before inspecting.

## How to Read Speed – Torque Characteristics

The motor torque changes approximately proportion to the square of the voltage. When the voltage supplied to the motor is changed, speed – torque curves with a sloping characteristics (torque is highest at zero speed and decreases steadily with increasing speed) shifts to that of the corresponding voltage.

When the voltage is changed to 100 VAC, 80 VAC and 60 VAC while the load torque is  $T_0$ , the motor rotates at the speeds  $N_1$ ,  $N_2$  and  $N_3$  respectively. Thus, the speed can be changed easily by varying the voltage.

When choosing a torque motor, first determine the required torque and speed. Then select a motor using the speed – torque characteristics curves to determine whether the motor should be operated under continuous duty or limited duty. When used under locked rotor conditions, only the torque factor is considered. The temperature rise of the motor may cause a problem during continuous operation. In this case, choose a motor with an output power large enough for continuous operation and adjust the voltage to control the torque and speed.



## ■Voltage Control of Torque Motors

The method most commonly used to control voltage is by phase control using a triac. As shown in Fig. 1, by changing the phase angle " $\alpha$ " at which the triac switches, the input voltage is controlled as represented by the phase angle areas of the graph.

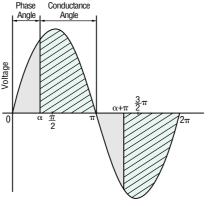


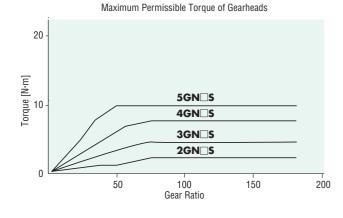
Fig. 1 Phase Control

## ■Gearmotor – Torque Table

Due to the sloping characteristics, torque motors can be operated over a wide speed range, from locked rotor condition to the maximum speed. The permissible torque when a gearhead and a decimal gearhead are directly connected can be calculated according to the following formula, using the speed and torque determined from the speed – torque characteristics.

Speed of gearhead output shaft  $N_c$ =Motor speed $\times$ 1/gearhead gear ratio Output torque of gearhead  $T_c$ =Motor torque $\times$ Gearhead gear ratio $\times$ Gearhead efficiency

The output torque of the gearhead must be lower than the maximum permissible torque.



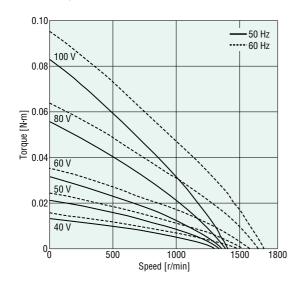
Gearhead Model	Gearhead Gear Ratio	Gearhead Efficiency
2GN□S	3~18	81%
3GN⊡S 4GN⊡S	25∼36	73%
5GN□S	50~180	66%

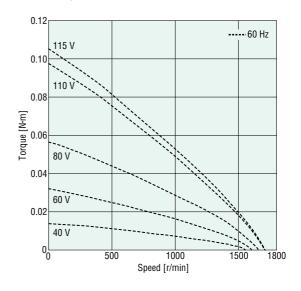
- Gearheads and decimal gearheads are sold separately.
- Enter the gear ratio in the box (□) within the model name.

## ■ Speed - Torque Characteristics (Reference Values)

#### 2TK3GN-AW2J, 2TK3A-AW2J

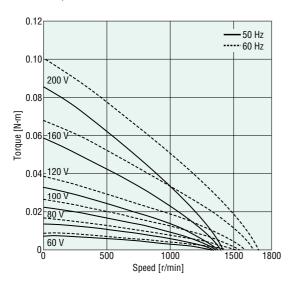
#### 2TK3GN-AW2U, 2TK3A-AW2U

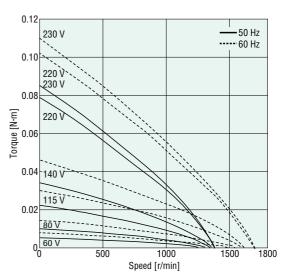




#### 2TK3GN-CW2J, 2TK3A-CW2J

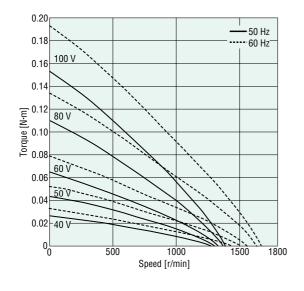
#### 2TK3GN-CW2E, 2TK3A-CW2E

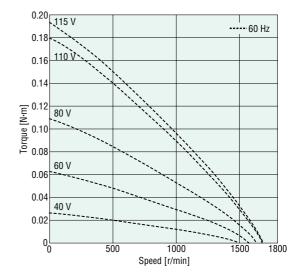




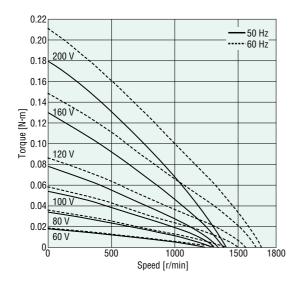
#### 3TK6GN-AW2J, 3TK6A-AW2J

#### 3TK6GN-AW2U, 3TK6A-AW2U

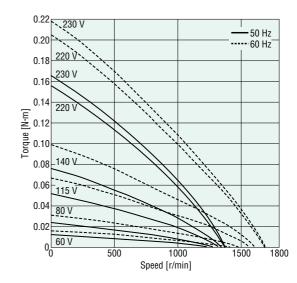




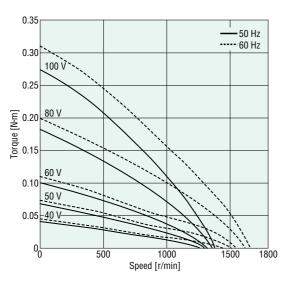
#### 3TK6GN-CW2J, 3TK6A-CW2J



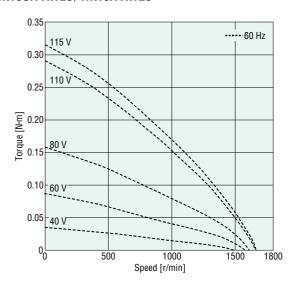
#### 3TK6GN-CW2E, 3TK6A-CW2E



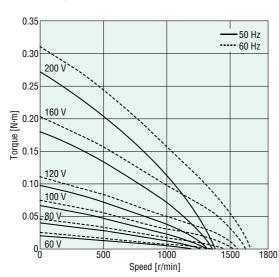
#### 4TK10GN-AW2J, 4TK10A-AW2J



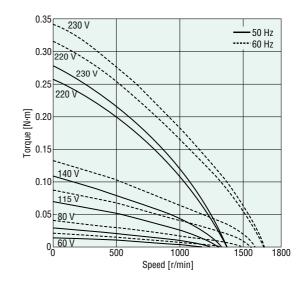
#### 4TK10GN-AW2U, 4TK10A-AW2U



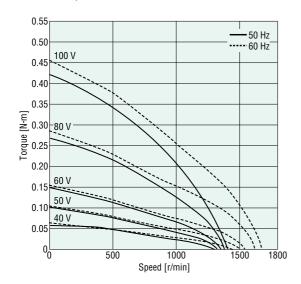
#### 4TK10GN-CW2J, 4TK10A-CW2J



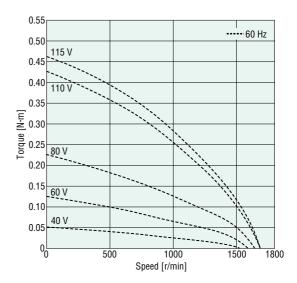
#### 4TK10GN-CW2E, 4TK10A-CW2E



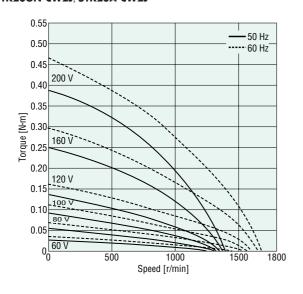
#### 5TK20GN-AW2J, 5TK20A-AW2J



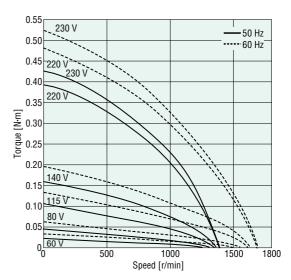
#### 5TK20GN-AW2U, 5TK20A-AW2U



#### 5TK20GN-CW2J, 5TK20A-CW2J



#### 5TK20GN-CW2E, 5TK20A-CW2E



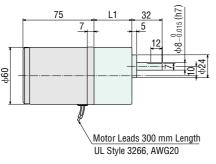
## **Dimensions** (Unit = mm)

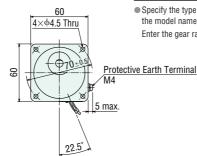
Mounting screws are included with gearheads.

#### **3** W

#### 

Mass: Motor 0.7 kg Gearhead 0.4 kg





Motor Model	Gearhead Model	Gear Ratio	L1	CAD
2TK3GN-AW2	2CN□C	3~18	30	A443A
2TK3GN-CW2■	2GN⊔S	<b>25</b> ~180	40	A443B

Specify the type of the capacitor to be included by entering J, U or E in the box ( ) within the model name.

Enter the gear ratio in the box ( ) within the model name



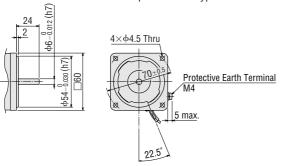
Detail Drawing of Protective Earth Terminal

#### ♦ Shaft Section of Round Shaft Type

#### 2TK3A-AW2

#### 2TK3A-CW2

The mass and motor's dimensions (excluding the shaft section) are the same as those of the pinion shaft type.



#### 

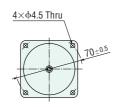
Can be connected to **2TK3GN** type.

#### **2GN10XS**

Mass: 0.2 kg

# (AD A003 38.5 26 12.5

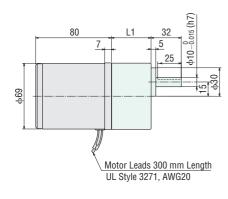
Ф24

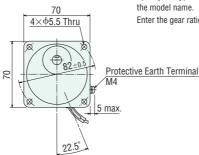


#### **6** W

#### 

Mass: Motor 1.1 kg Gearhead 0.55 kg

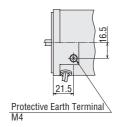




Motor Model	Gearhead Model	Gear Ratio	L1	CAD
3TK6GN-AW2■	3GN□S	3~18	32	A447A
3TK6GN-CW2■	3GN_3	<b>25~180</b>	42	A447B

 Specify the type of the capacitor to be included by entering J, U or E in the box () within the model name

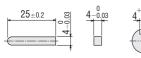
Enter the gear ratio in the box ( $\square$ ) within the model name.



Detail Drawing of Protective Earth Terminal

## $\diamondsuit$ Key and Key Slot

(The key is included with the gearhead)

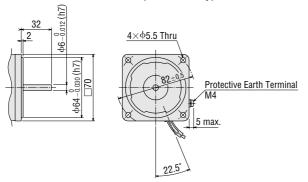


#### ♦ Shaft Section of Round Shaft Type

#### 3TK6A-AW2

#### 3TK6A-CW2

The mass and motor's dimensions (excluding the shaft section) are the same as those of the pinion shaft type.



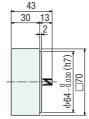
#### ♦ Decimal Gearhead

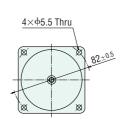
Can be connected to **3TK6GN** type.

#### **3GN10XS**

Mass: 0.3 kg

#### **CAD** A009

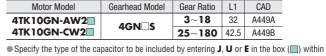


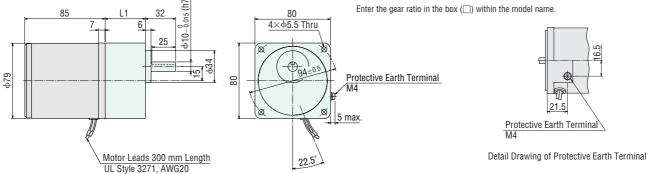


#### ●10 W

#### 

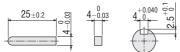
Mass: Motor 1.5 kg Gearhead 0.65 kg





#### 

(The key is included with the gearhead)

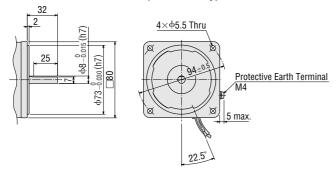


#### ♦ Shaft Section of Round Shaft Type

## 4TK10A-AW2

#### 4TK10A-CW2

The mass and motor's dimensions (excluding the shaft section) are the same as those of the pinion shaft type.

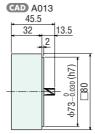


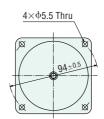
#### 

Can be connected to **4TK10GN** type.

## **4GN10XS**

Mass: 0.4 kg





●20 W

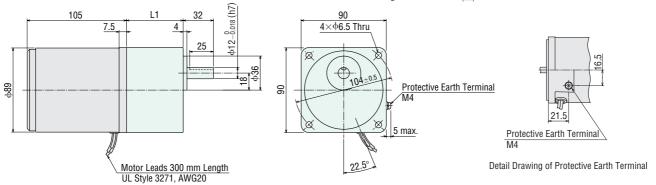
#### 

Mass: Motor 2.5 kg Gearhead 1.5 kg

Motor Model	Gearhead Model	Gear Ratio	L1	CAD
5TK20GN-AW2	5GN□S	3~18	42	A452A
5TK20GN-CW2■	3GN_3	<b>25~180</b>	60	A452B

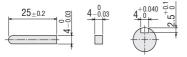
Specify the type of the capacitor to be included by entering J, U or E in the box () within
the model name.

Enter the gear ratio in the box  $(\Box)$  within the model name.



## $\diamondsuit$ Key and Key Slot

(The key is included with the gearhead)

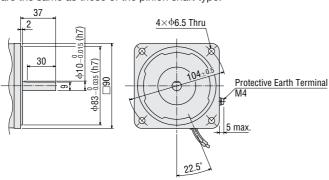


## ♦ Shaft Section of Round Shaft Type

#### 5TK20A-AW2

#### 5TK20A-CW2

The mass and motor's dimensions (excluding the shaft section) are the same as those of the pinion shaft type.



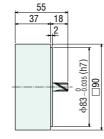
#### 

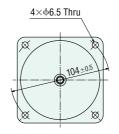
Can be connected to **5TK20GN** type.

#### 5GN10XS

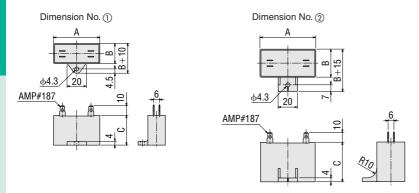
Mass: 0.6 kg

CAD A022





#### 

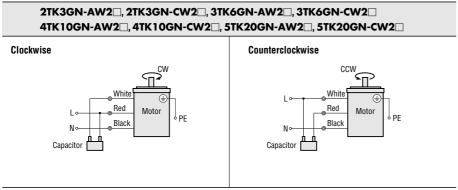


#### 

Model Capacitor A D Mass Dimension Capacitor								
	Model		A	В	С	Mass	Dimension	Capacitor
Pinion Shaft Type	Round Shaft Type	Model	, ,			(g)	No.	Сар
2TK3GN-AW2J	2TK3A-AW2J	CH70CFAUL2	48	19	29	36	1	
2TK3GN-AW2U	2TK3A-AW2U	CH60CFAUL2	38	21	31	40	1	
2TK3GN-CW2J	2TK3A-CW2J	CH18BFAUL	38	21	31	35	1)	
2TK3GN-CW2E	2TK3A-CW2E	CH15BFAUL	38	21	31	35	1	
3TK6GN-AW2J	3TK6A-AW2J	CH110CFAUL2	58	21	31	50	1	
3TK6GN-AW2U	3TK6A-AW2U	CH90CFAUL2	48	22.5	31.5	45	1	
3TK6GN-CW2J	3TK6A-CW2J	CH30BFAUL	58	21	31	50	1)	
3TK6GN-CW2E	3TK6A-CW2E	CH25BFAUL	48	21	31	45	1	Included
4TK10GN-AW2J	4TK10A-AW2J	CH140CFAUL2	58	22	35	61	1	IIICiuueu
4TK10GN-AW2U	4TK10A-AW2U	CH110CFAUL2	58	21	31	50	1)	
4TK10GN-CW2J	4TK10A-CW2J	CH35BFAUL	58	22	35	55	1	
4TK10GN-CW2E	4TK10A-CW2E	CH30BFAUL	58	21	31	50	1)	
5TK20GN-AW2J	5TK20A-AW2J	CH180CFAUL2	58	29	41	95	2	
5TK20GN-AW2U	5TK20A-AW2U	CH140CFAUL2	58	22	35	61	1)	
5TK20GN-CW2J	5TK20A-CW2J	CH45BFAUL	58	23.5	37	73	2	
5TK20GN-CW2E	5TK20A-CW2E	CH40BFAUL	58	23.5	37	70	2	

## **■**Connection Diagrams

- The direction of motor rotation is as viewed from the shaft end of the motor. CW represents the clockwise direction, while CCW represents the counterclockwise direction.
- Connection diagrams are also valid for the equivalent round shaft type.
- lacktriangle Specify the type of the capacitor to be included by entering lacktriangle or lacktriangle in the box  $(\Box)$  within the model name.



PE: Protective Earth

# **Common Specifications**

## Permissible Overhung Load and Permissible Thrust Load of Motor

#### Permissible Overhung Load

Motor		Permissible Overhung Load N		
Motor Frame Size	Output Shaft Diameter	Distance fro	m Shaft End	
☐ (mm)	ф (mm)	10 mm	20 mm	
42	5	40	_	
60	6	50	110	
70	6	40	60	
80	8	90	140	
00	10	110	120	
90	10	140	200	
	12	240	270	

#### Permissible Thrust Load

Avoid thrust loads as much as possible. If thrust load is unavoidable, keep it to half or less of the motor mass.

## Permissible Overhung Load and Permissible Thrust Load of Gearheads

Model	Gear Ratio	Maximum Permissible Torque Permissible Overhung Load N		rerhung Load N	Permissible Thrust Load
Wodei	Gear Railo	N∙m	10 mm from Shaft End	20 mm from Shaft End	N
0GN□K	3~180	1.0	20	_	15
2GN□S	3~18	3.0	50	80	30
ZGN_5	25~180	3.0	120	180	30
3GN□S	3~18	5.0	80	120	40
3GN_3	<b>25~180</b>	3.0	150	250	40
4GN□S	3~18	8.0	100	150	50
4GN□5	<b>25~180</b>	0.0	200	300	30
5GN□S	3~18	10	250	350	100
3GN_3	<b>25~180</b>	10	300	450	100
	3∼9		400	500	
5GE□S	12.5~18	20	450	600	150
	25~180		500	700	

#### Permissible Load Inertia for Gearhead J

When a high load inertia (J) is connected to a gearhead, high torque is exerted instantaneously on the gearhead when starting up in frequent, discontinuous operations (or when stopped by an electromagnetic brake, or when stopped instantaneously by a brake pack). Excessive impact loads can cause the gearhead or motor damage.

The table below gives values for permissible load inertia on the motor shaft. Use the motor and gearhead within these parameters. The permissible inertial load value shown for three-phase motors is the value when reversing after a stop.

The permissible load inertia (J) on the gearhead output shaft is calculated with the following equation.

The life of the gearhead when operating at the permissible inertial load with instantaneous stops of the motors with electromagnetic brakes, brake packs or speed control motors is at least 2 million cycles.

#### Permissible Load Inertia for Gearhead Output Shaft

Gear ratio  $1/3 \sim 1/50$   $J_G = J_M \times i^2$   $J_G$ : Permissible load inertia for gearhead output shaft  $J (\times 10^{-4} \text{ kg·m}^2)$ 

Gear ratio 1/60 or higher  $JG=JM\times2500$  JM: Pemissible load inertia at the motor shaft J ( $\times10^4$  kg·m²)

i: Gear ratio (Example: i=3 means the gear ratio of 1/3)

#### Permissible Load Inertia at the Motor Shaft

No. of Phase	Motor Frame Size	Output Power	Permissible Load Inertia at the Motor Shaft J (×10 <sup>-4</sup> kg·m²)
	☐ 42 mm	1 W, 3 W	0.016
	□ 60 mm	3 W*, 6 W	0.062
	□ 70 mm	6 W*, 15 W	0.14
Single-Phase	□ 80 mm	10 W*, 25 W	0.31
	□ 90 mm	20 W*, 40 W	0.75
		60 W	1.1
	90 W	1.1	
	□ 60 mm	6 W	0.062
	□ 80 mm	25 W	0.31
Three-Phase		40 W	0.75
□ 90 mm	60 W	1.1	
		90 W	1.1

<sup>\*</sup>Output power for torque motors

## RoHS RoHS-Compliant

# **Right-Angle Gearheads**

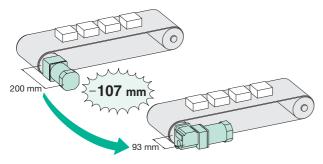
Right-angle gearheads are flange-mounted gearheads that use worm gears and special helical gears. They allow motors to be installed at right angles to the axis of equipment such as belt conveyors. They are available in hollow shaft **RH** and solid shaft **RA** models and are ideal for keeping equipment compact.



#### Features

#### Space-Saving

•The output shaft is perpendicular to the motor shaft, so the motor can be installed perpendicularly to the axis being driven, enabling space-saving.



Comparison between 51K90GE-AW2J and gearhead with a gear ratio of 1:18

•Hollow shaft gearheads allow additional space savings and simpler mechanism designs due to the removal of some parts of mechanism as they do not require couplings for mounting. When mounted with a torque arm\*, no centering is needed, so it is faster to mount the gearhead on the device.

#### \* Mounting Using Torque Arm Usually, hollow shaft gearheads are locked with a torque arm when mounted so the gearhead does not rotate from the reactive force of the load. The torque arm is available as an accessory for the 5GE□RH. Torque Arm → Page 113

#### Wide Variation

A wide variety of gear ratio (20 types, from **3** to **180**) is available. The optimum gear ratio can be selected as the same with ordinary gearheads. The maximum permissible torques are also the same as for ordinary gearheads.

## Applicable Products

**GN** and **GE** pinion motors with matching mounting frame sizes can be installed.

Example)  $\underline{4}$ IK25GN-CW2E  $\rightarrow \underline{4}$ GN $\square$ RH (or  $\underline{4}$ GN $\square$ RA)  $\underline{5}$ IK60GE-CW2E  $\rightarrow \underline{5}$ GE $\square$ RH (or  $\underline{5}$ GE $\square$ RA)

Gearheads can be used with pinion shaft type motors listed below.

Motor	Output Power
Induction Motors	25 W, 40 W, 60 W, 90 W
Reversible Motors	25 W, 40 W, 60 W, 90 W
Electromagnetic Brake Motors	25 W, 40 W, 60 W, 90 W

<sup>•</sup> The right-angle gearheads cannot be used with torque motors.

### Product Number Code

## 5 GE 25 R H

3

1	Gearhead Frame Size	<b>4</b> : 80 mm <b>5</b> : 90 mm					
_	Time	GN: GN Pinion Gear					
(2)	Туре	GE: GE Pinion Gear					
3	Gear Ratio	(Example) 25: Gear Ratio of 1:25					
4	R: Right-Angle Gearhead						
(5)	Shaft Type	H: Hollow Shaft Type A: Solid Shaft Type					

### ■Product Line RoHS

Shaft Type	Gearhead Model	Gear Ratio
	4GN□RH	3, 3.6, 5, 6, 7.5, 9, 12.5, 15, 18, 25, 30, 36, 50, 60, 75, 90, 100, 120, 150, 180
Hollow Shaft	5GN□RH	3, 3.6, 5, 6, 7.5, 9, 12.5, 15, 18, 25, 30, 36, 50, 60, 75, 90, 100, 120, 150, 180
	5GE□RH	3, 3.6, 5, 6, 7.5, 9, 12.5, 15, 18, 25, 30, 36, 50, 60, 75, 90, 100, 120, 150, 180
	4GN□RA	3, 3.6, 5, 6, 7.5, 9, 12.5, 15, 18, 25, 30, 36, 50, 60, 75, 90, 100, 120, 150, 180
Solid Shaft	5GN□RA	3, 3.6, 5, 6, 7.5, 9, 12.5, 15, 18, 25, 30, 36, 50, 60, 75, 90, 100, 120, 150, 180
	5GE□RA	3, 3.6, 5, 6, 7.5, 9, 12.5, 15, 18, 25, 30, 36, 50, 60, 75, 90, 100, 120, 150, 180

lacksquare Enter the gear ratio in the box ( $\Box$ ) within the model name.

### Specifications

Gearhead Model	Gear Ratio	Maximum Permissible Torque	Permissible Ov	Permissible Thrust Load	
deameau Model	deal natio	N∙m	10 mm from Shaft End	20 mm from Shaft End	N
4GN□RH	3~180	8.0	250*	220*	100
5GN□RH	3~180	10	350*	310*	200
5GE□RH	3~180	20	560*	500*	250
4GN□RA	3~18	8.0	100	150	100
4GN_KA	<b>25~180</b>	0.0	200	300	100
5GN□RA	3~18	10	250	350	200
5GN⊔KA	<b>25~180</b>	10	300	450	200
	3∼9		400	500	
5GE□RA	12.5~2 <b>5</b>	20	450	600	250
	30~180		500	700	

 $<sup>\</sup>textcolor{red}{*\,\text{With the hollow shaft type, the permissible overhung load is measured from the flange-mounting surface.}}$ 

The right-angle gearhead does not have self-locking capabilities.

### ■Gearmotor – Torque Table

Use the efficiency value in the table below for your calculations. When making a selection, remember that the transfer efficiency at startup is lower than at the rated speed.

#### Permissible torque $\cdots TG = TM \times i \times \eta$

 $T_{\rm G}$  : Permissible torque of gearhead

Tm: Motor torque i : Gearhead gear ratio η : Gearhead efficiency

### Gearhead Efficiency

	Gear Ratio	3	3.6	5	6	7.5	9	12.5	15	18	25	30	36	50	60	75	90	100	120	150	180
Gearhead Model		3	3.0	3	0	7.5	7	12.5	13	10	23	30	30	30	80	73	70	100	120	130	100
4GN□RH	Rating		40	%		50	1%							60	)%						
4GN_KH	Startup		40	%		50	1%							54	1%						
5GN□RH	Rating		50	%				68%								60%					
3GN_K⊓	Startup		50	%				60%	60% 54%												
5GE□RH	Rating	50%			68	1%		60%			50%										
3GE□K⊓	Startup		50	%				60	1%	54%			45%								
4GN□RA	Rating			50	1%			60%													
4GN_KA	Startup			50	1%			54%													
5GN□RA	Rating					68%			60%												
3GN_KA	Startup	60%				54%															
ECE□DA	Rating		68%		%	60%				50%											
5GE□RA	Startup					60	1%								54%					45%	

 $<sup>\</sup>bullet$  Enter the gear ratio in the box (  $\square$  ) within the model name.

<sup>■</sup> Enter the gear ratio in the box (□) within the model name.

### Calculating Permissible Overhung Load for Hollow Shaft Models

When the end of the shaft being driven is not supported by a bearing as in the figure shown below, calculate the permissible overhung load using the following equations.

(This mechanism is the most demanding in terms of overhung load.)

#### ●4GN□RH

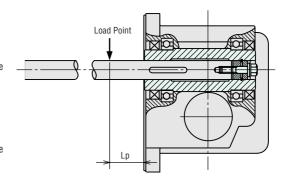
Permissible overhung load  $W[N] = \frac{59.5}{59.5 + Lp} \times 295[N]$ 

\*295 [N]: Permissible overhung load at the flange mounting surface

#### ●5GN□RH

Permissible overhung load  $W[N] = \frac{70}{70 + L_D} \times 400 [N]$ 

\*400 [N]: Permissible overhung load at the flange mounting surface



### ●5GE□RH

Permissible overhung load  $W[N] = \frac{68.5}{68.5 + Lp} \times 645 [N]^*$ 

\*645 [N]: Permissible overhung load at the flange mounting surface

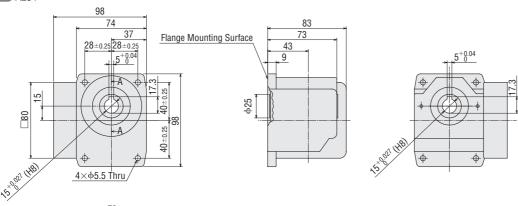
 $\label{local_point} \mbox{Lp (mm): Distance from flange mounting surface to overhung load point}$ 

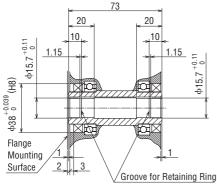
### Dimensions (Unit = mm)

- •Mounting screws are included with gearheads.
- lacktriangle Enter the gear ratio in the box ( $\Box$ ) within the model name.

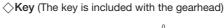
#### ♦ Hollow Shaft Type

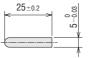
# **4GN**□**RH**Mass: 1.6 kg CAD A254





Cross Section AA (Detail Drawing of Output Shaft)



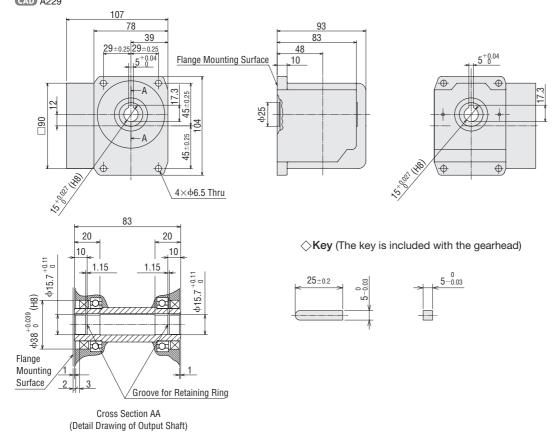




### ♦ Hollow Shaft Type

**5GN**□**RH** Mass: 2.0 kg

CAD A229

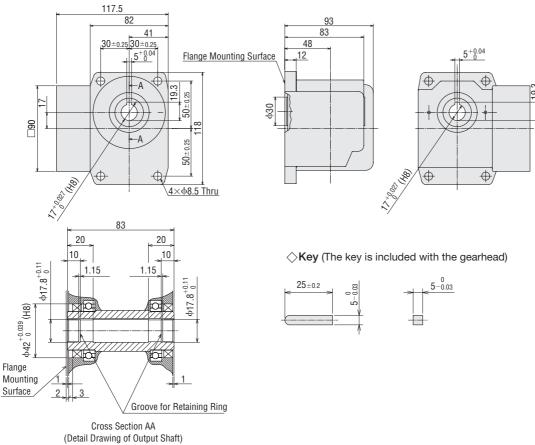


### ♦ Hollow Shaft Type

5GE□RH

Mass: 2.5 kg

**CAD** A230

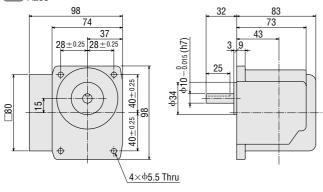


#### 

### 4GN□RA

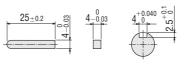
Mass: 1.6 kg

**CAD** A255



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(The key is included with the gearhead)

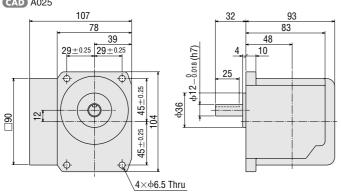


#### 

### 5GN□RA

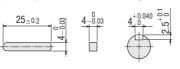
Mass: 2.0 kg

**CAD** A025



#### ♦ Key and Key Slot

(The key is included with the gearhead)

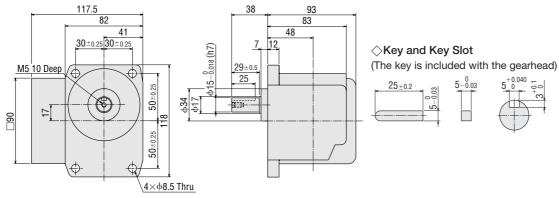


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### 5GE□RA

Mass: 2.5 kg

**CAD** A512

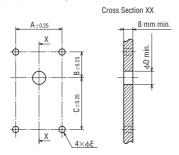


(Unit = mm)

(Unit = mm)

#### ♦ Dimensions of the Gearhead Mounting Surface

Allow at least 8 mm for the thickness of the mounting plate and use screws of the appropriate length.



					(01	11111)
Shaft Type	Model	Α	В	С	φD	φЕ
	4GN□RH	56	25	55	ф15	ф5.5
Hollow Shaft	5GN□RH	58	33	57	ф15	ф6.5
	5GE□RH	60	33	67	φ17	ф8.5
	4GN□RA	56	25	55	ф35	ф5.5
Solid Shaft	5GN□RA	58	33	57	ф37	ф6.5
	5GE□RA	60	33	67	ф35	ф8.5

Enter the gear ratio in the box ( ) within the model name.

### Mounting Method for Hollow Shaft Type Gearhead

#### Example of Mounting the Load

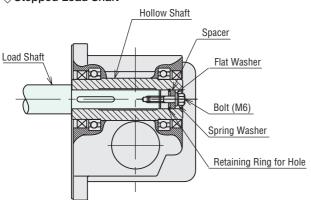
These diagrams show how to mount loads depending on the shape of the shaft.

The tolerance of the inner diameter for the hollow shaft is finished as H8, and "key slot" processing is given to mount the load shaft. The recommended tolerance of the load shaft is h7. Use the key provided with the product by fastening it to the shaft. Apply a coating of molybdenum disulfide or similar grease to the inner diameter of the load shaft to prevent binding. Recommended load shaft dimensions are shown on the right.

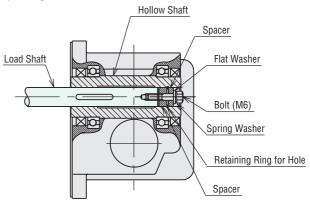
#### Inner Diameter of Hollow Shaft Recommended Load Shaft Diameter Model Н8 0 -0.018 +0.0274GN□RH ф15 +0.0275GN□RH ф15 ф15 - 0.018 +0.027n 5GE□RH ф17 ф17 -0.018

■ Enter the gear ratio in the box (□) within the model name.

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If the bolt extends out more than 4 mm from the end of the hollow shaft, a safety cover can not be installed. (Hollow shaft type gearheads include safety covers.)

#### Torque Arm

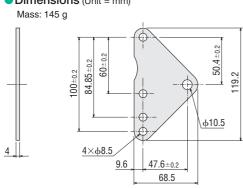
The torque arm serves as an anti-rotation guide for the gearhead when a right-angle hollow shaft type gearhead is used in a shaftmounted fashion (with the gearhead mounted on the shaft of a connected device).

When using it as a shaft-mounted gearhead, be sure to use a torque arm and secure the gearhead to the device.

#### Model: SOT6

**5GE**□RH Gearhead

Dimensions (Unit = mm)

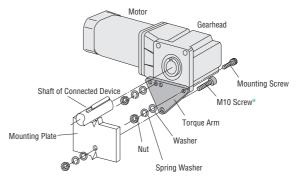




#### Mounting Method

When mounting on a device, secure the torque arm firmly using an M10 screw

\*M10 screws must be purchased separately.



### RoHS RoHS-Compliant

## **Brake Pack for Standard AC Motors**

## **SB50W**

**AU**us **(E** 

The **SB50W** provides instantaneous stop, forward/reverse operation, electromagnetic brake control and thermal protector open detection functions integrated into one unit. These brake packs can sense when the thermal protector is opened, further ensuring the safety of your equipment.



#### Features

#### • Four Functions in One Integrated Unit

The **\$B50W** provides instantaneous stop, forward/reverse operation, electromagnetic brake control and thermal protector open detection functions\*.

\*Thermal protector open detection function

(Available only when combined with a motor having a built-in thermal protector) When the motor's thermal protector (overheat protection device) is activated, the **SB50W** outputs an alarm signal and automatically cuts the power supply to the motor. The motor will not restart by itself, even after the temperature drops and the thermal protector recovers, until the power is cycled. Possible to reset the alarm through external signals.

#### Wide Voltage Range of 100 to 230 VAC

The **\$B50W** covers a single-phase voltage range of 100 to 230 VAC  $\pm 10\%$ , 50/60 Hz, accommodating all of the world's key voltage specifications.

#### Conforms to Safety Standards

This is the world first brake pack which conforms to safety standards. The CE marking is used in accordance with the EMC directives and low voltage directives.

#### Supports Motors with 1 to 90 W Output

The **\$B50W** can be used with induction, reversible, electromagnetic brake and watertight, dust-resistant motors with an output range of 1 to 90 W.

#### Switchable Sink/Source Logic

Select the sink mode or source mode for the input/output circuit. You can change the setting at any time.

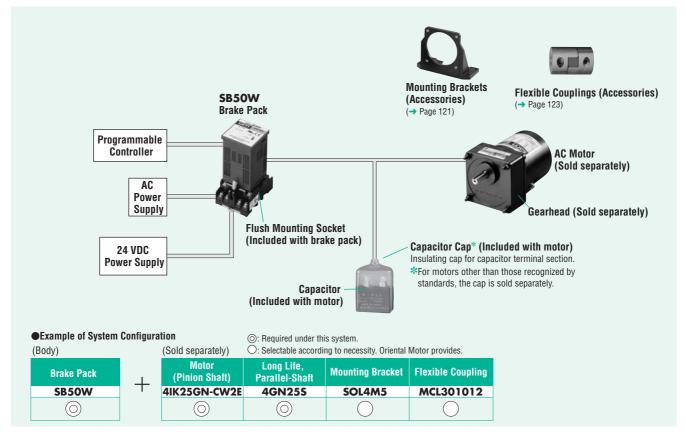
### ■Safety Standards and CE Marking

Standards	Certification Body	Standards File No.	CE Marking	
UL508		E91291		
CSA C22.2 No.14	UL	E91291	Low Voltage Directives	
EN50178 EN60950-1	Conform to E	N Standards	EMC Directives	

<sup>•</sup> The EMC value changes according to the wiring and layout. Therefore, the final EMC level must be checked with the brake pack incorporated in the user's equipment.

**M**us 66

### System Configuration



<sup>•</sup> The system configuration shown above is an example. Other configurations are available.

## Specifications (RoHS)

Мо	del	Power Supply Voltage	Frequency	Applicable Motor Output Voltage	Functions	Power Source for Control	Input Signals	Output Signals	Braking Current Duration
SB5	ow	Single-phase 100-230 VAC ±10%		1 W∼90 W	Instantaneous stop Forward/reverse operation Electromagnetic brake control (Electromagnetic brake motors) Thermal protector open detection (Alarm output) Sink/Source logic switch		CW, CCW, FREE/ALARM-RESET Input specifications Photocoupler input Input impedance 4.7 k $\Omega$ 24 VDC $\pm 10\%$	ALARM  Output specifications Open collector output External use conditions 26.4 VDC max. 10 mA max.	Approximately 0.2~0.4 seconds

### ■General Specifications

Item	Specifications	
Insulation Resistance	$100 \text{ M}\Omega$ or more when measured by a 500 VDC megger between the power supply input terminal and the signal input terminal after rated motor operation under normal ambient temperature and humidity.	
Dielectric Strength Sufficient to withstand 3.0 kV at 50 Hz or 60 Hz applied between the power supply input terminal and the signal input terminal for 1 minute after rated mo operation under normal ambient temperature and humidity.		
Ambient Temperature	0°C∼+40°C (nonfreezing)	
Ambient Humidity	85% or less (noncondensing)	
Degree of Protection	IP10	

### Applicable Products

<sup>\*</sup> Except for 2-pole type

#### Braking Current

When a motor is stopped suddenly, a large half-wave rectified current flows through the motor for approximately 0.2 to 0.4 seconds. When connecting a circuit breaker, fuse or transformer, refer to the table below for the braking current (peak value) and select its current capacity.

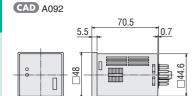
Motor Output Power	Braking Current [A] (Peak Value)				
wotor output rower	100/110/115 VAC	200/220/230 VAC			
1 W	1.0	0.3*			
6 W	1.5	1.0			
15 W	4.5	2.5			
25 W	7.5	4.0			
40 W	12	7.0			
60 W	18	8.5			
90 W	26	17			

<sup>\*</sup>Can be used only for 200 VAC.

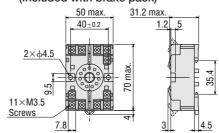
### Dimensions (Unit = mm)

#### **♦SB50W**

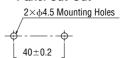
Mass: 0.1 kg



#### Flush Mounting Socket (Included with brake pack)

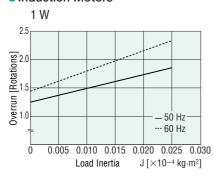


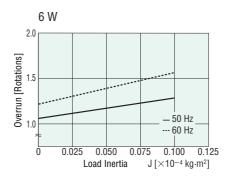
#### Flush Mounting Socket Panel Cut-Out

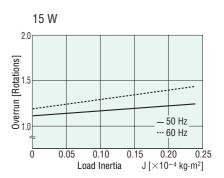


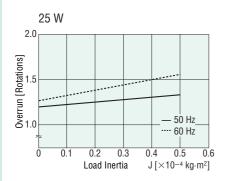
### ■ Braking Characteristics (Reference Values)

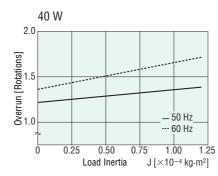
#### Induction Motors

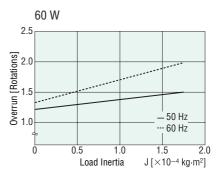


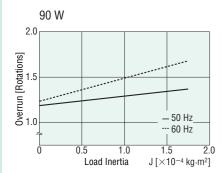




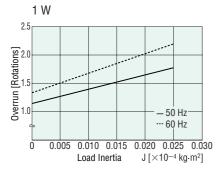


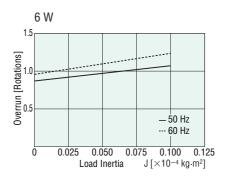


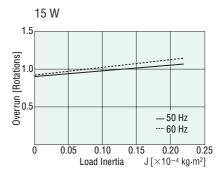


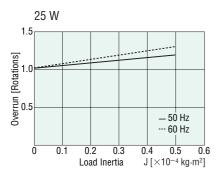


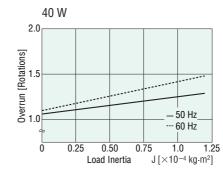
#### Reversible Motors

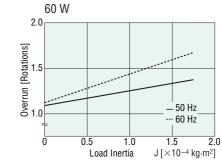


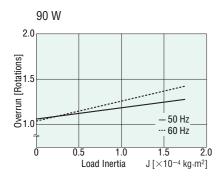




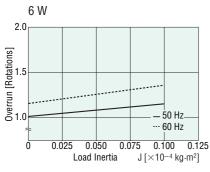


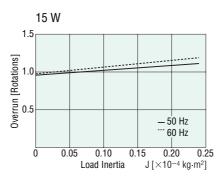


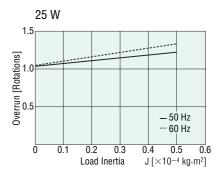


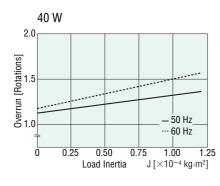


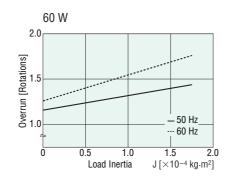
### Electromagnetic Brake Motors

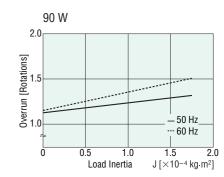












### **■**Connection and Operation

#### Names and Functions of Brake Pack Parts

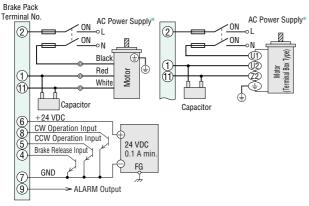


No.	Name	Factory Setting	Functions
1)	POWER Indicator (Green)	_	Lit when 24 VDC is supplied.
2	ALARM Indicator (Red)	-	Lit when the ALARM output is "OFF."
3	Motor Output Select Switch	60-90 W	Used to set the motor output.
4	SINK/SOURCE Select Switch	SINK	Used to switch between Sink/Source for the control signal output.

#### Connection Diagrams

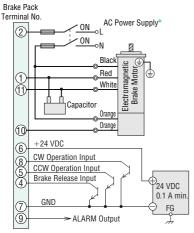
The wiring diagram is for when the SINK/SOURCE select switch is set to the "SINK" side.

#### ♦ Induction Motors/Reversible Motors



\$Single-phase 100/110/115 VAC, single-phase 200/220/230 VAC

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\*Single-phase 100/110/115 VAC, single-phase 200/220/230 VAC

#### Terminal Arrangement for Flush Mounting Socket

Terminal No.	Signal Name	Description			
1	Motor/Capacitor	Connect the motor and capacitor.			
2	AC Power Input (L)	Single-phase 100 – 115 VAC Single-phase 200 – 230 VAC			
3	NC	Not used. Leave this terminal unconnected.			
<b>4</b> )*1	Brake Release Input*2	Not an instantaneous stop but a natural stop			
(4)	ALARM-RESET Input	Reset ALARM Output.			
(5)	CCW Operation Input*3	Motor runs in the CCW direction during "ON."			
6	DC Power Input	+24 VDC input			
7	GND	GND			
8	CW Operation Input	Motor runs in the CW direction during "ON."			
9	ALARM Output	Turns "OFF" when the motor's thermal protector is "open."			
10	Electromagnetic Brake*4	Connect to the electromagnetic brake.			
11)	Motor/Capacitor	Connect the motor and capacitor.			

- \*1 Functions as a brake release input during normal operation, and as an ALARM-RESET input when the ALARM output is OFF.
- \*2 Releases the electromagnetic brake for electromagnetic brake motors.
- \*3 Not used with an induction motor with four lead wires.
- \*4 Only for electromagnetic brake motors.

#### Notes:

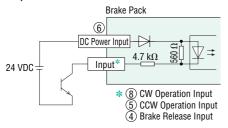
- The input-signal voltage is 24 VDC±10% and 0.1 A or more.
- $\bullet$  Minimize the length of the motor cable and the input/output signal cable to reduce EMI.
- Use a cable of AWG18 (0.75 mm²) or more in diameter for the motor cable and power cable.
- Be sure to connect the GND terminal to GND (negative side) of the external controller, or the unit will not operate.

#### ■I/O Signal Circuit

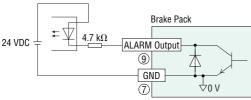
The I/O signal circuit can be switched between the sink mode and source mode using the sink/source select switch on the brake pack. The factory setting is the sink mode.

#### 

#### •Input Circuit

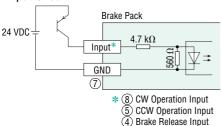


#### Output Circuit

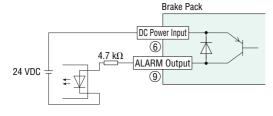


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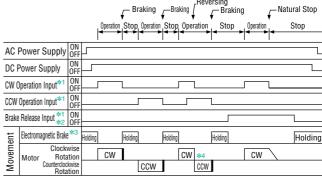
#### •Input Circuit



#### Output Circuit



#### Timing Chart



- \*1 Turn on CW operation input, CCW operation input, and brake release input after turning on AC power.
  - The motor does not operate if they are input ahead of AC power.
- The ALARM indicator will light and ALARM output will switch to "OFF."
- \*2 The brake release input becomes ALARM-RESET input when the ALARM output is OFF.
- \*3 Only for electromagnetic brake motors.
- \*4 The induction motor will not accommodate instantaneous forward/reverse switching.

#### 

Turning the CW operation signal to "ON" causes the motor's output shaft to turn in the CW direction. Turning it to "OFF" triggers an instantaneous stop.

#### **♦** CCW Operation Input

Turning the CCW operation signal to "ON" causes the motor's output shaft to turn in the CCW direction. Turning it to "OFF" triggers an instantaneous stop.

If both the CW and CCW operation signals are simultaneously turned to "ON," the CW operation signal will take priority. Therefore, the wiring must be changed with an induction motor having four lead wires.

#### ♦ Brake Release Input [ALARM-RESET Input]

Functions as a brake release input during normal operation, and as an ALARM-RESET input when the ALARM output is OFF.

#### •When normal: [Brake Release Input]

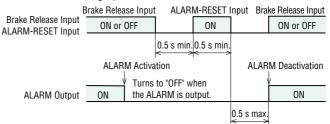
Turning the brake release signal to "ON" disables both the electronic brake and electromagnetic brake. When the CW and CCW operation signals are turned to "OFF," the motor operates via inertial force before coming to a natural stop. When the motor is stationary, the electromagnetic brake is not activated, so the motor's output shaft can be moved freely.

Turning the brake release signal to "OFF" (or leaving the signal unconnected) and turning both CW and CCW operation signals to "OFF" will activate the electronic brake and electromagnetic brake, bringing the motor to an instantaneous stop. Once the motor stops, the electronic brake will release automatically. However, the electromagnetic brake will continue to operate and hold the load.

#### •When ALARM output is OFF: [ALARM-RESET Input]

When ALARM output is turned OFF, turn all input signals "OFF" and input 0.5 seconds or more for ALARM-RESET input.

Wait at least 0.5 seconds after turning the ALARM-RESET input OFF before restarting operation.



It is also possible to deactivate the alarm by turning off the power and turning it on again. Turn off the DC or AC power, and turn all input signals "OFF" before turning on the power again.

#### 

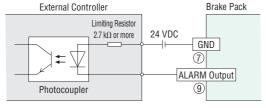
Since the **\$B50W** ALARM output function detects the operations of the thermal protector, the current flowing in the motor is monitored. Operation occurs under the following conditions:

- •When the thermal protector built-in to the motor is opened
- •When there is improper connection/disconnection of the power supply cable and motor cable
- •When the input signal is turned "ON" before the AC power is turned on
- •When the AC power is turned off while the motor is in operation or while it is stopped

In the above conditions, state of the **SB50W** ALARM output is "OFF," the ALARM indicator lamp (red) on the panel lights up, and power supply to the motor is stopped.

With electromagnetic brake motors, the brake is activated in order to hold the load in position.

\* When the DC power is turned on, the alarm indication lamp lights up instantaneously, but this is not an abnormality.



Use a power source of 26.4 VDC or less, and limit the output current to 10 mA or less.

### Operating/Braking Repetition Cycle

The repeated operation and braking of a motor will cause about a temperature increase in the motor and brake pack, thereby limiting the continuous operating time.

Observe the repetition cycle given in the table below for the operation and braking of the motor. The motor may generate heat depending on the conditions in which it is driven. Ensure that the temperature of the motor case does not exceed 90°C.

Motor Output Power	Repetition Cycle
1 W~25 W	2 seconds or more
40 W~90 W	4 seconds or more

(A repetition cycle of two seconds represents operation for one second and stopping for one second.)

## **Accessories**

### ■ Motor/Gearhead Mounting Brackets (RoHS)

Mounting Brackets for attaching and securing a motor and gearhead. They are high-strength type, which can be used with high power motors/gearheads. These brackets come with tapped holes. To mount the motor and gearhead, simply fasten with the screws provided to the gearhead. To mount the motor alone, mounting screws must be provided separately.

Please note that these mounting brackets cannot be used with the following products.

• Right-angle gearheads (**RH** type, **RA** type)



### For Motor Frame Size: ☐42 mm

#### • Model: **SOLOM3**

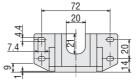
Mass: 85 g Material: Aluminum CAD A320

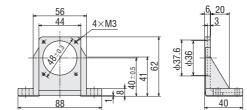
#### 

#### **OGN** Gearhead

Motor with the flame size of □42 mm

#### Dimensions (Unit = mm)





### For Motor Frame Size: ☐60 mm

#### Model: SOL2M4

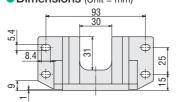
Mass: 135 g Material: Aluminum CAD A321

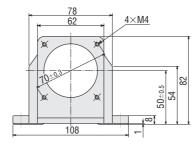
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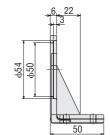
#### **2GN** Gearhead

Motor with the flame size of □60 mm

#### • Dimensions (Unit = mm)







### ■For Motor Frame Size: 70 mm

#### • Model: **SOL3M5**

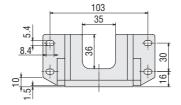
Mass: 175 g Material: Aluminum CAD A322

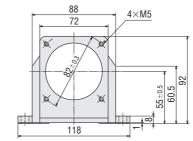
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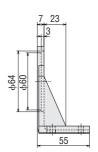
#### **3GN** Gearhead

Motor with the flame size of  $\Box 70~\text{mm}$ 

● Dimensions (Unit = mm)







### ■For Motor Frame Size: 80 mm

#### Model: SOL4M5

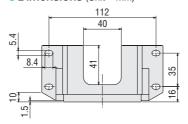
Mass: 210 g Material: Aluminum CAD A236

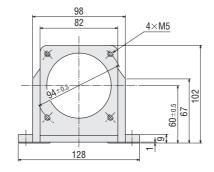
#### 

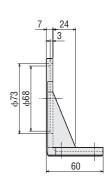
#### 4GN Gearhead

Motor with the flame size of □80 mm

#### ● Dimensions (Unit = mm)







### ■For Motor Frame Size: 90 mm

### • Model: SOL5M6

Mass: 270 g Material: Aluminum CAD A238

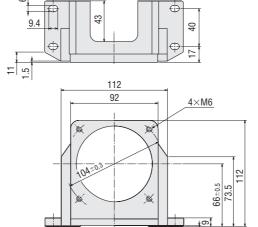
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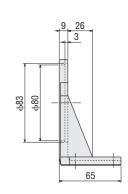
#### 5GN Gearhead

**5GE** Gearhead

Motor with the flame size of  $\square 90 \text{ mm}$ 

### • Dimensions (Unit = mm)





### Flexible Couplings (RoHS)

These products are the clamping type couplings to connect between the shaft of motor/gearhead and the shaft of the equipment to be connected.

Once the motor and gearhead are determined, the coupling can be done.



#### Features

- Couplings come with shaft holes and have standardized combinations for different diameter shaft holes.
- Characteristics are the same for clockwise and counterclockwise rotation.
- Oil-resistant and electrically insulated.
- •Aluminum alloy construction.
- •The shaft being driven is not damaged, since shafts are joined by clamping.
- Easy installation due to a separated hub and sleeve design.

Gearhead Model	Coupling Type
0GN□K	MCL20
2GN□5	MCL20
	MCL30
3GN□S	MCL30
4GN□S	MCL30
4GN <b>□RA</b>	MCL40
5GN□S	MCL30
5GN <b>□RA</b>	MCL40
5GE□S	MCL40
5GE□RA	MCL55

<sup>\*</sup>Type of coupling varies depending on condition of the load.

### ■CR Circuit for Surge Suppression (RoHS)

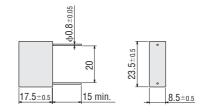
This product is used to protect the contacts of the relay and/ or switch used for controlling the reversal of direction and the electromagnetic brake.





### Dimensions (Unit = mm)

Mass: 5 g



# **Oriental motor**

This product is manufactured at a plant certified with the international standards ISO 9001 (for quality assurance) and ISO 14001 (for systems of environmental management).

Specifications are subject to change without notice. This catalogue was published in November, 2008.

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