

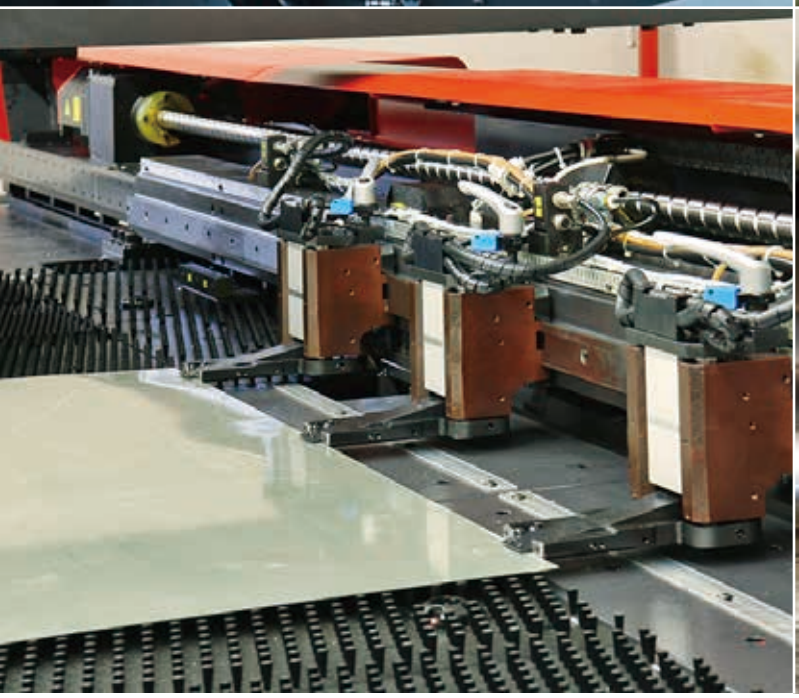


Automation for a Changing World

Delta AC Servo Drive & Motor
ASDA-A2 Series

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DELTA

Smarter. Greener. Together.

Product Line-up

220V Series

Servo Motors				
Motor Series		Phase	Rated Output Power (W)	Model Name
Low Inertia	ECMA-C 3000 r/min	1-phase / 3-phase	50	ECMA-C1040F □ S
			100	ECMA-C △ 0401 □ S
			200	ECMA-C △ 0602 □ S
			400	ECMA-C △ 0604 □ S
			400	ECMA-C △ 0804 □ 7
			750	ECMA-C △ 0807 □ S
			750	ECMA-C △ 0907 □ S
			1000	ECMA-C △ 0910 □ S
			1000	ECMA-C △ 1010 □ S
			2000	ECMA-C △ 1020 □ S
			3000	ECMA-C △ 1330 □ 4
Medium Inertia	ECMA-E 2000 r/min	1-phase / 3-phase	500	ECMA-E △ 1305 □ S
			1000	ECMA-E △ 1310 □ S
			1500	ECMA-E △ 1315 □ S
			2000	ECMA-E △ 1320 □ S
			2000	ECMA-E △ 1820 □ S
			3000	ECMA-E △ 1830 □ S
			3500	ECMA-E △ 1835 □ S
Medium-High Inertia	ECMA-F 1500 r/min	1-phase / 3-phase	500	ECMA-F △ 1305 □ S
			850	ECMA-F △ 1308 □ S
			1300	ECMA-F △ 1313 □ S
			1800	ECMA-F △ 1318 □ S
			3000	ECMA-F △ 1830 □ S
			4500	ECMA-F △ 1845 □ S
			5500	ECMA-F △ 1855 □ 3
			7500	ECMA-F △ 1875 □ 3
			11000	ECMA-F1221B □ 3
			15000	ECMA-F1221F □ S
High Inertia	ECMA-C/G 3000 r/min	1-phase / 3-phase	400	ECMA-C △ 0604 □ H
			750	ECMA-C △ 0807 □ H
			300	ECMA-G △ 1303 □ S
			600	ECMA-G △ 1306 □ S
			900	ECMA-G △ 1309 □ S

1) The boxes (□) at the ends of the servo drive model names are for optional configurations. For the actual model name, please refer to the model explanation of
2) The boxes (△) in the model names represent encoder type. △ =1: Incremental encoder, 20-bit; △ =2: Incremental encoder, 17-bit; △ =A: Absolute type
3) The boxes (□) in the model names represent shaft end/brake or the number of oil seal.

		Servo Drives		
Rated current (Arms)	Maximum current (A)	Model Name	Continuous Output Current (Arms)	Max. Instantaneous Current (A)
0.69	2.05	ASD-A2-0121-□	0.90	2.70
0.90	2.70			
1.55	4.65	ASD-A2-0221-□	1.55	4.65
2.60	7.80	ASD-A2-0421-□	2.60	7.80
2.60	7.80			
5.10	15.30	ASD-A2-0721-□	5.10	15.30
3.66	11.00			
4.25	12.37	ASD-A2-1021-□	7.30	21.90
7.30	21.90			
12.05	36.15	ASD-A2-2023-□	13.40	40.20
17.2	47.5	ASD-A2-3023-□	19.40	58.20
2.90	8.70	ASD-A2-0421-□	2.60	7.80
		ASD-A2-0721-□	5.10	15.30
5.60	16.80	ASD-A2-1021-□	7.30	21.90
8.30	24.90	ASD-A2-1521-□	8.66	24.90
11.01	33.03	ASD-A2-2023-□	13.40	40.20
11.22	33.66			
16.10	48.30	ASD-A2-3023-□	19.40	58.20
19.20	57.60			
3.90	12.10	ASD-A2-0721-□	5.10	15.30
7.10	19.40	ASD-A2-1021-□	7.30	21.90
12.60	38.60	ASD-A2-2023-□	13.40	40.20
13.00	36.00			
19.40	58.20	ASD-A2-3023-□	19.40	58.20
32.50	81.30	ASD-A2-4523-□	32.50	70.7
		ASD-A2-5523-□	40.00	106
40.00	100.00	ASD-A2-5523-□	40.00	106
47.50	118.80	ASD-A2-7523-□	47.50	141.1
51.80	129.50	ASD-A2-1B23-□	54.40	141.1
67	162	ASD-A2-1F23-□	70.00	212.2
2.60	7.80	ASD-A2-0421□	2.60	7.80
5.10	15.30	ASD-A2-0721-□	5.10	15.30
2.50	7.50	ASD-A2-0421-□	2.60	7.80
4.80	14.40	ASD-A2-0721-□	5.10	15.30
7.50	22.50	ASD-A2-1021-□	7.30	21.90

the servo drive.

Product Line-up

400V Series

Servo Motors				
Motor Series		Phase	Rated Output Power (W)	Model Name
Low Inertia	ECMA-J 3000 r/min	3-phase	400	ECMA-J △ 0604 □ S
			750	ECMA-J △ 0807 □ S
			750	ECMA-J △ 0907 □ S
			1000	ECMA-J △ 0910 □ S
			1000	ECMA-J △ 1010 □ S
			2000	ECMA-J △ 1020 □ S
			3000	ECMA-J △ 1330 □ 4
Medium Inertia	ECMA-K 2000 r/min	3-phase	750	ECMA-K △ 1305 □ S
			1000	ECMA-K △ 1310 □ S
			1500	ECMA-K △ 1315 □ S
			2000	ECMA-K △ 1320 □ S
			2000	ECMA-K △ 1820 □ S
Medium-High Inertia	ECMA-L 1500 r/min	3-phase	750	ECMA-L △ 1305 □ S
			850	ECMA-L △ 1308 □ S
			1300	ECMA-L △ 1313 □ S
			3000	ECMA-L △ 1830 □ S
			4500	ECMA-L △ 1845 □ S
			5500	ECMA-L △ 1855 □ 3
			7500	ECMA-L △ 1875 □ 3
			11000	ECMA-L1221B □ 3
			15000	ECMA-L1221F □ 3
High Inertia	ECMA-M 3000 r/min	3-phase	900	ECMA-M △ 1309 □ S

NOTE

1) The boxes (□) at the ends of the servo drive model names are for optional configurations. For the actual model name, please refer to the model explanatio
2) The boxes (△) in the model names represent encoder type. △ =1: Incremental encoder, 20-bit ; △ =2: Incremental encoder, 17-bit; △ =A: Absolute type
3) The boxes (□) in the model names represent shaft end/brake or the number of oil seal.

		Servo Drives		
Rated current (Arms)	Maximum current (A)	Model Name	Continuous Output Current (Arms)	Max. Instantaneous Current (A)
1.62	4.85	ASD-A2-0743-□	3.07	9.21
3.07	9.5	ASD-A2-0743-□	3.07	9.21
		ASD-A2-1043-□	3.52	9.86
2.16	6.37	ASD-A2-0743-□	3.07	9.21
2.4	7.17	ASD-A2-1043-□	3.52	9.86
4.15	12.46	ASD-A2-1543-□	5.02	10.04
		ASD-A2-2043-□	6.66	18.65
7.09	21.28	ASD-A2-2043-□	6.66	18.65
		ASD-A2-3043-□	11.9	33.2
9.8	29.99	ASD-A2-3043-□	11.9	33.32
1.7	5.2	ASD-A2-0743-□	3.07	9.21
3.52	10.56	ASD-A2-1043-□	3.52	9.86
		ASD-A2-1543-□	5.02	10.04
		ASD-A2-2043-□	6.66	18.65
5.02	15.06	ASD-A2-1543-□	5.02	10.04
		ASD-A2-2043-□	6.66	18.65
6.66	19.98	ASD-A2-2043-□	6.66	18.65
		ASD-A2-3043-□	11.9	33.32
6.6	19.88	ASD-A2-2043-□	6.66	18.65
		ASD-A2-3043-□	11.9	33.32
2.1	6.1	ASD-A2-0743-□	3.07	9.21
3.4	8.85	ASD-A2-1043-□	3.52	9.86
5.02	15	ASD-A2-1543-□	5.02	10.04
		ASD-A2-2043-□	6.66	18.65
11.53	34.6	ASD-A2-3043-□	11.9	33.32
		ASD-A2-4543-□	20	44
20.8	52	ASD-A2-4543-□	20	44
		ASD-A2-5543-□	22.04	48.49
		ASD-A2-7543-□	28.39	62.46
22.37	56	ASD-A2-5543-□	22.04	48.49
		ASD-A2-7543-□	28.39	62.46
27.3	68.3	ASD-A2-7543-□	28.39	62.46
		ASD-A2-1B43-□	28.1	61.82
		ASD-A2-1F43-□	38.65	85.03
27.2	68	ASD-A2-1B43-□	28.1	61.82
		ASD-A2-1F43-□	38.65	85.03
41.6	100	ASD-A2-1F43-□	38.65	85.03
4.4	13.1	ASD-A2-1543-□	5.02	10.04

n of the servo drive.

Model Explanation

ASDA-A2 Series Servo Drives

ASD - A2[*5] - 04 21 - M

Product Name:
AC Servo Drive

Series:
A2

Rated Output Power

01: 100 W	10: 1 kW	45: 4.5 kW
02: 200 W	15: 1.5 kW	55: 5.5 kW
04: 400 W	20: 2 kW	75: 7.5 kW
07: 750 W	30: 3 kW	1B: 11 kW
		1F: 15 kW

Input Voltage and Phase
21: 220V 1-phase / 3-phase[*6]
23: 220V 3-phase
43: 400V 3-phase

Model Type
(see the table below)

	Type	RS-485 (CN3)	Full-Closed Control (CN5) [*1]	Extension Port for Digital Input (CN7)	EtherCAT [*4]	CANpen	DMCNET	Analog Voltage Control	Pulse Input Port	PR Parameters	E-CAM [*3]
Standard Model	L	○	○	X	X	X	X	○	○	○	X
	U	○	○	○	X	X	X	○	○	○	○
Network Model	E	X	X	○	○	X	X	X	X	○	X
	F	○	○	X	X	X	○	X	X	○ [*2]	X
	M	○	○	X	X	○	X	○	○	○	○

NOTE

1. In PR mode, only A2-F supports full-closed control function.
2. When applying communication mode (A2-E, -F, -M models), PR parameters can be read and written through DMCNET only.
3. E-CAM function can only be used in PR mode.
4. For information about ASDA A2-E EtherCAT interface servo drive, please refer to the ASDA A2-E brochure.
5. For communication mode -F/-M models with 400V/11kW, 15kW is categorized as ASDA-A2R.
6. Rated power of 100W to 1.5kW are marked number 21 with 220V, single-phase and three-phase connections

ECMA Series Servo Motors

ECM A - C1 06 02 E S

Product Name
ECM: Electrical Commutation Motor

Driving Type
A: AC Servo Motor

S: Standard Shaft Diameter
H: High Inertia Model

Shaft Type and Oil Seal	W/O Brake W/O Oil Seal	With Brake W/O Oil Seal	W/O Brake With Oil Seal	With Brake With Oil Seal
Round Shaft (with screw hole)	-	-	C	D
Keyway	E	F	-	-
Keyway (with screw hole)	P	Q	R	S

Series
Rated Voltage / Rated Speed

C: 220V / 3000 r/min	J: 400V / 3000 r/min
E: 220V / 2000 r/min	K: 400V / 2000 r/min
F: 220V / 1500 r/min	L: 400V / 1500 r/min
G: 220V / 1000 r/min	M: 400V / 1000 r/min

Encoder Type

1: Incremental encoder, 20-bit	A: Absolute encoder,
2: Incremental encoder, 17-bit	Single-turn: 17-bit
3: 2500 ppr	Multi-turn: 16-bit

Motor Frame Size

04: 40 mm	10: 100 mm
06: 60 mm	13: 130 mm
08: 80 mm	18: 180 mm
09: 86 mm	22: 220 mm

Rated Output Power

0F: 50 W	08: 850 W	35: 3.5 kW
01: 100 W	09: 900 W	45: 4.5 kW
02: 200 W	10: 1 kW	50: 5.0 kW
03: 300 W	13: 1.3 kW	55: 5.5 kW
04: 400 W	15: 1.5 kW	75: 7.5 kW
05: 500 W	18: 1.8 kW	1B: 11 kW
06: 600 W	20: 2 kW	1F: 15 kW
07: 750 W	30: 3 kW	

Servo Motor Specifications

Low Inertia Series- 220V Series

ECMA Series	C104	C △ 04	C △ 06		C △ 08		C △ 09		C △ 10		C △ 13
	0F	01	02	04 □ S	04	07	07	10	10	20	30
Rated output power (kW)	0.05	0.1	0.2	0.4	0.4	0.75	0.75	1.0	1.0	2.0	3.0
Rated torque (N-m)*1	0.159	0.32	0.64	1.27	1.27	2.39	2.39	3.18	3.18	6.37	9.55
Maximum torque (N-m)	0.477	0.96	1.92	3.82	3.82	7.16	7.14	8.78	9.54	19.11	28.65
Rated speed (r/min)	3000						3000		3000		3000
Maximum speed (r/min)	5000						3000		5000		4500
Rated current (A)	0.69	0.90	1.55	2.6	2.6	5.1	3.66	4.25	7.3	12.05	17.2
Maximum current (A)	2.05	2.70	4.65	7.8	7.8	15.3	11	12.37	21.9	36.15	47.5
Power rating (kW/s)	12.27	27.7	22.4	57.6	24.0	50.4	29.6	38.6	38.1	90.6	71.8
Rotor moment of inertia ($x10^{-4}$kg-m^2)	0.0206	0.037	0.177	0.277	0.68	1.13	1.93	2.62	2.65	4.45	12.7
Mechanical time constant (ms)	1.2	0.75	0.80	0.53	0.74	0.63	1.72	1.20	0.74	0.61	1.11
Torque constant-KT (N-m/A)	0.23	0.36	0.41	0.49	0.49	0.47	0.65	0.75	0.44	0.53	0.557
Voltage constant-KE (mV/(r/min)	9.8	13.6	16	17.4	18.5	17.2	24.2	27.5	16.8	19.2	20.98
Armature resistance (Ohm)	12.7	9.30	2.79	1.55	0.93	0.42	1.34	0.897	0.20	0.13	0.0976
Armature inductance (mH)	26	24.0	12.07	6.71	7.39	3.53	7.55	5.7	1.81	1.50	1.21
Electrical time constant (ms)	2.05	2.58	4.3	4.3	7.96	8.36	5.66	6.35	9.3	11.4	12.4
Insulation class	Class A (UL), Class B (CE)										
Insulation resistance	100MΩ , DC 500V above										
Insulation strength	1.8k Vac,1 sec										
Weight (kg)(without brake)	0.42	0.5	1.2	1.6	2.1	3.0	2.9	3.8	4.3	6.2	7.8
Weight (kg)(with brake)	--	0.8	1.5	2.0	2.9	3.8	3.69	5.5	4.7	7.2	9.2
Max. radial shaft load (N)	78.4	78.4	196	196	245	245	245	245	490	490	490
Max. thrust shaft load (N)	39.2	39.2	68	68	98	98	98	98	98	98	98
Power rating (kW/s)(with brake)	--	25.6	21.3	53.8	22.1	48.4	29.3	37.9	30.4	82	65.1
Rotor moment of inertia ($x10^{-4}$kg-m^2)(with brake)	--	0.04	0.19	0.30	0.73	1.18	1.95	2.67	3.33	4.95	14.0
Mechanical time constant (ms)(with brake)	--	0.81	0.85	0.57	0.78	0.65	1.74	1.22	0.93	0.66	1.22
Brake holding torque [Nt-m (min)]*2	--	0.3	1.3	1.3	2.5	2.5	2.5	2.5	8	8	10.0
Brake power consumption (at 20˚C)[W]	--	7.3	6.5	6.5	8.2	8.2	8.2	8.2	18.7	18.7	19.0
Brake release time [ms (Max)]	--	5	10	10	10	10	10	10	10	10	10
Brake pull-in time [ms (Max)]	--	25	70	70	70	70	70	70	70	70	70
Vibration grade (μm)	15										
Operating temperature (˚C)	0ºC to 40ºC										
Storage temperature (˚C)	-10ºC to 80ºC										
Operating humidity	20 to 90%RH (non-condensing)										
Storage humidity	20 to 90%RH (non-condensing)										
Vibration capacity	2.5G										
IP Rating	IP65 (when waterproof connectors are used, or when an oil seal is used to be fitted to the rotating shaft (an oil seal model is used))										
Approvals	CE c UL us										

*1. Rate torque values are continuous permissible values at 0 ~ 40˚C ambient temperature when attaching with the sizes of heatsinks listed below:
ECMA-_ _ 04 / 06 / 08: 250 mm x 250 mm x 6 mm
ECMA-_ _ 10: 300 mm x 300 mm x 12 mm
ECMA-_ _ 13: 400 mm x 400 mm x 20 mm
ECMA-_ _ 18: 550 mm x 550 mm x 30 mm
ECMA-_ _ 22: 650 mm x 650 mm x 35 mm
Material type : Aluminum – F40, F60, F80, F100, F130, F180, F220

*2. The holding brake is used to hold the motor shaft, not for braking the rotation. Never use it for decelerating or stopping the machine.

Medium Series- 220V Series

ECMA Series	E △ 13				E △ 18		
	05	10	15	20	20	30	35
Rated output power (kW)	0.5	1.0	1.5	2.0	2.0	3.0	3.5
Rated torque (N-m)*1	2.39	4.77	7.16	9.55	9.55	14.32	16.71
Maximum torque (N-m)	7.16	14.3	21.48	28.65	28.65	42.97	50.13
Rated speed (r/min)	2000						
Maximum speed (r/min)	3000						
Rated current (A)	2.9	5.6	8.3	11.01	11.22	16.1	19.2
Maximum current (A)	8.7	16.8	24.9	33.03	33.66	48.3	57.6
Power rating (kW/s)	7.0	27.1	45.9	62.5	26.3	37.3	50.8
Rotor moment of inertia ($x10^{-4}$kg-m^2)(without brake)	8.17	8.41	11.18	14.59	34.68	54.95	54.95
Mechanical time constant (ms)	1.91	1.51	1.10	0.96	1.62	1.06	1.08
Torque constant-KT (N-m/A)	0.83	0.85	0.87	0.87	0.85	0.89	0.87
Voltage constant-KE (mV/(r/min)	30.9	31.9	31.8	31.8	31.4	32.0	32
Armature resistance (Ohm)	0.57	0.47	0.26	0.174	0.119	0.052	0.052
Armature inductance (mH)	7.39	5.99	4.01	2.76	2.84	1.38	1.38
Electrical time constant (ms)	12.96	12.88	15.31	15.86	23.87	26.39	26.39
Insulation class	Class A (UL), Class B (CE)						
Insulation resistance	100MΩ , DC 500V above						
Insulation strength	1.8k Vac,1 sec						
Weight (kg)(without brake)	6.8	7.0	7.5	7.8	13.5	18.5	18.5
Weight (kg)(with brake)	8.2	8.4	8.9	9.2	17.5	22.5	22.5
Max. radial shaft load (N)	490	490	490	490	1176	1470	1470
Max. thrust shaft load (N)	98	98	98	98	490	490	490
Power rating (kW/s)(with brake)	6.4	24.9	43.1	57.4	24.1	35.9	48.9
Rotor moment of inertia ($x10^{-4}$kg-m^2)(with brake)	8.94	9.14	11.90	15.88	37.86	57.06	57.06
Mechanical time constant (ms)(with brake)	2.07	1.64	1.19	1.05	1.77	1.10	1.12
Brake holding torque [Nt-m (min)]*2	10.0	10.0	10.0	10.0	25.0	25.0	25.0
Brake power consumption (at 20˚C)[W]	19.0	19.0	19.0	19.0	20.4	20.4	20.4
Brake release time [ms (Max)]	10	10	10	10	10	10	10
Brake pull-in time [ms (Max)]	70	70	70	70	70	70	70
Vibration grade (μm)	15						
Operating temperature (˚C)	0ºC to 40ºC						
Storage temperature (˚C)	-10ºC to 80ºC						
Operating humidity	20 to 90%RH (non-condensing)						
Storage humidity	20 to 90%RH (non-condensing)						
Vibration capacity	2.5G						
IP Rating	IP65 (when waterproof connectors are used, or when an oil seal is used to be fitted to the rotating shaft (an oil seal model is used))						
Approvals	CE c UL us						

*1. Rate torque values are continuous permissible values at 0 ~ 40˚C ambient temperature when attaching with the sizes of heatsinks listed below:
ECMA-_ _ 04 / 06 / 08: 250 mm x 250 mm x 6 mm
ECMA-_ _ 10: 300 mm x 300 mm x 12 mm
ECMA-_ _ 13: 400 mm x 400 mm x 20 mm
ECMA-_ _ 18: 550 mm x 550 mm x 30 mm
ECMA-_ _ 22: 650 mm x 650 mm x 35 mm
Material type : Aluminum – F40, F60, F80, F100, F130, F180, F220
*2. The holding brake is used to hold the motor shaft, not for braking the rotation. Never use it for decelerating or stopping the machine.

Servo Motor Specifications

Medium-High Inertia Series- 220V Series

ECMA Series	F △ 13				F △ 18				F122	
	05	08	13	18	30	45	55	75	1B	1F
Rated output power (kW)	0.5	0.85	1.3	1.8	3.0	4.5	5.5	7.5	11	15
Rated torque (N-m)*1	3.18	5.41	8.34	11.48	19.10	28.65	35.01	47.74	70	95.4
Maximum torque (N-m)	8.92	13.8	23.3	28.7	57.29	71.62	87.53	119.36	175	224.0
Rated speed (r/min)	1500									
Maximum speed (r/min)	3000								2000	
Rated current (A)	3.9	7.1	12.6	13	19.4	32.5	40.0	47.5	51.8	67
Maximum current (A)	12.1	19.4	38.6	36	58.2	81.3	100.0	118.8	129.5	162
Power rating (kW/s)	9.8	21.52	34.78	52.93	66.4	105.5	122.9	159.7	144.9	201.8
Rotor moment of inertia ($x10^{-4}$kg-m^2)(without brake)	10.3	13.6	20	24.9	54.95	77.75	99.78	142.7	338	451
Mechanical time constant (ms)	2.8	2.43	1.62	1.7	1.28	0.92	0.96	0.63	1.38	1.23
Torque constant-KT (N-m/A)	0.82	0.76	0.66	0.88	0.98	0.88	0.88	1.01	1.37	1.42
Voltage constant-KE (mV/(r/min)	29.5	29.2	24.2	32.2	35.0	32.0	31.0	35.5	49	50
Armature resistance (Ohm)	0.624	0.38	0.124	0.185	0.077	0.032	0.025	0.015	0.026	0.0184
Armature inductance (mH)	7	4.77	1.7	2.6	1.27	0.89	0.60	0.40	0.65	0.48
Electrical time constant (ms)	11.22	12.55	13.71	14.05	16.5	27.8	24.0	26.7	24.79	26.09
Insulation class	Class A (UL), Class B (CE)									
Insulation resistance	100MΩ , DC 500V above									
Insulation strength	1.8k Vac,1 sec									
Weight (kg)(without brake)	6.3	8.6	9.4	10.5	18.5	23.5	30.5	40.5	56.4	75
Weight (kg)(with brake)	7.7	10.0	10.8	11.9	22.5	29	36	46	68.4	87
Max. radial shaft load (N)	490	490	490	490	1470	1470	1764	1764	3300	3300
Max. thrust shaft load (N)	98	98	98	98	490	490	588	588	1100	1100
Power rating (kW/s)(with brake)	8.8	19.78	32.66	50.3	63.9	101.8	119.4	156.6	141.4	197.1
Rotor moment of inertia ($x10^{-4}$kg-m^2)(with brake)	11.5	14.8	21.3	26.2	57.06	80.65	102.70	145.55	346.5	461.8
Mechanical time constant (ms)(with brake)	3.12	2.65	1.73	1.79	1.33	0.96	0.99	0.64	1.41	1.25
Brake holding torque[Nt-m(min)]*2	10	10.0	10.0	10.0	25.0	55.0	55.0	55.0	115	115
Brake power consumption (at 20˚C)[W]	19	19.0	19.0	19.0	20.4	19.9	19.9	19.9	28.8	28.8
Brake release time [ms (Max)]	10	10	10	10	10	10	10	10	10	10
Brake pull-in time [ms (Max)]	70	70	70	70	70	70	70	70	70	70
Vibration grade (μm)	15									
Operating temperature (˚C)	0ºC to 40ºC									
Storage temperature (˚C)	-10ºC to 80ºC									
Operating humidity	20 to 90%RH (non-condensing)									
Storage humidity	20 to 90%RH (non-condensing)									
Vibration capacity	2.5G									
IP Rating	IP65 (when waterproof connectors are used, or when an oil seal is used to be fitted to the rotating shaft (an oil seal model is used))									
Approvals	CE c UL us									

*1. Rate torque values are continuous permissible values at 0 ~ 40˚C ambient temperature when attaching with the sizes of heatsinks listed below:
ECMA-_ _ 04 / 06 / 08: 250 mm x 250 mm x 6 mm
ECMA-_ _ 10: 300 mm x 300 mm x 12 mm
ECMA-_ _ 13: 400 mm x 400 mm x 20 mm
ECMA-_ _ 18: 550 mm x 550 mm x 30 mm
ECMA-_ _ 22: 650 mm x 650 mm x 35 mm
Material type : Aluminum – F40, F60, F80, F100, F130, F180, F220

*2. The holding brake is used to hold the motor shaft, not for braking the rotation. Never use it for decelerating or stopping the machine.

High Inertia Series- 220V Series

ECMA Series	C △ 06	C △ 08	G △ 13		
	04□H	07□H	03	06	09
Rated output power (kW)	0.4	0.75	0.3	0.6	0.9
Rated torque (N-m)*1	1.27	2.39	2.86	5.73	8.59
Maximum torque (N-m)	3.82	7.16	8.59	17.19	21.48
Rated speed (r/min)	3000		1000		
Maximum speed (r/min)	5000		2000		
Rated current (A)	2.6	5.1	2.5	4.8	7.5
Maximum current (A)	7.8	15.3	7.5	14.4	22.5
Power rating (kW/s)	21.7	19.63	10.0	39.0	66.0
Rotor moment of inertia ($x10^{-4}$kg-m^2)(without brake)	0.743	2.91	8.17	8.41	11.18
Mechanical time constant (ms)	1.42	1.6	1.84	1.40	1.06
Torque constant-KT (N-m/A)	0.49	0.47	1.15	1.19	1.15
Voltage constant-KE (mV/(r/min)	17.4	17.2	42.5	43.8	41.6
Armature resistance (Ohm)	1.55	0.42	1.06	0.82	0.43
Armature inductance (mH)	6.71	3.53	14.29	11.12	6.97
Electrical time constant (ms)	4.3	8.36	13.5	13.50	16.06
Insulation class	Class A (UL), Class B (CE)				
Insulation resistance	100MΩ , DC 500V above				
Insulation strength	1.8k Vac,1 sec				
Weight (kg)(without brake)	1.8	3.4	6.8	7.0	7.5
Weight (kg)(with brake)	2.2	3.9	8.2	8.4	8.9
Max. radial shaft load (N)	196	245	490	490	490
Max. thrust shaft load (N)	68	98	98	98	98
Power rating (kW/s)(with brake)	21.48	19.3	9.2	35.9	62.1
Rotor moment of inertia ($x10^{-4}$kg-m^2)(with brake)	0.751	2.96	8.94	9.14	11.9
Mechanical time constant (ms)(with brake)	1.43	1.62	2.0	1.51	1.13
Brake holding torque [Nt-m (min)]*2	1.3	2.5	10.0	10.0	10.0
Brake power consumption (at 20˚C)[W]	6.5	8.2	19.0	19.0	19.0
Brake release time [ms (Max)]	10	10	10	10	10
Brake pull-in time [ms (Max)]	70	70	70	70	70
Vibration grade (μm)	15				
Operating temperature (˚C)	0ºC to 40ºC				
Storage temperature (˚C)	-10ºC to 80ºC				
Operating humidity	20 to 90%RH (non-condensing)				
Storage humidity	20 to 90%RH (non-condensing)				
Vibration capacity	2.5G				
IP Rating	IP65 (when waterproof connectors are used, or when an oil seal is used to be fitted to the rotating shaft (an oil seal model is used))				
Approvals	CE cULus				

*1. Rate torque values are continuous permissible values at 0 ~ 40˚C ambient temperature when attaching with the sizes of heatsinks listed below:
ECMA-_ _ 04 / 06 / 08: 250 mm x 250 mm x 6 mm
ECMA-_ _ 10: 300 mm x 300 mm x 12 mm
ECMA-_ _ 13: 400 mm x 400 mm x 20 mm
ECMA-_ _ 18: 550 mm x 550 mm x 30 mm
ECMA-_ _ 22: 650 mm x 650 mm x 35 mm
Material type : Aluminum – F40, F60, F80, F100, F130, F180, F220
*2. The holding brake is used to hold the motor shaft, not for braking the rotation. Never use it for decelerating or stopping the machine.

Servo Motor Specifications

Low / Medium Series- 400V Series

ECMA Series	J △ 06	J △ 08	J △ 09		J △ 10		J △ 13	K △ 13				K △ 18
	04	07	07	10	10	20	30	05	10	15	20	20
Rated output power (kW)	0.4	0.75	0.75	1	1.0	2.0	3.0	0.5	1.0	1.5	2.0	2.0
Rated torque (N-m)*1	1.27	2.39	2.39	3.18	3.18	6.37	9.55	2.39	4.77	7.16	9.55	9.55
Maximum torque (N-m)	3.82	7.16	7.14	8.78	9.54	19.1	28.65	7.16	14.32	21.48	28.65	28.65
Rated speed (r/min)	3000		3000		3000		3000	2000				
Maximum speed (r/min)	5000		3000		5000		4500	3000				
Rated current (A)	1.62	3.07	2.16	2.4	4.15	7.09	9.8	1.7	3.52	5.02	6.66	6.6
Maximum current (A)	4.85	9.5	6.37	7.17	12.46	21.28	29.99	5.2	10.56	15.06	19.98	19.88
Power rating (kW/s)	58.2	50.4	29.6	38.6	38.2	91.2	71.8	6.99	27.1	45.9	62.5	26.3
Rotor moment of inertia ($x10^{-4}$kg-m^2)(without brake)	0.277	1.13	1.93	2.62	2.65	4.45	12.7	8.17	8.41	11.18	14.59	34.68
Mechanical time constant (ms)	0.47	0.66	1.56	1.06	0.77	0.58	0.99	2.08	1.80	1.24	1.04	1.74
Torque constant-KT (N-m/A)	0.79	0.78	1.12	1.29	0.77	0.9	0.97	1.41	1.35	1.43	1.43	1.45
Voltage constant-KE (mV/(r/min)	30.6	28.24	42	50.9	29.0	34.4	37.3	51.5	53.2	55	55	54.0
Armature resistance (Ohm)	3.95	1.22	3.62	2.58	0.617	0.388	0.269	1.76	1.47	0.83	0.57	0.376
Armature inductance (mH)	21.3	10.68	21.2	15.28	6.03	4.62	3.55	22.4	17.79	11.67	8.29	7.87
Electrical time constant (ms)	5.39	8.75	5.85	5.93	9.77	11.9	13.2	12.73	12.04	14.04	14.39	20.9
Insulation class	Class A (UL), Class B (CE)											
Insulation resistance	100MΩ, DC 500V above											
Insulation strength	2.3k Vac, 1 sec											
Weight (kg)(without brake)	1.6	3.0	2.9	3.8	4.3	6.2	7.8	6.8	7.0	7.5	7.8	13.5
Weight (kg)(with brake)	2	3.8	-	-	4.7	7.2	9.2	8.2	8.4	8.9	9.2	17.5
Max. radial shaft load (N)	19.6	245	245	245	490	490	490	490	490	490	490	1176
Max. thrust shaft load (N)	68	98	98	98	98	98	98	98	98	98	98	490
Power rating (kW/s)(with brake)	53.8	48.4	29.3	37.9	30.4	82	65.1	6.39	24.9	43.1	59.7	24.1
Rotor moment of inertia ($x10^{-4}$kg-m^2)(with brake)	0.3	1.18	1.95	2.67	3.33	4.95	14.0	8.94	9.14	11.90	15.88	37.86
Mechanical time constant (ms)(with brake)	0.52	0.65	1.57	1.08	0.96	0.65	1.09	2.28	1.96	1.32	1.13	1.9
Brake holding torque [Nt-m (min)]*2	1.3	2.5	2.5	2.5	8.0	8.0	10.0	10.0	10.0	10.0	10.0	25.0
Brake power consumption (at 20˚C)[W]	6.5	8.5	8.2	8.2	18.5	18.5	19.0	19.0	19.0	19.0	19.0	20.4
Brake release time [ms (Max)]	10	10	10	10	10	10	10	10	10	10	10	10
Brake pull-in time [ms (Max)]	70	70	70	70	70	70	70	70	70	70	70	70
Vibration grade (μm)	15											
Operating temperature (˚C)	0ºC to 40ºC											
Storage temperature (˚C)	-10ºC to 80ºC											
Operating humidity	20 to 90%RH (non-condensing)											
Storage humidity	20 to 90%RH (non-condensing)											
Vibration capacity	2.5G											
IP Rating	IP65 (when waterproof connectors are used, or when an oil seal is used to be fitted to the rotating shaft (an oil seal model is used))											
Approvals	CE c UL us											

*1. Rate torque values are continuous permissible values at 0 ~ 40˚C ambient temperature when attaching with the sizes of heatsinks listed below:
ECMA-_ _ 08: 250 mm x 250 mm x 6 mm
ECMA-_ _ 13: 400 mm x 400 mm x 20 mm
ECMA-_ _ 18: 550 mm x 550 mm x 30 mm
Material type : Aluminum – F80, F130, F180, F220

*2. The holding brake is used to hold the motor shaft, not for braking the rotation. Never use it for decelerating or stopping the machine.

Medium-High / High Inertia Series- 400V Series

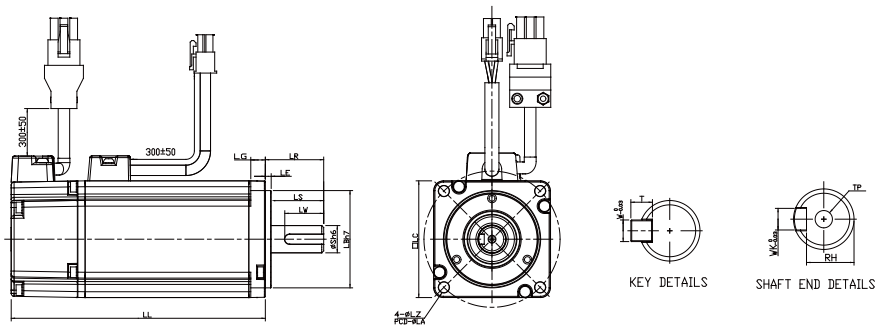
ECMA Series	L △ 13			L △ 18				L122		M △ 13
	05	08	13	30	45	55	75	1B	1F	09
Rated output power (kW)	0.5	0.85	1.3	3.0	4.5	5.5	7.5	11	15	0.9
Rated torque (N-m)*1	3.18	5.39	8.34	19.10	28.65	35.0	47.74	70	95.4	8.59
Maximum torque (N-m)	8.92	13.8	23.3	57.29	71.62	87.53	119.36	175	224	21.48
Rated speed (r/min)				1500				1500		1000
Maximum speed (r/min)				3000				2000		2000
Rated current (A)	2.1	3.4	5.02	11.53	20.8	22.37	27.3	27.2	41.6	4.4
Maximum current (A)	6.1	8.85	15	34.6	52	56	68.3	68	100	13.1
Power rating (kW/s)	7.72	17.0	29.47	66.4	105.5	122.9	159.7	145	201.8	66
Rotor moment of inertia ($x10^{-4}$kg-m^2)(without brake)	13.1	17.1	23.6	54.95	77.75	99.78	142.7	338	451	11.18
Mechanical time constant (ms)	2.3	1.76	1.44	1.11	0.94	0.88	0.77	1.42	1.34	1.21
Torque constant-KT (N-m/A)	1.5	1.59	1.66	1.66	1.38	1.56	1.75	2.57	2.29	1.95
Voltage constant-KE (mV/(r/min)	55.5	58.9	61.1	64.4	53	58.9	66.4	96	83.9	71.7
Armature resistance (Ohm)	1.41	0.92	0.59	0.21	0.09	0.07	0.06	0.0994	0.0545	1.45
Armature inductance (mH)	20	14.1	9.54	4.94	2.36	2.2	1.7	2.51	1.43	23.3
Electrical time constant (ms)	14.1	15.33	16.17	23.97	28.07	27.6	28.29	25.25	26.26	16.07
Insulation class	Class A (UL), Class B (CE)									
Insulation resistance	100MΩ, DC 500V above									
Insulation strength	2.3k Vac,1 sec									
Weight (kg)(without brake)	6.8	8.6	10.7	18.5	23.5	30.5	40.5	56.4	75	7.5
Weight (kg)(with brake)	-	10	--	22.5	29	36	46	68.4	87	8.9
Max. radial shaft load (N)	490	490	490	1470	1470	1764	1764	3300	3300	490
Max. thrust shaft load (N)	98	98	98	490	490	588	588	1100	1100	98
Power rating (kW/s)(with brake)	7.02	14.82	27.82	63.9	101.8	119.4	156.6	141.4	197.1	62
Rotor moment of inertia ($x10^{-4}$kg-m^2)(with brake)	14.4	19.6	25	57.06	80.65	102.70	145.5	346.5	461.8	11.9
Mechanical time constant (ms)(with brake)	2.54	2.02	1.52	1.16	0.95	0.91	0.79	1.46	1.37	1.29
Brake holding torque [Nt-m (min)]*2	10.0	10.0	10.0	25.0	55.0	55.0	55.0	115	115	10.0
Brake power consumption (at 20˚C)[W]	19.0	19.0	19.0	20.4	19.9	19.9	19.9	28.8	28.8	19.0
Brake release time [ms (Max)]	10	10	10	10	10	10	10	10	10	10
Brake pull-in time [ms (Max)]	70	70	70	70	70	70	70	70	70	70
Vibration grade (μm)	15									
Operating temperature (˚C)	0ºC to 40ºC									
Storage temperature (˚C)	-10ºC to 80ºC									
Operating humidity	20 to 90%RH (non-condensing)									
Storage humidity	20 to 90%RH (non-condensing)									
Vibration capacity	2.5G									
IP Rating	IP65 (when waterproof connectors are used, or when an oil seal is used to be fitted to the rotating shaft (an oil seal model is used))									
Approvals	CE c UL us									

*1. Rate torque values are continuous permissible values at 0 ~ 40˚C ambient temperature when attaching with the sizes of heatsinks listed below:
ECMA-_ _ 08: 250 mm x 250 mm x 6 mm
ECMA-_ _ 13: 400 mm x 400 mm x 20 mm
ECMA-_ _ 18: 550 mm x 550 mm x 30 mm
ECMA-_ _ 22: 650 mm x 650 mm x 35 mm
Material type : Aluminum – F80, F130, F180, F220
*2. The holding brake is used to hold the motor shaft, not for braking the rotation. Never use it for decelerating or stopping the machine.

Servo Motor Dimensions

220V Series

Frame Size 86mm and below



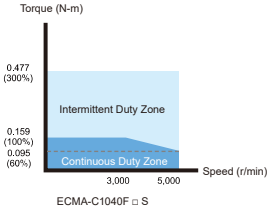
Units: mm

Model	C1040F □ S	C △ 0401 □ S	C △ 0602 □ S	C △ 0604 □ S	C △ 0604 □ H	C △ 0804 □ 7	C △ 0807 □ S	C △ 0807 □ H	C △ 0907 □ S	C △ 0910 □ S
LC	40	40	60	60	60	80	80	80	86	86
LZ	4.5	4.5	5.5	5.5	5.5	6.6	6.6	6.6	6.6	6.6
LA	46	46	70	70	70	90	90	90	100	100
S	8 ($^{+0}_{-0.009}$)	8 ($^{+0}_{-0.009}$)	14 ($^{+0}_{-0.011}$)	14 ($^{+0}_{-0.011}$)	14 ($^{+0}_{-0.011}$)	14 ($^{+0}_{-0.011}$)	19 ($^{+0}_{-0.013}$)	19 ($^{+0}_{-0.013}$)	16 ($^{+0}_{-0.011}$)	16 ($^{+0}_{-0.011}$)
LB	30 ($^{+0}_{-0.021}$)	30 ($^{+0}_{-0.021}$)	50 ($^{+0}_{-0.025}$)	50 ($^{+0}_{-0.025}$)	50 ($^{+0}_{-0.025}$)	70 ($^{+0}_{-0.030}$)	70 ($^{+0}_{-0.030}$)	70 ($^{+0}_{-0.030}$)	80 ($^{+0}_{-0.030}$)	80 ($^{+0}_{-0.030}$)
LL (without brake)	79.1	100.6	105.5	130.7	145.8	112.3	138.3	154.8	130.2	153.2
LL (with brake)	--	136.8	141.6	166.8	176.37	152.8	178	187.8	161.3	184.3
LS	20	20	27	27	27	27	32	32	30	30
LR	25	25	30	30	30	30	35	35	35	35
LE	2.5	2.5	3	3	3	3	3	3	3	3
LG	5	5	7.5	7.5	7.5	8	8	8	8	8
LW	16	16	20	20	20	20	25	25	20	20
RH	6.2	6.2	11	11	11	11	15.5	15.5	13	13
WK	3	3	5	5	5	5	6	6	5	5
W	3	3	5	5	5	5	6	6	5	5
T	3	3	5	5	5	5	6	6	5	5
TP	M3 Depth 8	M3 Depth 8	M4 Depth 15	M4 Depth 15	M4 Depth 15	M4 Depth 15	M6 Depth 20	M6 Depth 20	M5 Depth 15	M5 Depth 15

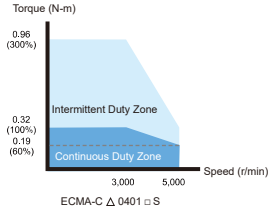
NOTE

1) Dimensions are in millimeters.
2) Dimensions of the servo motors may be revised without prior notice.
3) The boxes (□) in the model names are for optional configurations(keyway, brake and oil seal).
4) The boxes (△) in the model names are for encoder resolution types. (△ =1: Incremental encoder, 20-bit; △ =2: Incremental encoder, 17-bit; △ =A: Absolute type)

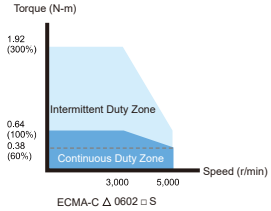
Speed-Torque Curves (T-N Curves)



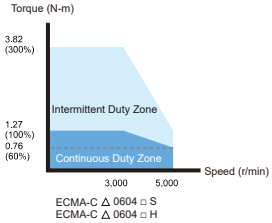
ECMA-C1040F □ S



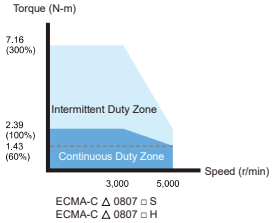
ECMA-C △ 0401 □ S



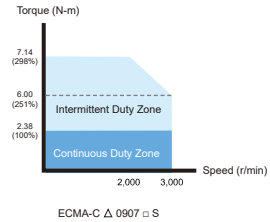
ECMA-C △ 0602 □ S



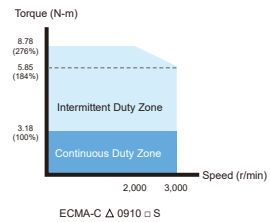
ECMA-C △ 0604 □ S
ECMA-C △ 0604 □ H
ECMA-C △ 0804 □ 7



ECMA-C △ 0807 □ S
ECMA-C △ 0807 □ H



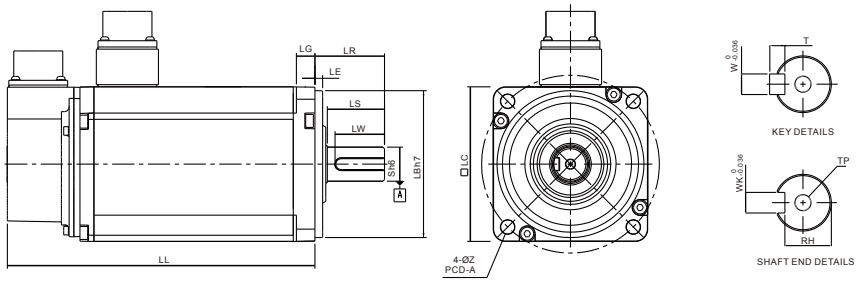
ECMA-C △ 0907 □ S



ECMA-C △ 0910 □ S

220V Series

Frame Size 100mm and 130mm



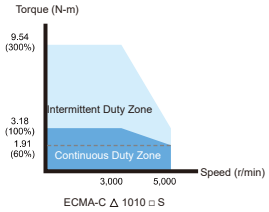
Units: mm

Model	C △ 1010 □ S	C △ 1020 □ S	C △ 1330 □ 4	E △ 1305 □ S	E △ 1310 □ S	E △ 1315 □ S	E △ 1320 □ S
LC	100	100	130	130	130	130	130
LZ	9	9	9	9	9	9	9
LA	115	115	145	145	145	145	145
S	22 ($^{+0}_{-0.013}$)	22 ($^{+0}_{-0.013}$)	24 ($^{+0}_{-0.013}$)	22 ($^{+0}_{-0.013}$)	22 ($^{+0}_{-0.013}$)	22 ($^{+0}_{-0.013}$)	22 ($^{+0}_{-0.013}$)
LB	95 ($^{+0}_{-0.035}$)	95 ($^{+0}_{-0.035}$)	110 ($^{+0}_{-0.035}$)	110 ($^{+0}_{-0.035}$)	110 ($^{+0}_{-0.035}$)	110 ($^{+0}_{-0.035}$)	110 ($^{+0}_{-0.035}$)
LL (without brake)	153.3	199	187.5	147.5	147.5	167.5	187.5
LL (with brake)	192.5	226	216	183.5	183.5	202	216
LS	37	37	47	47	47	47	47
LR	45	45	55	55	55	55	55
LE	5	5	6	6	6	6	6
LG	12	12	11.5	11.5	11.5	11.5	11.5
LW	32	32	36	36	36	36	36
RH	18	18	20	18	18	18	18
WK	8	8	8	8	8	8	8
W	8	8	8	8	8	8	8
T	7	7	7	7	7	7	7
TP	M6 Depth 20	M6 Depth 20	M6 Depth 20	M6 Depth 20	M6 Depth 20	M6 Depth 20	M6 Depth 20

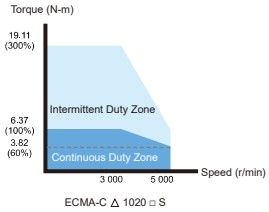
NOTE

1) Dimensions are in millimeters.
2) Dimensions of the servo motors may be revised without prior notice.
3) The boxes (□) in the model names are for optional configurations(keyway, brake and oil seal).
4) The boxes (△) in the model names are for encoder resolution types. (△ =1: Incremental encoder, 20-bit; △ =2: Incremental encoder, 17-bit; △ =A: Absolute type)

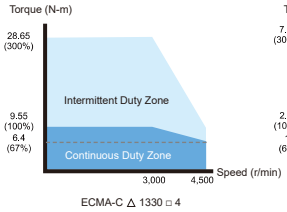
Speed-Torque Curves (T-N Curves)



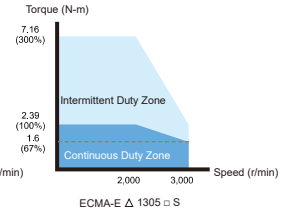
ECMA-C △ 1010 □ S



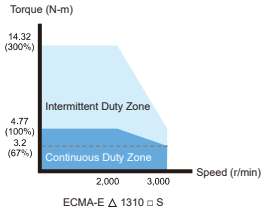
ECMA-C △ 1020 □ S



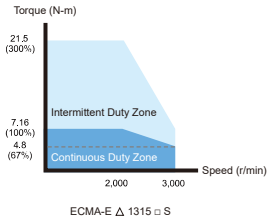
ECMA-C △ 1330 □ 4



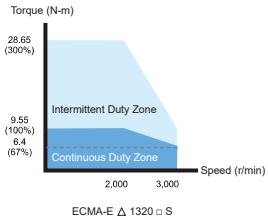
ECMA-E △ 1305 □ S



ECMA-E △ 1310 □ S



ECMA-E △ 1315 □ S

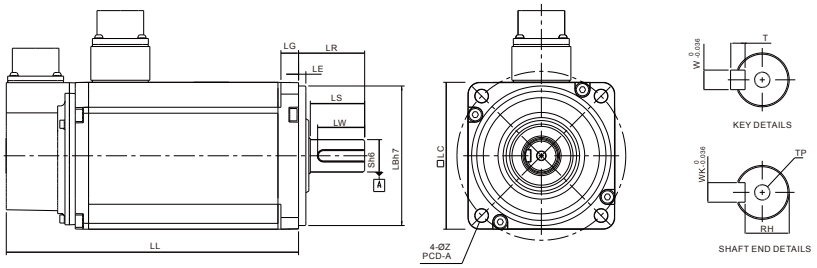


ECMA-E △ 1320 □ S

Servo Motor Dimensions

220V Series

Frame Size 100mm and 130mm



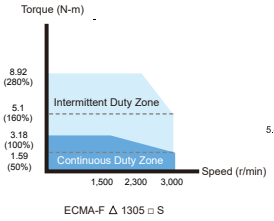
Units: mm

Model	F △ 1305 □ S	F △ 1308 □ S	F △ 1313 □ S	F △ 1318 □ S	G △ 1303 □ S	G △ 1306 □ S	G △ 1309 □ S
LC	130	130	130	130	130	130	130
LZ	9	9	9	9	9	9	9
LA	145	145	145	145	145	145	145
S	22 ($^{+0}_{-0.013}$)	22 ($^{+0}_{-0.013}$)	22 ($^{+0}_{-0.013}$)	22 ($^{+0}_{-0.013}$)	22 ($^{+0}_{-0.013}$)	22 ($^{+0}_{-0.013}$)	22 ($^{+0}_{-0.013}$)
LB	110 ($^{+0}_{-0.035}$)	110 ($^{+0}_{-0.035}$)	110 ($^{+0}_{-0.035}$)	110 ($^{+0}_{-0.035}$)	110 ($^{+0}_{-0.035}$)	110 ($^{+0}_{-0.035}$)	110 ($^{+0}_{-0.035}$)
LL (without brake)	139.5	147.5	187.5	202	147.5	147.5	163.5
LL (with brake)	168	183.5	216	230.7	183.5	183.5	198
LS	47	47	47	47	47	47	47
LR	55	55	55	55	55	55	55
LE	6	6	6	6	6	6	6
LG	11.5	11.5	11.5	11.5	11.5	11.5	11.5
LW	36	36	36	36	36	36	36
RH	18	18	18	18	18	18	18
WK	8	8	8	8	8	8	8
W	8	8	8	8	8	8	8
T	7	7	7	7	7	7	7
TP	M6 Depth 20	M6 Depth 20	M6 Depth 20	M6 Depth 20	M6 Depth 20	M6 Depth 20	M6 Depth 20

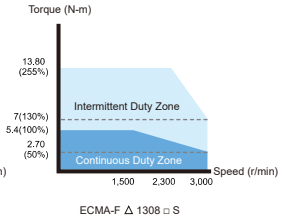
NOTE

1) Dimensions are in millimeters.
2) Dimensions of the servo motors may be revised without prior notice.
3) The boxes (□) in the model names are for optional configurations (keyway, brake and oil seal).
4) The boxes (△) in the model names are for encoder resolution types. (△ =1: Incremental encoder, 20-bit; △ =2: Incremental encoder, 17-bit; △ =A: Absolute type)

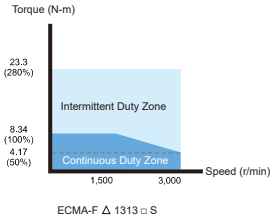
Speed-Torque Curves (T-N Curves)



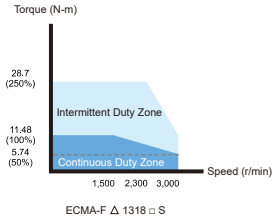
ECMA-F △ 1305 □ S



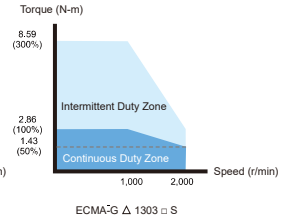
ECMA-F △ 1308 □ S



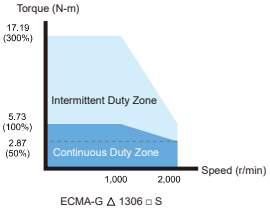
ECMA-F △ 1313 □ S



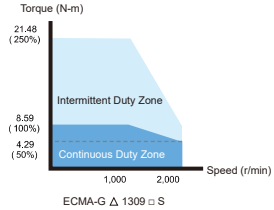
ECMA-F △ 1318 □ S



ECMA-G △ 1303 □ S



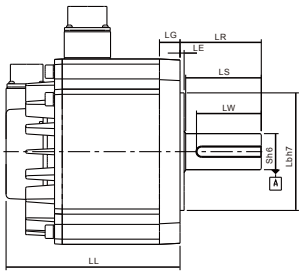
ECMA-G △ 1306 □ S

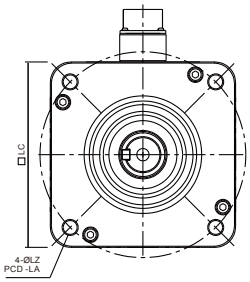


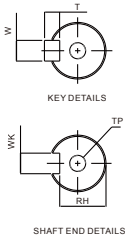
ECMA-G △ 1309 □ S

220V Series

Frame Size 180mm







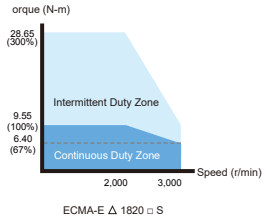
Units: mm

Model	E △ 1820 □ S	E △ 1830 □ S	E △ 1835 □ S	F △ 1845 □ S	F △ 1855 □ 3	F △ 1875 □ 3
LC	180	180	180	180	180	180
LZ	13.5	13.5	13.5	13.5	13.5	13.5
LA	200	200	200	200	200	200
S	35 ($^{+0}_{-0.016}$)	35 ($^{+0}_{-0.016}$)	35 ($^{+0}_{-0.016}$)	35 ($^{+0}_{-0.016}$)	42 ($^{+0}_{-0.016}$)	42 ($^{+0}_{-0.016}$)
LB	114.3 ($^{+0}_{-0.035}$)	114.3 ($^{+0}_{-0.035}$)	114.3 ($^{+0}_{-0.035}$)	114.3 ($^{+0}_{-0.035}$)	114.3 ($^{+0}_{-0.035}$)	114.3 ($^{+0}_{-0.035}$)
LL (without brake)	169	202.1	202.1	235.3	279.7	342.0
LL (with brake)	203.1	235.3	235.3	279.3	311.7	376.1
LS	73	73	73	73	108.5	108.5
LR	79	79	79	79	113	113
LE	4	4	4	4	4	4
LG	20	20	20	20	20	20
LW	63	63	63	63	90	90
RH	30	30	30	30	37	37
WK	10	10	10	10	12	12
W	10	10	10	10	12	12
T	8	8	8	8	8	8
TP	M12 Depth 25	M12 Depth 25	M12 Depth 25	M12 Depth 25	M16 Depth 32	M12 Depth 32

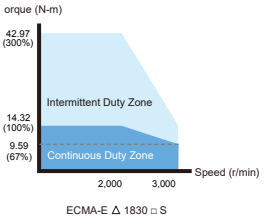
NOTE

1) Dimensions are in millimeters.
2) Dimensions of the servo motors may be revised without prior notice.
3) The boxes (□) in the model names are for optional configurations(keyway, brake and oil seal).
4) The boxes (△) in the model names are for encoder resolution types. (△ =1: Incremental encoder, 20-bit; △ =2: Incremental encoder, 17-bit; △ =A: Absolute type)

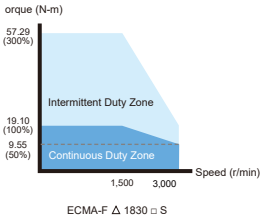
Speed-Torque Curves (T-N Curves)



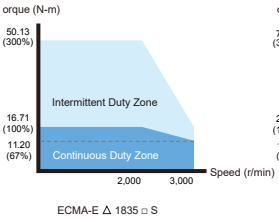
ECMA-E △ 1820 □ S



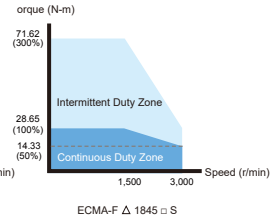
ECMA-E △ 1830 □ S



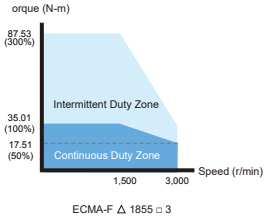
ECMA-F △ 1830 □ S



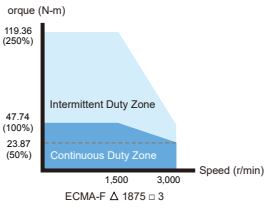
ECMA-E △ 1835 □ S



ECMA-F △ 1845 □ S



ECMA-F △ 1855 □ 3

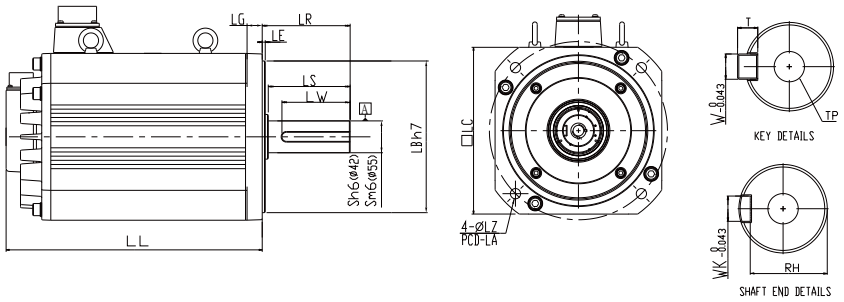


ECMA-F △ 1875 □ 3

Servo Motor Dimensions

220V / 400V Series

Frame Size 220mm and above



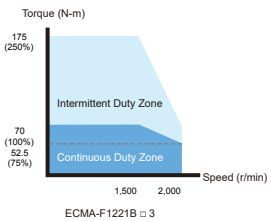
Units: mm

Model	F1221B □ 3	F1221F □ S	L1221B □ 3	L1221F □ S
LC	220	220	220	220
LZ	13.5	13.5	13.5	13.5
LA	235	235	235	235
S	42 ($^{+0}_{-0.016}$)	55 ($^{+0.03}_{-0.011}$)	42 ($^{+0}_{-0.016}$)	55 ($^{+0.03}_{-0.011}$)
LB	200 ($^{+0}_{-0.046}$)	200 ($^{+0}_{-0.046}$)	200 ($^{+0}_{-0.046}$)	200 ($^{+0}_{-0.046}$)
LL (without brake)	371.4	453.4	371.4	450.4
LL (with brake)	434.4	513.4	434.4	513.4
LS	108	108	110	110
LR	116	116	116	116
LE	4	4	4	4
LG	20	20	20	20
LW	90	90	90	90
RH	37	49	37	49
WK	12	16	12	16
W	12	16	12	16
T	8	10	8	10
TP	M16 Depth 32	M20 Depth 40	M16 Depth 32	M20 Depth 40

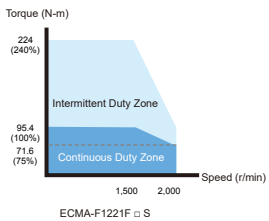
NOTE

1) Dimensions are in millimeters.
2) Dimensions of the servo motors may be revised without prior notice.
3) The boxes (□) in the model names are for optional configurations (keyway, brake and oil seal).

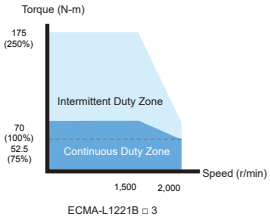
Speed-Torque Curves (T-N Curves)



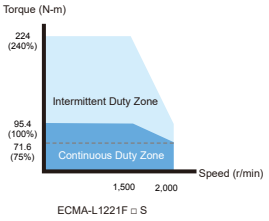
ECMA-F1221B □ 3



ECMA-F1221F □ S



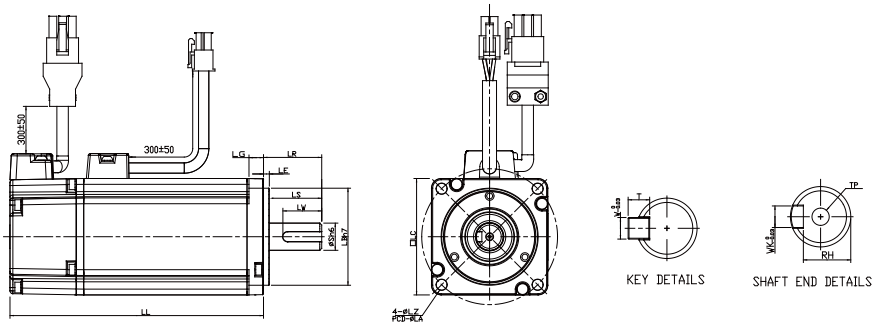
ECMA-L1221B □ 3



ECMA-L1221F □ S

400V Series

Frame Size 80mm and below



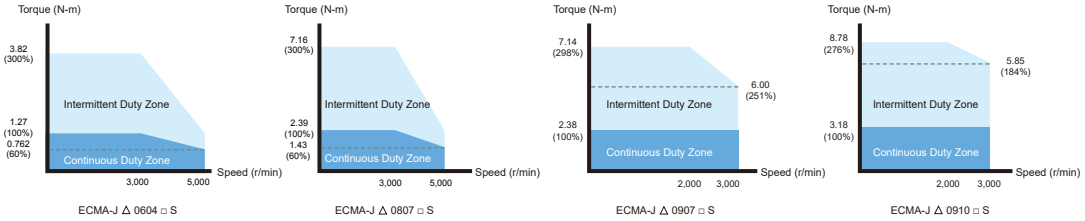
Units: mm

Model	J △ 0604 □ S	J △ 0807 □ S	J △ 0907 □ S	J △ 0910 □ S
LC	60	80	86	86
LZ	5.5	6.6	6.6	6.6
LA	70	90	100	100
S	14($^{+0}_{-0.011}$)	19($^{+0}_{-0.013}$)	16($^{+0}_{-0.011}$)	16($^{+0}_{-0.011}$)
LB	50($^{+0}_{-0.025}$)	70($^{+0}_{-0.030}$)	80($^{+0}_{-0.030}$)	80($^{+0}_{-0.030}$)
LL (without brake)	130.7	138.3	130.2	153.2
LL (with brake)	166.8	178	161.3	184.3
LS (without oil seal)	27	32	30	30
LS (with oil seal)	--	29.5	30	30
LR	30	35	35	35
LE	3	3	3	3
LG	7.5	8	8	8
LW	20	25	20	20
RH	11	15.5	13	13
WK	5	6	5	5
W	5	6	5	5
T	5	6	5	5
TP	M4 Depth 15	M6 Depth 20	M5 Depth 15	M5 Depth 15

NOTE

1) Dimensions are in millimeters.
2) Dimensions of the servo motors may be revised without prior notice.
3) The boxes (□) in the model names are for optional configurations (keyway, brake and oil seal).
4) The boxes (△) in the model names are for encoder resolution types (△ =1: Incremental encoder, 20-bit; △ =2: Incremental encoder, 17-bit); △ =A: Absolute type

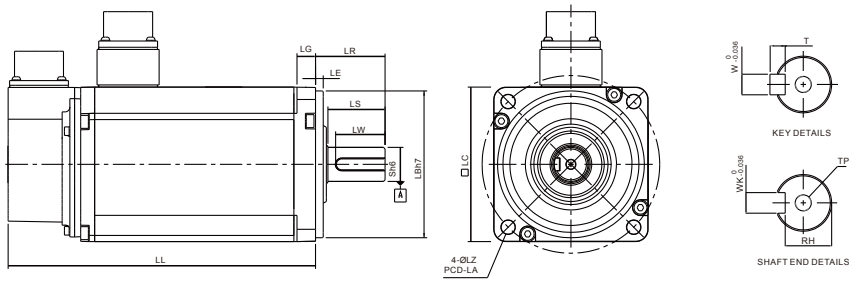
Speed-Torque Curves (T-N Curves)



Servo Motor Dimensions

400V Series

Frame Size 100mm and 130mm



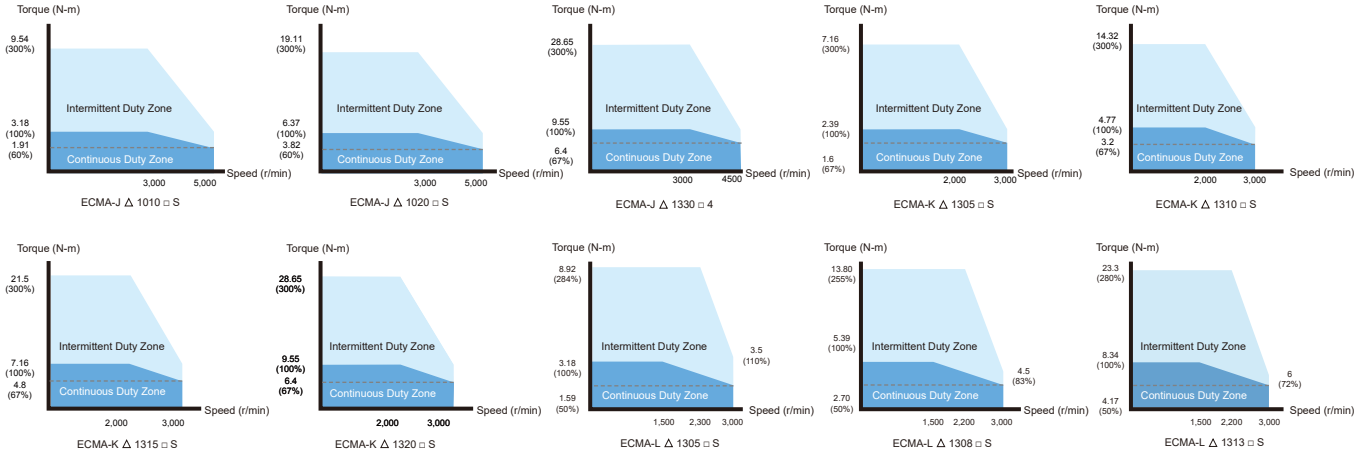
Units: mm

Model	J △ 1010 □ S	J △ 1020 □ S	J △ 1330 □ 4	K △ 1305 □ S	K △ 1310 □ S	K △ 1315 □ S	K △ 1320 □ S	L △ 1305 □ S	L △ 1308 □ S	L △ 1313 □ S
LC	100	100	130	130	130	130	130	130	130	130
LZ	9	9	9	9	9	9	9	9	9	9
LA	115	115	145	145	145	145	145	145	145	145
S	22 ($^{+0}_{-0.013}$)	22 ($^{+0}_{-0.013}$)	24 ($^{+0}_{-0.013}$)	22 ($^{+0}_{-0.013}$)	22 ($^{+0}_{-0.013}$)	22 ($^{+0}_{-0.013}$)	22 ($^{+0}_{-0.013}$)	22 ($^{+0}_{-0.013}$)	22 ($^{+0}_{-0.013}$)	22 ($^{+0}_{-0.013}$)
LB	95 ($^{+0}_{-0.035}$)	95 ($^{+0}_{-0.035}$)	110 ($^{+0}_{-0.035}$)	110 ($^{+0}_{-0.035}$)	110 ($^{+0}_{-0.035}$)	110 ($^{+0}_{-0.035}$)	110 ($^{+0}_{-0.035}$)	110 ($^{+0}_{-0.035}$)	110 ($^{+0}_{-0.035}$)	110 ($^{+0}_{-0.035}$)
LL (without brake)	153.3	199	187.5	139.5	147.5	167.5	187.5	147.5	163.5	194.5
LL (with brake)	192.5	226	216.0	168	183.5	202	216	168.0	181	223
LS	37	37	47	47	47	47	47	47	47	47
LR	45	45	55	55	55	55	55	55	55	55
LE	5	5	6	6	6	6	6	6	6	6
LG	12	12	11.5	11.5	11.5	11.5	11.5	11.5	11.5	11.5
LW	32	32	36	36	36	36	36	36	36	36
RH	18	18	20	18	18	18	18	18	18	18
WK	8	8	8	8	8	8	8	8	8	8
W	8	8	8	8	8	8	8	8	8	8
T	7	7	7	7	7	7	7	7	7	7
TP	MP6 Depth 20	MP6 Depth 20	MP6 Depth 20	MP6 Depth 20	MP6 Depth 20	MP6 Depth 20	MP6 Depth 20	M8 Depth 25	MP6 Depth 20	MP6 Depth 20

NOTE

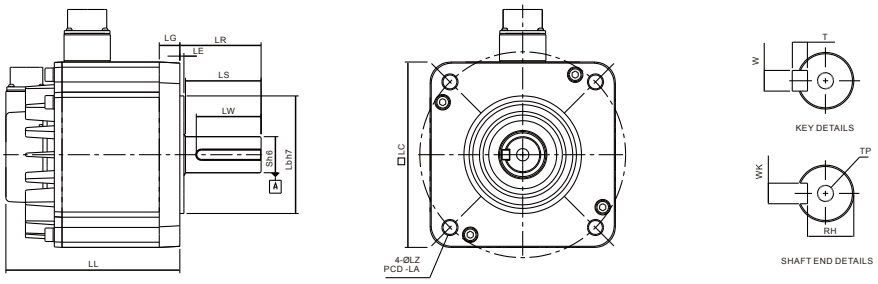
1) Dimensions are in millimeters.
2) Dimensions of the servo motors may be revised without prior notice.
3) The boxes (□) in the model names are for optional configurations (keyway, brake and oil seal).
4) The boxes (△) in the model names are for encoder resolution types (△ =1: Incremental encoder, 20-bit; △ =2: Incremental encoder, 17-bit); △ =A: Absolute type

Speed-Torque Curves (T-N Curves)



400V Series

Frame Size 180mm and above



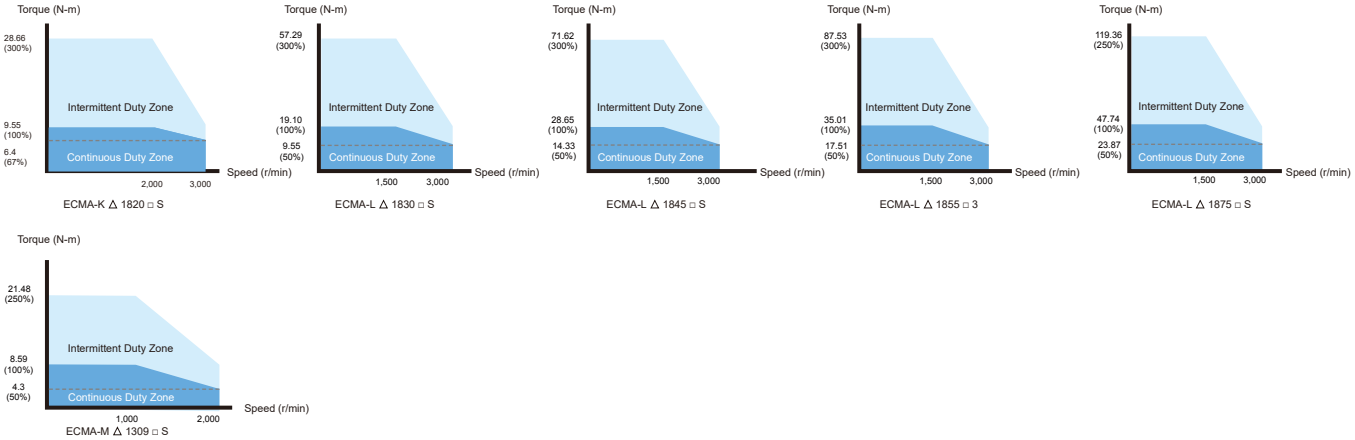
Units: mm

Model	K △ 1820 □ S	L △ 1830 □ S	L △ 1845 □ S	L △ 1855 □ 3	L △ 1875 □ S	M △ 1309 □ S
LC	180	180	180	180	180	130
LZ	13.5	13.5	13.5	13.5	13.5	9
LA	200	200	200	200	200	145
S	35 ($^{+0}_{-0.016}$)	35 ($^{+0}_{-0.016}$)	35 ($^{+0}_{-0.016}$)	42 ($^{+0}_{-0.016}$)	42 ($^{+0}_{-0.016}$)	22 ($^{+0}_{-0.013}$)
LB	114.3($^{+0}_{-0.035}$)	114.3($^{+0}_{-0.035}$)	114.3($^{+0}_{-0.035}$)	114.3($^{+0}_{-0.035}$)	114.3($^{+0}_{-0.035}$)	110($^{+0}_{-0.035}$)
LL (without brake)	169	202.1	235.3	279.7	342.0	163.5
LL (with brake)	203.1	235.3	279.3	311.7	376.1	198
LS	73	73	73	108.5	108.5	47
LR	79	79	79	113	113	55
LE	4	4	4	4	4	6
LG	20	20	20	20	20	11.5
LW	63	63	63	90	90	36
RH	30	30	30	37	37	18
WK	10	10	10	12	12	8
W	10	10	10	12	12	8
T	8	8	8	8	8	7
TP	M12 Depth 25	M12 Depth 25	M12 Depth 25	M16 Depth 32	M16 Depth 32	M6 Depth 20

NOTE

1) Dimensions are in millimeters.
2) Dimensions of the servo motors may be revised without prior notice.
3) The boxes (□) in the model names are for optional configurations (keyway, brake and oil seal).
4) The boxes (△) in the model names are for encoder resolution types (△ =1: Incremental encoder, 20-bit; △ =2: Incremental encoder, 17-bit); △ =A: Absolute type

Speed-Torque Curves (T-N Curves)



Servo Drive Specifications

220V Series

ASDA-A2 Series			100 W	200 W	400 W	750 W	1 kW	1.5 kW	2 kW	3 kW	4.5 kW	5.5 kW	7.5 kW	11 kW	15kW
			01	02	04	07	10	15	20	30	45	55	75	1B	1F
Power supply	Phase / Voltage		Three-phase / Single-phase 220V_{AC}						3-phase 220V_{AC}						
	Permissible Voltage Range		1-phase / 3-phase 200 ~ 230V_{AC}, -15% ~ 10%						3-phase 200 ~ 230V_{AC}, -15% ~ 10%						
	Input Current(3PH) (Units: Arms)		0.8	1.11	1.86	3.66	4.68	6.33	8.76	9.83	17.5	19.4	26.3	48	63
	Input Current(1PH) (Units: Arms)		1	1.92	3.22	6.78	8.88	10.96	-	-	-	-	-	-	-
	Continuous Output Current (Units: Arms)		0.9	1.55	2.6	5.1	7.3	8.86	13.4	19.4	32.5	40	47.5	54.4	70
Cooling System			Natural Air Circulation			Fan Cooling									
Encoder Resolution / Feedback Resolution			Incremental encoder: 20-bit ; Absolute encoder: 17-bit												
Control of Main Circuit			SVPWM(Space Vector Pulse Width Modulation) Control												
Tuning Modes			Auto / Manual												
Regenerative Resistor			None		Built-in							External			
Position Control Mode	Max. Input Pulse Frequency (Only for Non-DMCNET mode)		Max. 500Kpps / 4Mpps (Line driver), Max. 200Kpps (Open collector)												
	Pulse Type (Only for Non-DMCNET mode)		Pulse + Direction, A phase + B phase, CCW pulse + CW pulse												
	Command Source		External pulse train (PT mode) (Only for Non-DMCNET mode) / Internal parameters (PR mode)												
	Smoothing Strategy		Low-pass and P-curve filter												
	Electronic Gear		Electronic gear N/M multiple N: 1~32767, M: 1:32767 (1/50<N/M<25600)												
	Torque Limit Operation		Set by parameters												
	Feed Forward Compensation		Set by parameters												
Speed Control Mode	Analog Input Command (Only for Non-DMCNET mode)	Voltage Range	0 ~ ±10 V_{DC}												
		Input Resistance	10KΩ												
		Time Constant	354.6 μs												
	Speed Control Range *1		1: 5000									1: 3000		1: 2000	
	Command Source		External analog signal (Only for Non-DMCNET mode) / Internal parameters												
	Smoothing Strategy		Low-pass and S-curve filter												
	Torque Limit Operation		Set by parametersor via analog input (Only for Non-DMCNET mode)												
	Frequency Response Characteristic		Maximum 1kHz												
	Speed Accuracy *2 (At rated rotation speed)		0.01% or less at 0 to 100% load fluctuation												
			0.01% or less at ±10% power fluctuation												
			0.01% or less at 0ºC to 50ºC ambient temperature fluctuation												
Torque Control Mode	Analog Input Command (Only for Non-DMCNET mode)	Voltage Range	0 ~ ±10 V_{DC}												
		Input Resistance	10KΩ												
		Time Constant	2.2 μs												
	Command Source		External analog signal (Only for Non-DMCNET mode) / Internal parameters												
	Smoothing Strategy		Low-pass filter												
	Speed Limit Operation		Set by parametersor via analog input (Only for Non-DMCNET mode)												
Analog Monitor Output			Monitor signal can set by parameters (Output voltage range: ±8V)												
Digital Inputs / Outputs	Inputs		Servo on, Reset, Gain switching, Pulse clear, Zero speed CLAMP, Command input reverse control, Command triggered, Speed/ Torque limit enabled, Position command selection, Motor stop, Speed position selection, Position / Speed mode switching, Speed / Torque mode switching, Torque / Position mode switching, PT / PR command switching, Emergency stop, Forward / Reverse inhibit limit, Reference "Home" sensor, Forward / Reverse operation torque limit, Move to "Home", Electronic Cam (E-CAM), Forward / Reverse JOG input, Event trigger PR command, Electronic gear ratio (Numerator) selection and Pulse inhibit input * Please note that the above digital signals and inputs are available only for Non-DMCNET mode. In DMCNET mode, it is recommended to write digital inputs into the servo drives through DMCNET communication, and the digital inputs should be used for Emergency Stop, Forward / Reverse Inhibit limit and Reference "Home" sensor only.												
	Outputs		Encoder signal output (A, B, Z Line Driver and Z Open Collector) Servo ready, Servo on, At Zero speed, At Speed reached, At Positioning completed, At Torques limit, Servo alarm (Servo fault) activated, Electromagnetic brake control, Homing completed, Output overload warning, Servo warning activated, Position command overflow, Forward / Reverse software limit, Internal position command completed, Capture operation completed output., Motion control completed output., Master position of E-CAM (Electronic CAM)												
Protective Functions			Overcurrent, Overvoltage, Undervoltage, Motor overheated, Regeneration error, Overload, Overspeed, Abnormal pulse control command, Excessive deviation, Encoder error, Adjustment error, Emergency stop activated, Reverse/ Forward limit switch error, Position excessive deviation of full-close control loop, Serial communication error, Input power phase loss, Serial communication time out, short circuit protection of U, V, W, and CN1, CN2, CN3 terminals												
Communication Interface			RS-232 / RS-485 / CANopen / USB / DMCNET												
Environment	Installation Site		Indoor location (free from direct sunlight), no corrosive liquid and gas (far away from oil mist, flammable gas, dust)												
	Altitude		Altitude 2000m or lower above sea level												
	Atmospheric Pressure		86kPa ~ 106kPa												
	Operating Temperature		0ºC ~ 55ºC (If operating temperature is above 45ºC, forced cooling will be required)												
	Storage Temperature		-20ºC ~ 65ºC												
	Humidity		0 ~ 90% RH (non-condensing)												
	Vibration		9.80665 m/s^2 (1G) less than 20Hz, 5.88 m/s^2 (0.6G) 20 to 50Hz												
	IP Rating		IP20												
	Power System		TN System *3												
	Approvals		IEC/EN 61800-5-1, UL 508C, C-tick												

Footnote:

*1. Rated rotation speed: When full load, speed ratio is defined as the minimum speed (the motor will not pause).
*2. When command is rated rotation speed, the speed fluctuation rate is defined as: (Empty load rotation speed Full load rotation speed) / Rated rotation speed
*3. TN system: A power distribution system having one point directly earthed, the exposed conductive parts of the installation being connected to that points by protective earth conductor.

400V Series

ASDA-A2 Series			750 W	1kW	1.5kW	2kW	3kW	4.5kW	5.5kW	7.5kW	11 kW	15 kW
			07	10	15	20	30	45	55	75	1B	1F
Control Power	Input Voltage		$24V_{DC}$, ±10%									
	Input Current			0.89A			1.18A			1.66A	2A	
	Input Power			21.4W			28.2W			39.85W	48W	
Main Power	Permissible Voltage Range		3-phase380 ~ $480V_{AC}$, ±10%									
	Input Current (Units: Arms)		2.22	3.02	4.24	5.65	8.01	11.9	14.1	17.27	28.95	39.47
	Continuous Output Current (Units: Arms)		3.07	3.52	5.02	6.66	11.9	20	22.37	30	28.1	38.65
Cooling System			Fan Cooling									
Encoder Resolution / Feedback Resolution			Incremental encoder: 20-bit ; Absolute encoder: 17-bit									
Control of Main Circuit			SVPWM(Space Vector Pulse Width Modulation) Control									
Tuning Modes			Auto / Manual									
Regenerative Resistor				Built-in			External					
Position Control Mode	Max. Input Pulse Frequency(Only for Non-DMCNET mode)		Max. 500Kpps / 4Mpps (Line driver), Max. 200Kpps (Open collector)									
	Pulse Type (Only for Non-DMCNET mode)		Pulse + Direction, A phase + B phase, CCW pulse + CW pulse									
	Command Source		External pulse train (Only for Non-DMCNET mode)/Internal parameters									
	Smoothing Strategy		Low-pass and P-curve filter									
	Electronic Gear		Electronic gear N/M multiple N: 1~32767, M: 1:32767 (1/50<N/M<25600)									
	Torque Limit Operation		Set by parameters									
	Feed Forward Compensation		Set by parameters									
Speed Control Mode	Analog Input Command (Only for Non-DMCNET mode)	Voltage Range	$0 \sim \pm 10\ V_{DC}$									
		Input Resistance	10KΩ									
		Time Constant	2.2 μs									
	Speed Control Range *1		1: 5000					1: 3000				
	Command Source		External analog signal (Only for Non-DMCNET mode) / Internal parameters									
	Smoothing Strategy		Low-pass and S-curve filter									
	Torque Limit Operation		Set by parametersor via analog input (Only for Non-DMCNET mode)									
	Frequency Response Characteristic		Maximum 1kHz									
	Speed Accuracy *2		0.01% or less at 0 to 100% load fluctuation									
			0.01% or less at ±10% power fluctuation									
			0.01% or less at 0ºC to 50ºC ambient temperature fluctuation									
Torque Control Mode	Analog Input Command (Only for Non-DMCNET mode)	Voltage Range	$0 \sim \pm 10\ V_{DC}$									
		Input Resistance	10KΩ									
		Time Constant	2.2 μs									
	Command Source		External analog signal (Only for Non-DMCNET mode) / Internal parameters									
	Smoothing Strategy		Low-pass filter									
	Speed Limit Operation		Set by parametersor via analog input (Only for Non-DMCNET mode)									
Analog Monitor Output			Monitor signal can set by parameters (Output voltage range: ±8V)									
Digital Inputs / Outputs	Inputs		Servo on, Reset, Gain switching, Pulse clear, Zero speed CLAMP, Command input reverse control, Command triggered, Speed/ Torque limit enabled, Position command selection, Motor stop, Speed position selection, Position / Speed mode switching, Speed / Torque mode switching, Torque / Position mode switching, PT / PR command switching, Emergency stop, Forward / Reverse inhibit limit, Reference "Home" sensor, Forward / Reverse operation torque limit, Move to "Home", Electronic cam, Forward / Reverse JOG input, Event trigger PR command, Electronic gear ratio (Numerator) selection and Pulse inhibit input * Please note that the above digital signals and inputs are available only for Non-DMCNET mode. In DMCNET mode, it is recommended to write digital inputs into the servo drives through DMCNET communication, and the digital inputs should be used for Emergency Stop, Forward / Reverse Inhibit limit and Reference "Home" sensor only.									
	Outputs		Encoder signal output (A, B, Z Line Driver and Z Open Collector) Servo ready, Servo on, At Zero speed, At Speed reached, At Positioning completed, At Torques limit, Servo alarm (Servo fault) activated, Electromagnetic brake control, Homing completed, Output overload warning, Servo warning activated, Position command overflow, Forward / Reverse software limit, Internal position command completed, Capture operation completed output., Motion control completed output., Master position of E-CAM (Electronic CAM)									
Protective Functions			Overcurrent, Overvoltage, Undervoltage, Motor overheated, Regeneration error, Overload, Overspeed, Abnormal pulse control command, Excessive deviation, Encoder error, Adjustment error, Emergency stop activated, Reverse/ Forward limit switch error, Position excessive deviation of full-close control loop, Serial communication error, Input power phase loss, Serial communication time out, short circuit protection of U, V, W, and CN1, CN2, CN3 terminals									
Communication Interface			RS-232 / RS-485 / CANopen / USB / DMCNET									
Environment	Installation Site		Indoor location (free from direct sunlight), no corrosive liquid and gas (far away from oil mist, flammable gas, dust)									
	Altitude		Altitude 2000m or lower above sea level									
	Atmospheric Pressure		86kPa ~ 106kPa									
	Operating Temperature		0ºC ~ 55ºC(If operating temperature is above 45ºC, forced cooling will be required)									
	Storage Temperature		-20ºC ~ 65ºC									
	Humidity		0 ~ 90% RH (non-condensing)									
	Vibration		9.80665 m/s^2 (1G) less than 20Hz, 5.88 m/s^2 (0.6G) 20 to 50Hz									
	IP Rating		IP20									
	Power System		TN System*3									
	Approvals		IEC/EN 61800-5-1, UL 508C, C-tick CE c UL us LISTED									

Footnote:

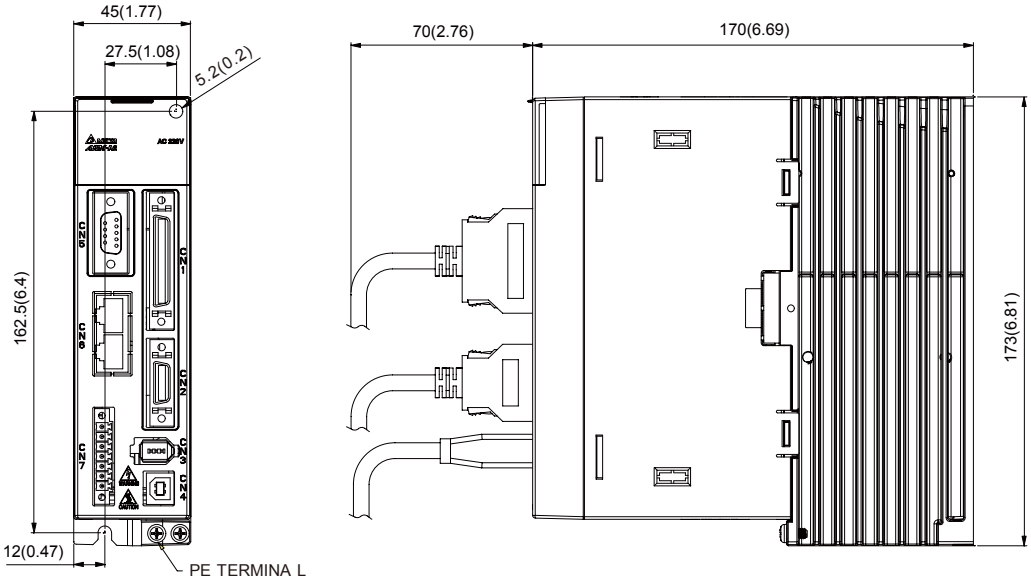
*1. Rated rotation speed: When full load, speed ratio is defined as the minimum speed (the motor will not pause).
*2. When command is rated rotation speed, the speed fluctuation rate is defined as: (Empty load rotation speed Full load rotation speed) / Rated rotation speed
*3. TN system: A power distribution system having one point directly earthed, the exposed conductive parts of the installation being connected to that points by protective earth conductor.

Servo Drive Dimensions Units: mm(inches)

220V Series

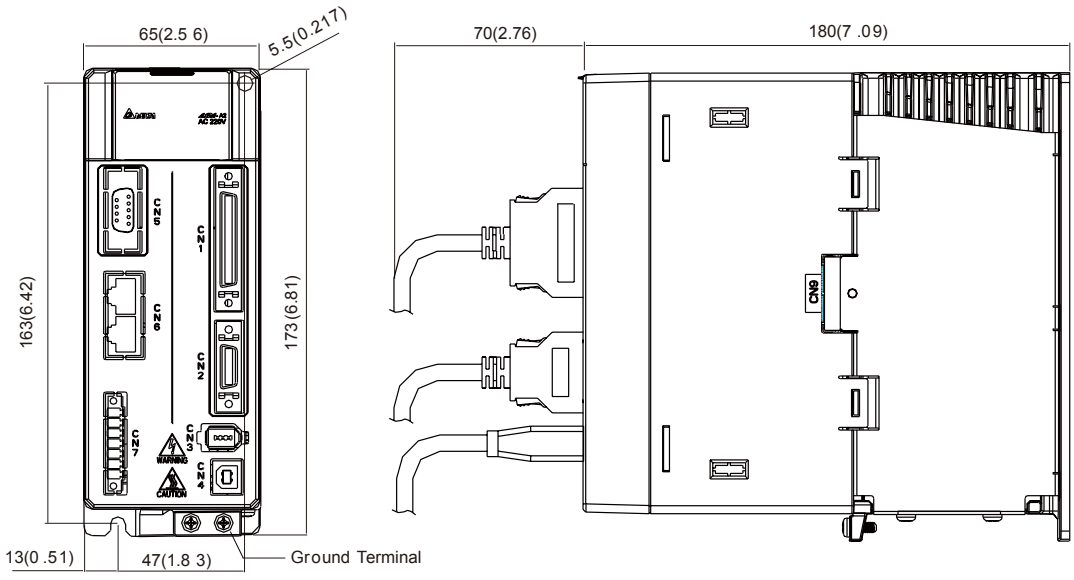
100W / 200W / 400W

Weight
1.5 (3.3)



750W / 1.0kW / 1.5kW

Weight
2.0 (4.4)

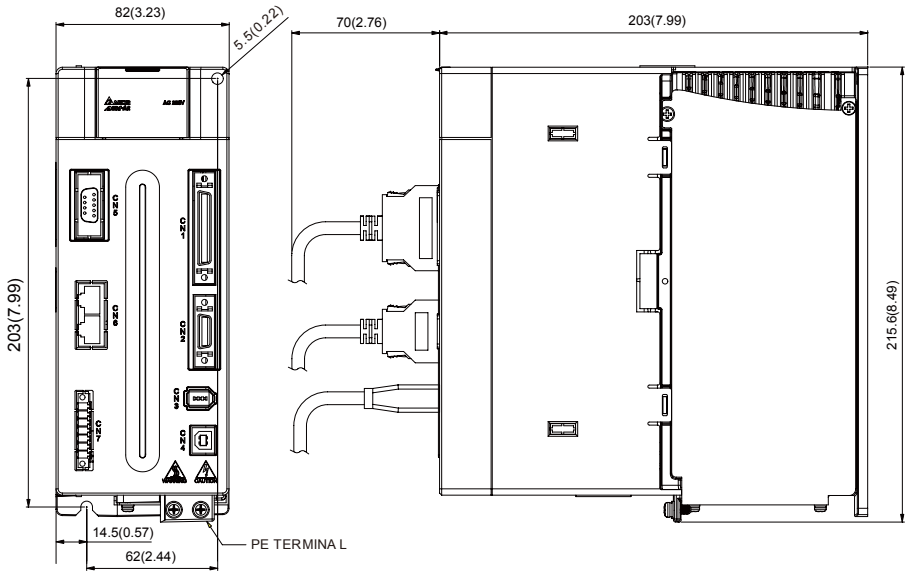


NOTE

1) Dimensions are in millimeters (inches); Weights are in kilograms (kg) and (pounds (lbs)).
2) Dimensions and weights of the servo drive may be revised without prior notice.

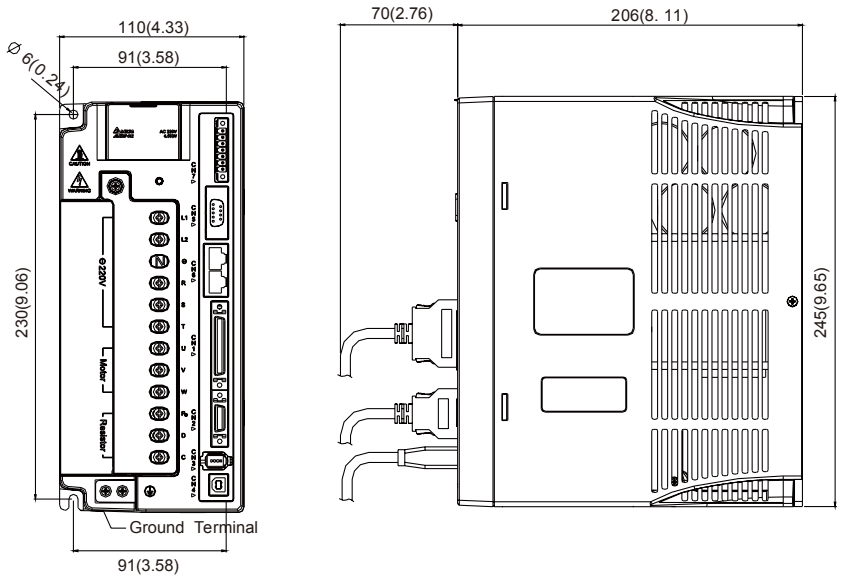
2.0kW / 3.0kW

Weight
2.89 (6.36)



4.5kW

Weight
4.4 (10.0)



NOTE

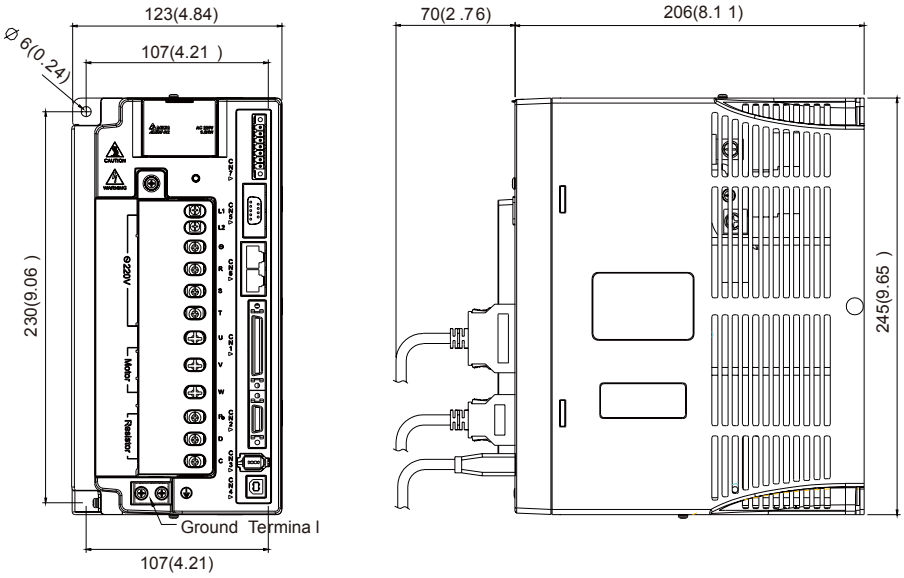
1) Dimensions are in millimeters (inches); Weights are in kilograms (kg) and (pounds (lbs)).
2) Dimensions and weights of the servo drive may be revised without prior notice.

Servo Drive Dimensions Units: mm(inches)

220V Series

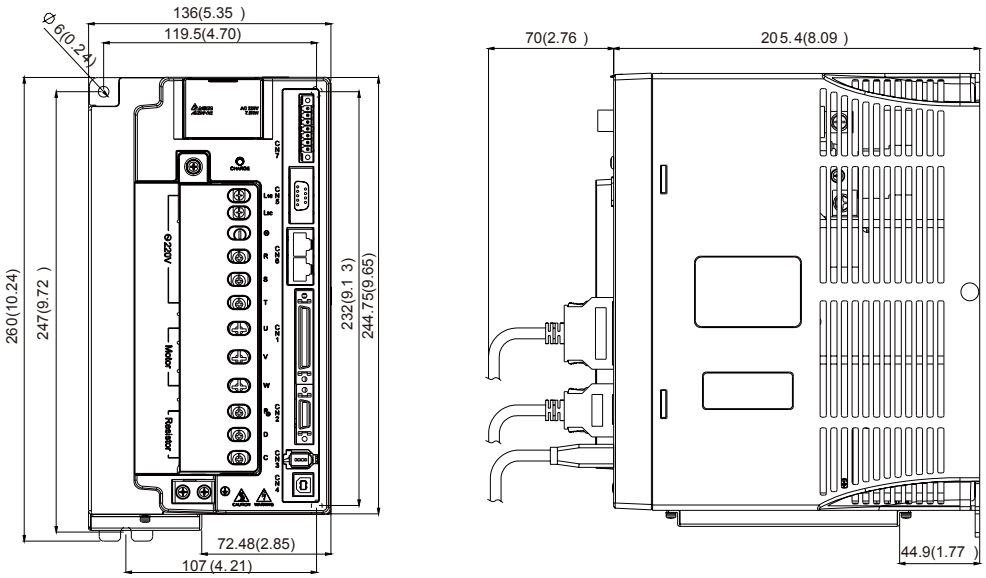
5.5kW

Weight
5.5 (12.1)



7.5kW

Weight
5.9 (13)

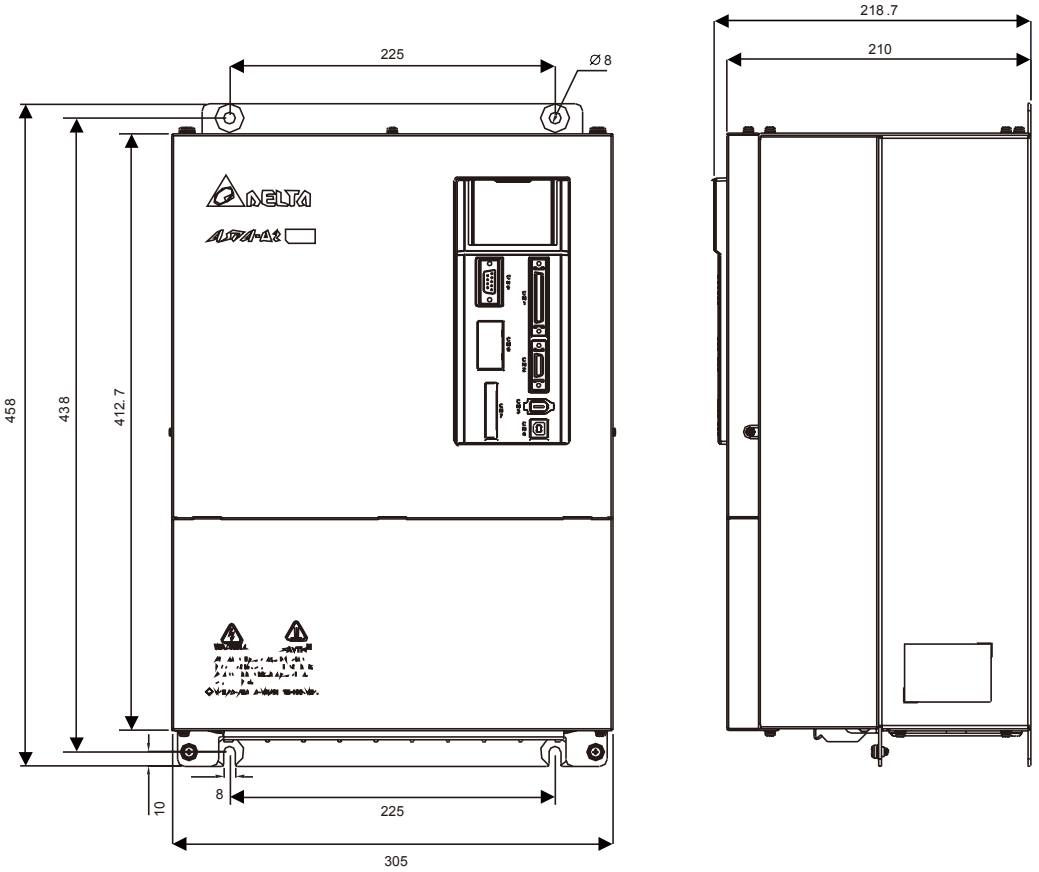


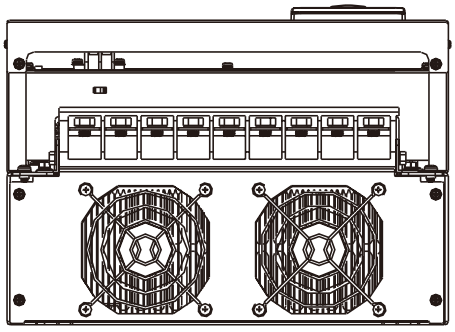
NOTE

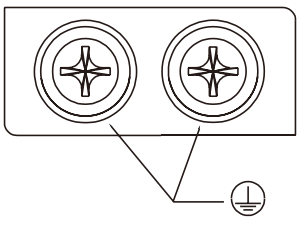
1) Dimensions are in millimeters (inches); Weights are in kilograms (kg) and (pounds (lbs)).
2) Dimensions and weights of the servo drive may be revised without prior notice.

11kW / 15kW

Weight
20 (44)







Screw: M4x0.7
Screw Torque: 14 (kgf-cm)

NOTE

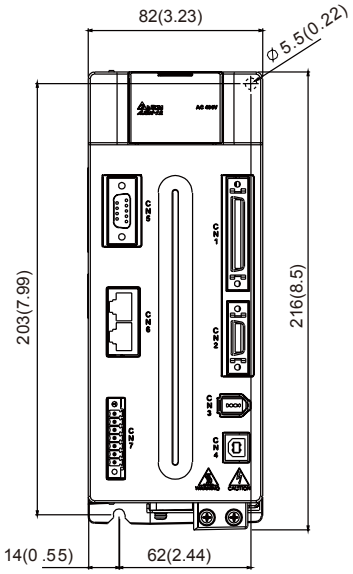
1) Dimensions are in millimeters (inches); Weights are in kilograms (kg) and (pounds (lbs)).
2) Dimensions and weights of the servo drive may be revised without prior notice.

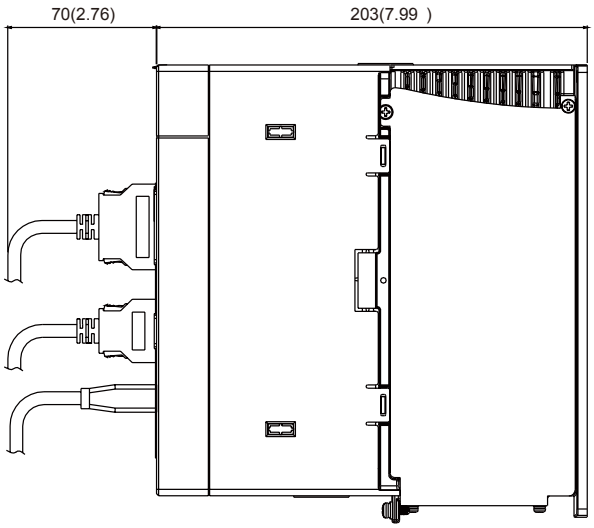
Servo Drive Dimensions Units: mm(inches)

400V Series

750W / 1.0kW / 1.5kW

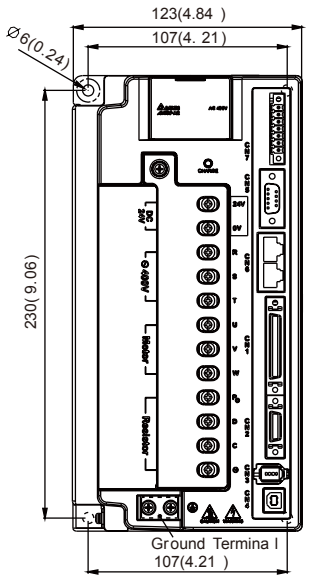
Weight
2.89 (6.36)

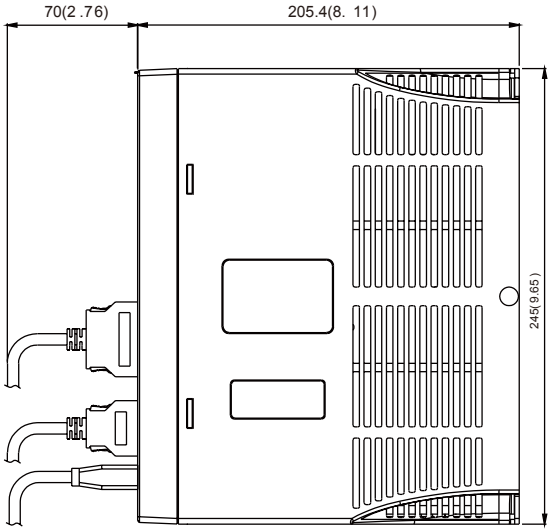




2.0kW / 3.0kW / 4.5kW / 5.5kW

Weight
5.5 (12.1)



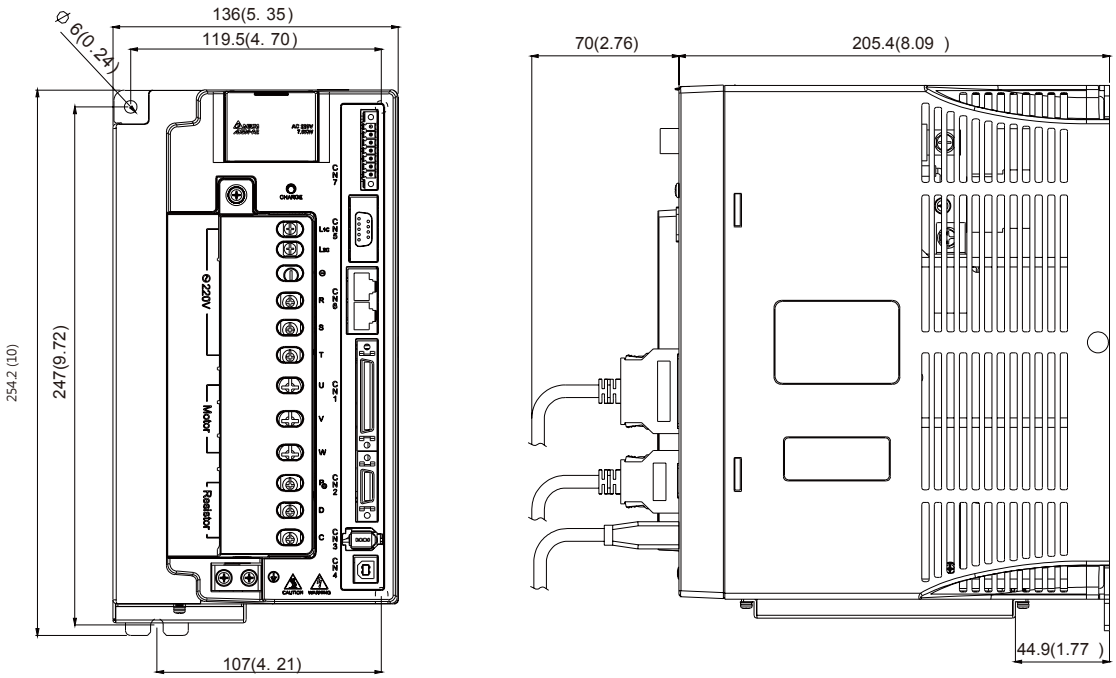


NOTE

1) Dimensions are in millimeters (inches); Weights are in kilograms (kg) and (pounds (lbs)).
2) Dimensions and weights of the servo drive may be revised without prior notice.

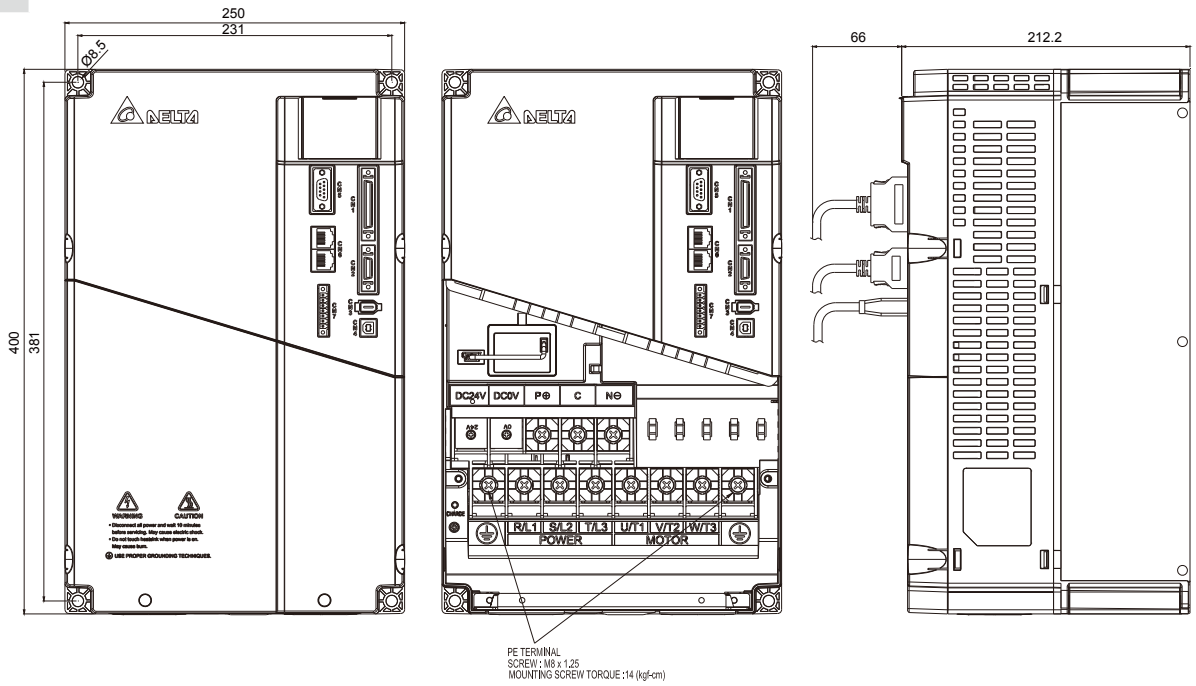
7.5kW

Weight
5.5 (12.1)



11kW / 15kW

Weight
10.3(22.66)



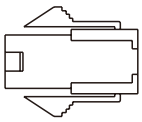
NOTE

1) Dimensions are in millimeters (inches); Weights are in kilograms (kg) and (pounds (lbs)).
2) Dimensions and weights of the servo drive may be revised without prior notice.

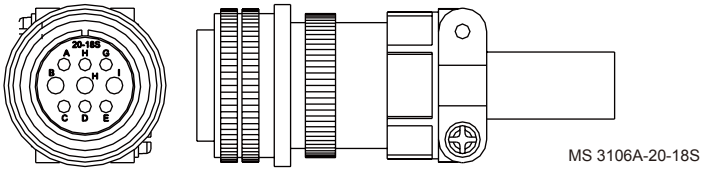
Optional Cables and Connectors

● Power Connectors

ASDBCAPW0000 (for 200V drives)

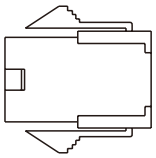


ASD-CAPW1000

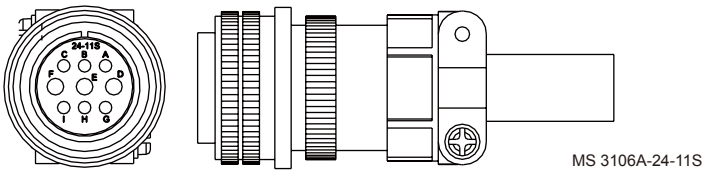


MS 3106A-20-18S

ASDBCAPW0100 (for 200V drives, with brake cable)

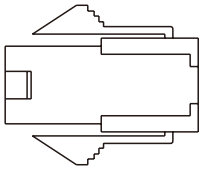


ASD-CAPW2000

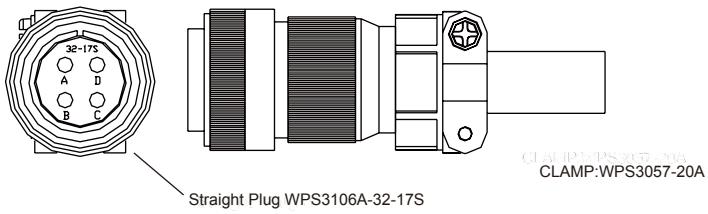


MS 3106A-24-11S

ASD-CAPW5400 (for 400V drives)



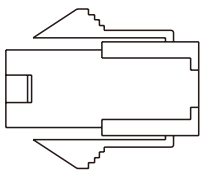
ASD-CAPW4000



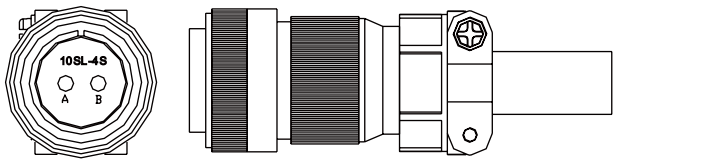
CLAMP:WPS3057-20A

Straight Plug WPS3106A-32-17S

ASD-CAPW5100 (for 400V drives, with brake cable)



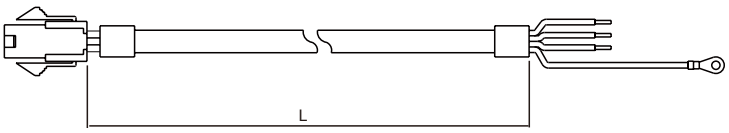
ASD-CNBR1000



CLAMP: WPS3106A 10SL-4S-R

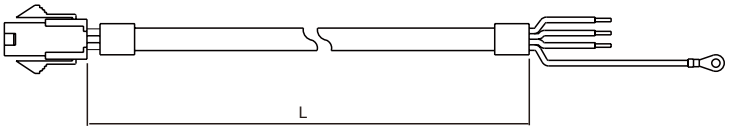
● Power Cables

ASD-ABPW0003, ASD-ABPW0005 (for 200V drives)



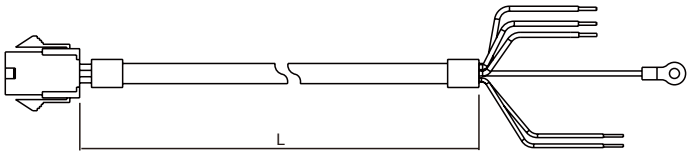
Item	Part No.	L	
		mm	inch
1	ASD-ABPW0003	3000 ± 100	118 ± 4
2	ASD-ABPW0005	5000 ± 100	197 ± 4

ASD-CAPW5403, ASD-CAPW5405 (for 400V drives)



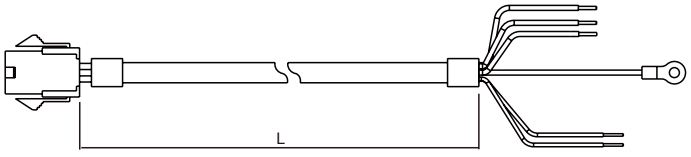
Item	Part No.	L	
		mm	inch
1	ASD-CAPW5403	3000 ± 100	118 ± 4
2	ASD-CAPW5405	5000 ± 100	197 ± 4

AASD-ABPW0103, ASD-ABPW0105 (for 200V drives, with brake cable)



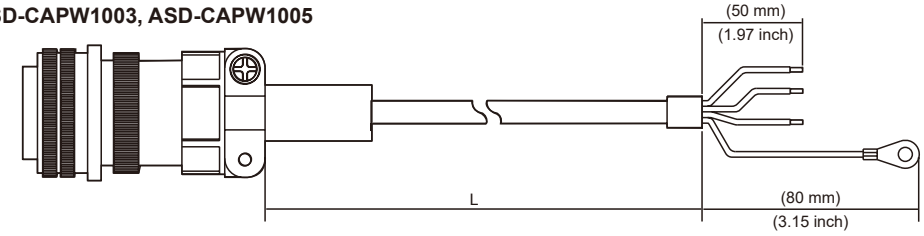
Item	Part No.	L	
		mm	inch
1	ASD-ABPW0103	3000 ± 100	118 ± 4
2	ASD-ABPW0105	5000 ± 100	197 ± 4

ASD-CAPW5103, ASD-CAPW5105 (for 400V drives, with brake cable)



Item	Part No.	L	
		mm	inch
1	ASD-CAPW5103	3000 ± 100	118 ± 4
2	ASD-CAPW5105	5000 ± 100	197 ± 4

ASD-CAPW1003, ASD-CAPW1005

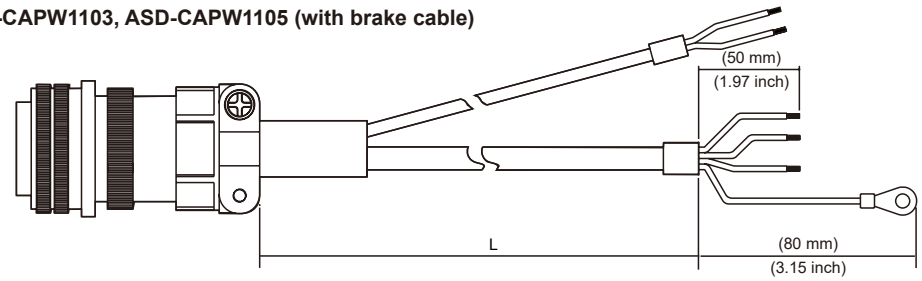


Item	Part No.	Straight	L	
			mm	inch
1	ASD-CAPW1003	3106A-20-18S	3000 ± 100	118 ± 4
2	ASD-CAPW1005	3106A-20-18S	5000 ± 100	197 ± 4

Optional Cables and Connectors

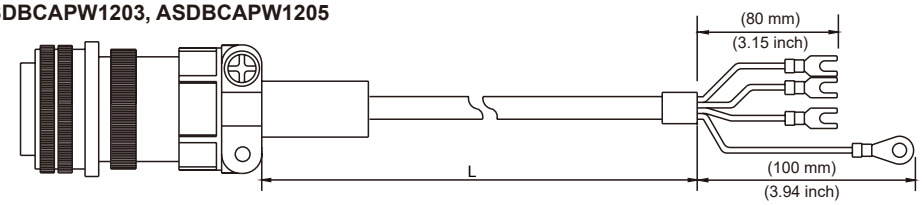
● Power Cables

ASD-CAPW1103, ASD-CAPW1105 (with brake cable)



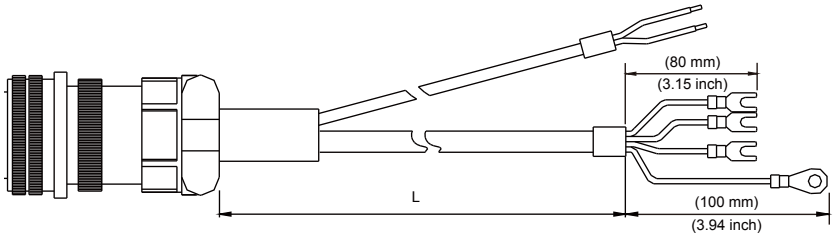
Item	Part No.	Straight	L	
			mm	inch
1	ASD-CAPW1103	3106A-20-18S	3000 ± 100	118 ± 4
2	ASD-CAPW1105	3106A-20-18S	5000 ± 100	197 ± 4

ASDBCAPW1203, ASDBCAPW1205



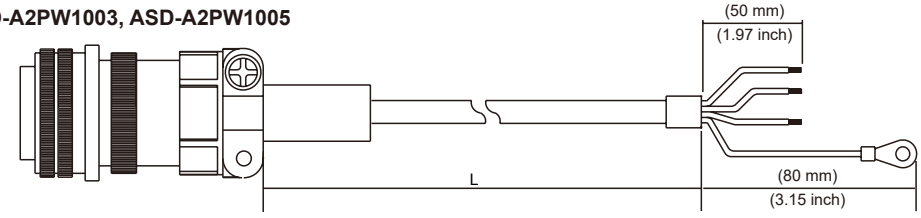
Item	Part No.	Straight	L	
			mm	inch
1	ASD-BCAPW1203	3106A-20-18S	3000 ± 100	118 ± 4
2	ASDB-CAPW1205	3106A-20-18S	5000 ± 100	197 ± 4

ASD-CAPW1303, ASD-CAPW1305 (with brake cable)



Item	Part No.	Straight	L	
			mm	inch
1	ASD-CAPW1303	3106A-20-18S	3000 ± 100	118 ± 4
2	ASD-CAPW1305	3106A-20-18S	5000 ± 100	197 ± 4

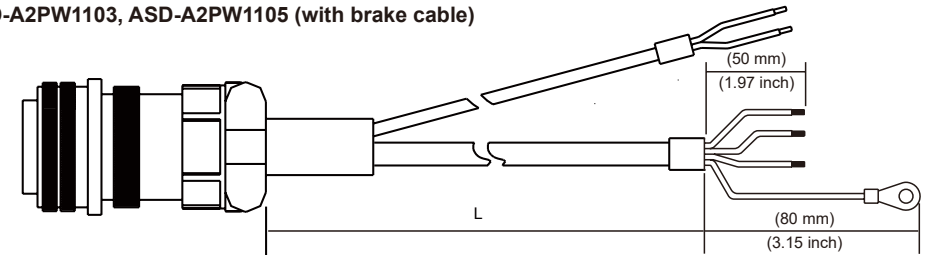
ASD-A2PW1003, ASD-A2PW1005



Item	Part No.	Straight	L	
			mm	inch
1	ASD-A2PW1003	3106A-20-18S	3000 ± 100	118 ± 4
2	ASD-A2PW1005	3106A-20-18S	5000 ± 100	197 ± 4

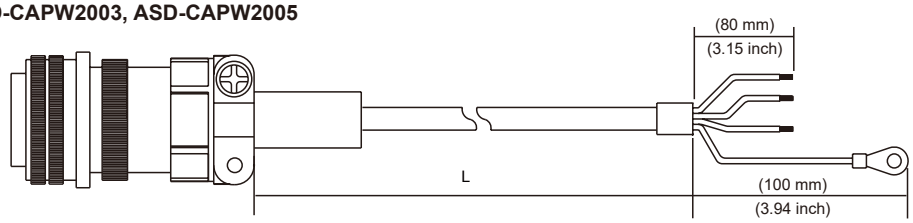
● Power Cables

ASD-A2PW1103, ASD-A2PW1105 (with brake cable)



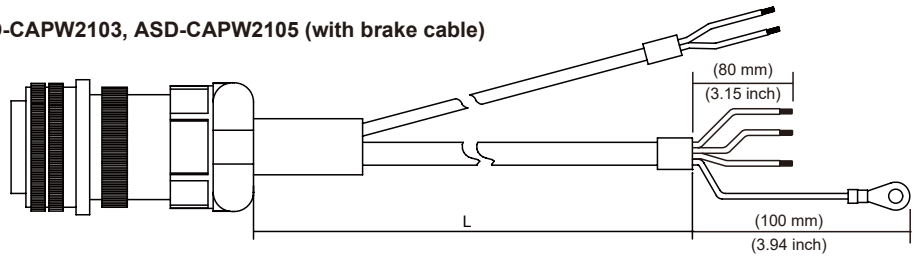
Item	Part No.	Straight	L	
			mm	inch
1	ASD-A2PW1103	3106A-20-18S	3000 ± 100	118 ± 4
2	ASD-A2PW1105	3106A-20-18S	5000 ± 100	197 ± 4

ASD-CAPW2003, ASD-CAPW2005



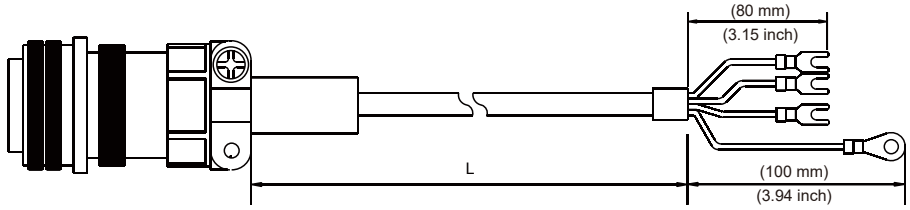
Item	Part No.	Straight	L	
			mm	inch
1	ASD-CAPW2003	3106A-24-11S	3000 ± 100	118 ± 4
2	ASD-CAPW2005	3106A-24-11S	5000 ± 100	197 ± 4

ASD-CAPW2103, ASD-CAPW2105 (with brake cable)



Item	Part No.	Straight	L	
			mm	inch
1	ASD-CAPW2103	3106A-24-11S	3000 ± 100	118 ± 4
2	ASD-CAPW2105	3106A-24-11S	5000 ± 100	197 ± 4

ASD-CAPW2203, ASD-CAPW2205

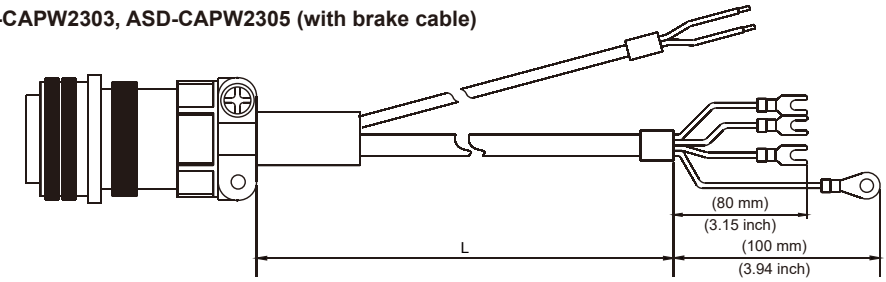


Item	Part No.	Straight	L	
			mm	inch
1	ASD-CAPW2203	3106A-24-11S	3000 ± 100	118 ± 4
2	ASD-CAPW2205	3106A-24-11S	5000 ± 100	197 ± 4

Optional Cables and Connectors

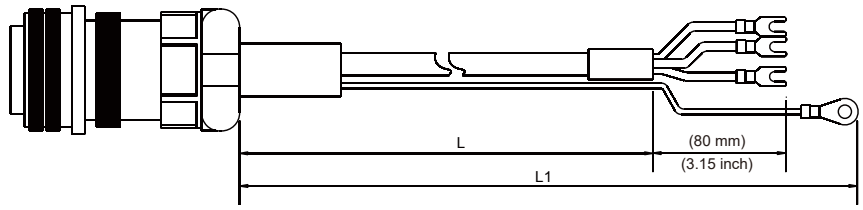
● Power Cables

ASD-CAPW2303, ASD-CAPW2305 (with brake cable)



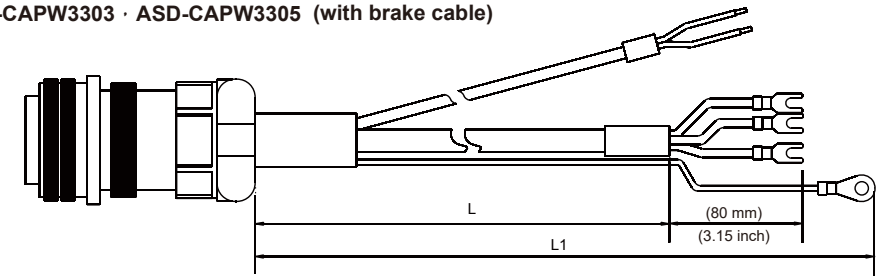
Item	Part No.	Straight	L	
			mm	inch
1	ASD-CAPW2303	3106A-24-11S	3000 ± 100	118 ± 4
2	ASD-CAPW2305	3106A-24-11S	5000 ± 100	197 ± 4

ASD-CAPW3203 · ASD-CAPW3205



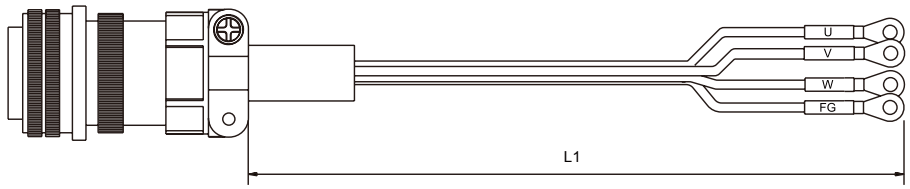
Item	Part No.	Straight	L		L1	
			mm	inch	mm	inch
1	ASD-CAPW3203	3106A-24-11S	3000 ± 100	118 ± 4	3100 ± 100	122 ± 4
2	ASD-CAPW3205	3106A-24-11S	5000 ± 100	197 ± 4	5100 ± 100	201 ± 4

ASD-CAPW3303 · ASD-CAPW3305 (with brake cable)



Item	Part No.	Straight	L		L1	
			mm	inch	mm	inch
1	ASD-CAPW3303	3106A-24-11S	3000 ± 100	118 ± 4	3100 ± 100	122 ± 4
2	ASD-CAPW3305	3106A-24-11S	5000 ± 100	197 ± 4	5100 ± 100	201 ± 4

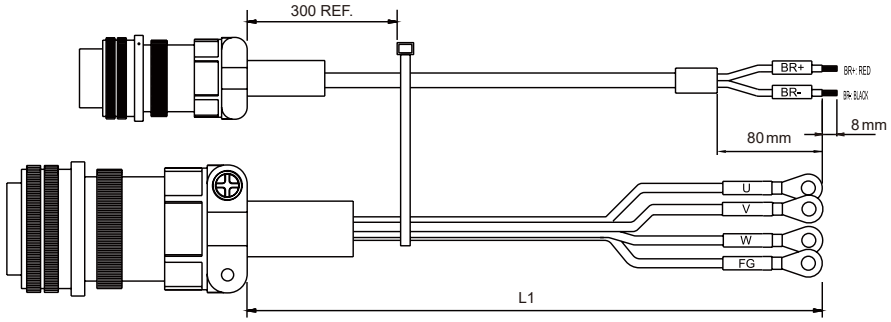
ASD-CAPW4503, ASD-CAPW4505



Item	Part No.	Straight	L1	
			mm	inch
1	ASD-CAPW4503	3106A-32-17S	3100 ± 100	122 ± 4
2	ASD-CAPW4505	3106A-32-17S	5100 ± 100	201 ± 4

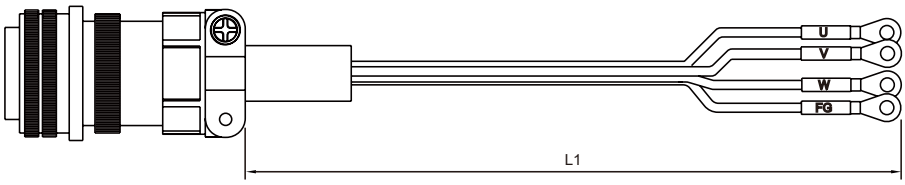
● Power Cables

ASD-CAPW4703, ASD-CAPW4705 (with brake cable)



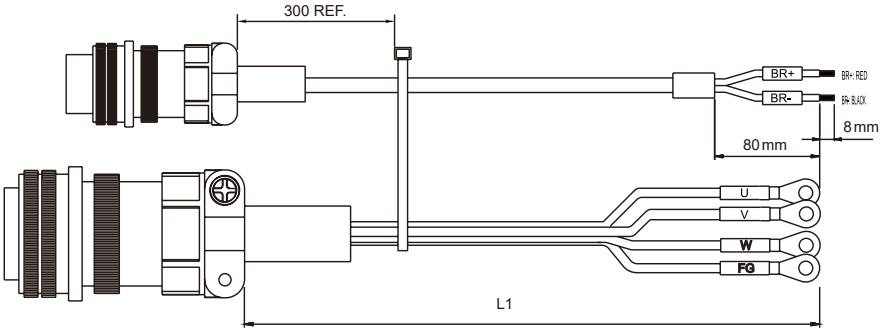
Item	Part No.	Straight	L	
			mm	inch
1	ASD-CAPW4703	3106A-32-17S	3100 ± 100	122 ± 4
		3106A-10SL-4S	3100 ± 100	122 ± 4
2	ASD-CAPW4705	3106A-32-17S	5100 ± 100	201 ± 4
		3106A-10SL-4S	5100 ± 100	201 ± 4

ASD-CAPW4603, ASD-CAPW4605



Item	Part No.	Straight	L	
			mm	inch
1	ASD-CAPW4603	3106A-32-17S	3100 ± 100	122 ± 4
2	ASD-CAPW4605	3106A-32-17S	5100 ± 100	201 ± 4

ASD-CAPW4803, ASD-CAPW4805 (with brake cable)

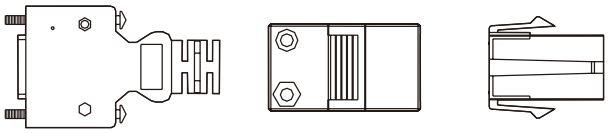


Item	Part No.	Straight	L	
			mm	inch
1	ASD-CAPW4803	3106A-32-17S	3100 ± 100	122 ± 4
		3106A-10SL-4S	3100 ± 100	122 ± 4
2	ASD-CAPW4805	3106A-32-17S	5100 ± 100	201 ± 4
		3106A-10SL-4S	5100 ± 100	201 ± 4

Optional Cables and Connectors

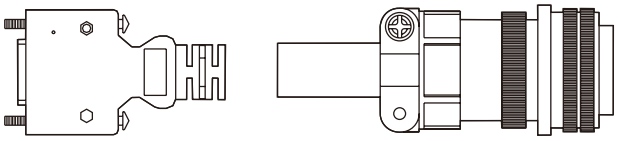
● Encoder Connectors

ASD-ABEN0000



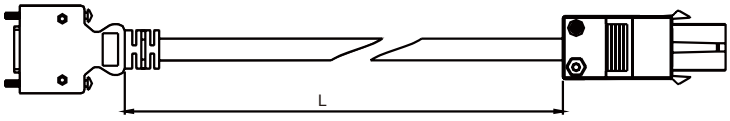
● Encoder Connectors

ASD-CAEN1000



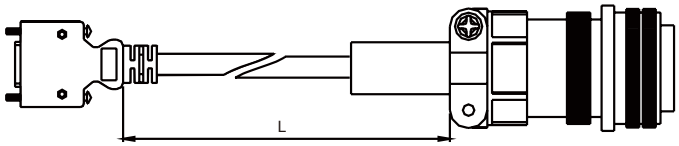
● Incremental Encoder Cables

ASD-ABEN0003 · ASD-ABEN0005



Item	Part No.	L	
		mm	inch
1	ASD-ABEN0003	3000 ± 100	118 ± 4
2	ASD-ABEN0005	5000 ± 100	197 ± 4

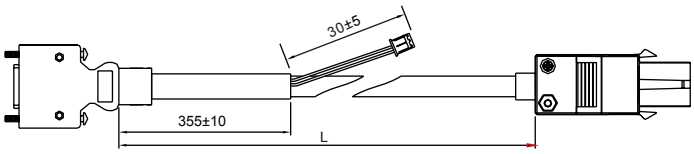
ASD-CAEN1003 · ASD-CAEN1005



Item	Part No.	Straight	L	
			mm	inch
1	ASD-CAEN1003	3106A-20-29S	3000 ± 100	118 ± 4
2	ASD-CAEN1005	3106A-20-29S	5000 ± 100	197 ± 4

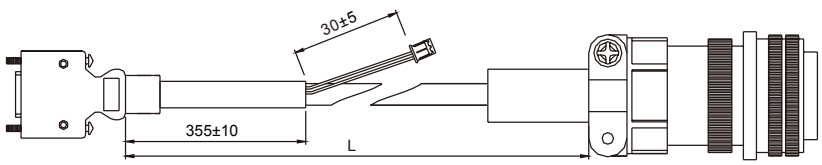
● Absolute Encoder Cables

ASD-A2EB0003 · ASD-A2EB0005



Item	Part No.	L	
		mm	inch
1	ASD-A2EB0003	3000 ± 100	118 ± 4
2	ASD-A2EB0005	5000 ± 100	197 ± 4

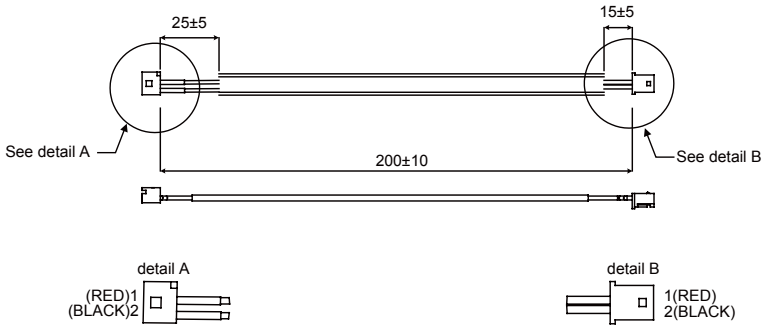
ASD-A2EB1003 · ASD-A2EB1005



Item	Part No.	L	
		mm	inch
1	ASD-A2EB1003	3000 ± 100	118 ± 4
2	ASD-A2EB1005	5000 ± 100	197 ± 4

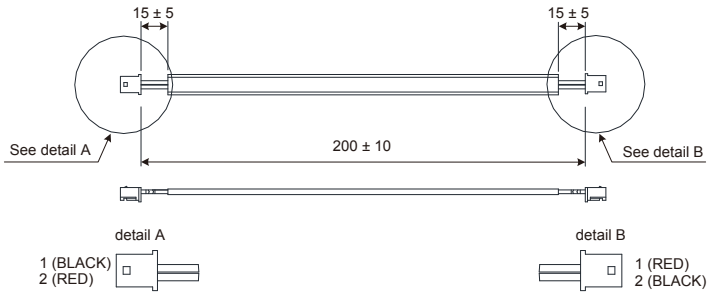
● Battery Box Cord AW (Connects to the battery side of the encoder cable) Units: mm

3864573700



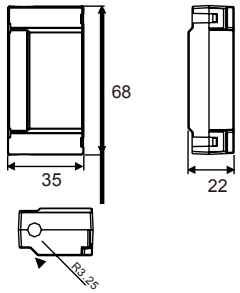
● Battery Box Cord IW (Connects to CN8) Units: mm

3864811900

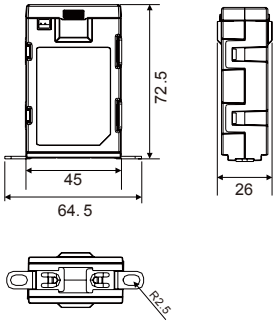


● Battery Boxes with batteries Units: mm

Single Battery Box
ASD-MDBT0100

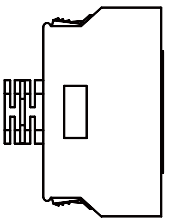


Dual Battery Box
ASD-MDBT0200



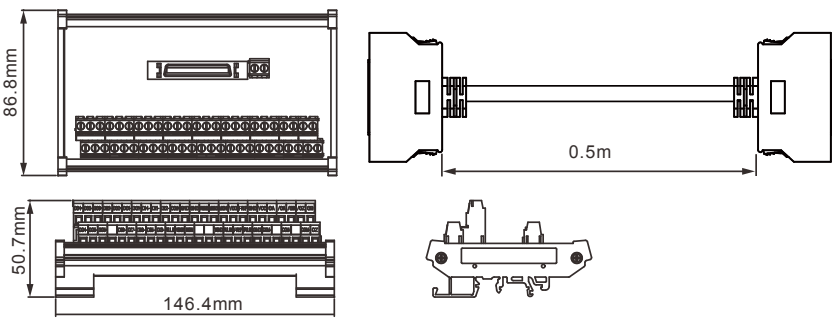
● I/O Signal Connector (CN1)

ASD-CNSC0050



● Terminal Block Module

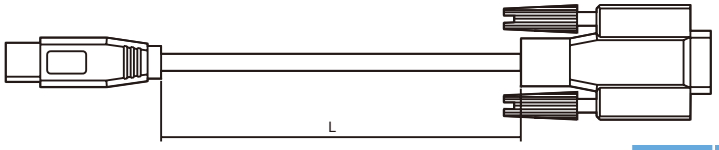
ASD-BM-50A



Optional Cables and Connectors

● RS-232 Communication Cable

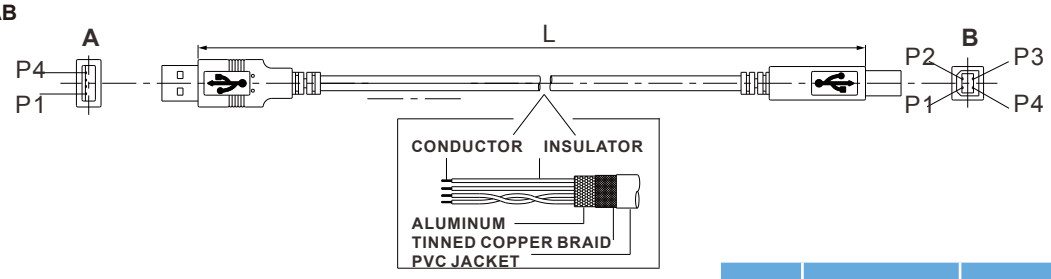
ASD-CARS0003



Item	Part No.	L	
		mm	inch
1	ASD-CARS0003	3000 ± 100	118 ± 4

● Communication Cable between Drive and Computer (for PC)

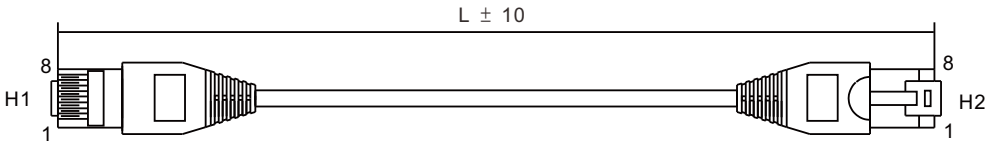
DOP-CAUSBAB



Item	Part No.	L	
		mm	inch
1	DOP-CAUSBAB	1400 ± 30	55 ± 1.2

● CANopen Communication Cable

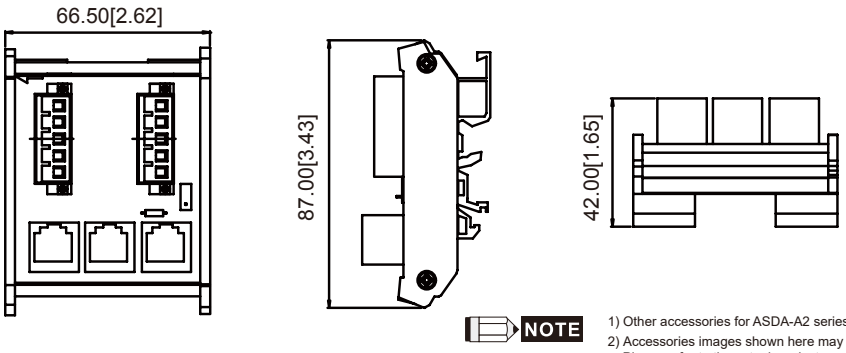
TAP-CB03 · TAP-CB05



Item	Part No.	L	
		mm	inch
1	TAP-CB03	300±10	11±0.4
2	TAP-CB05	500±10	19±0.4

● CANopen Distribution Box Units: mm[inch]

TAP-CN03

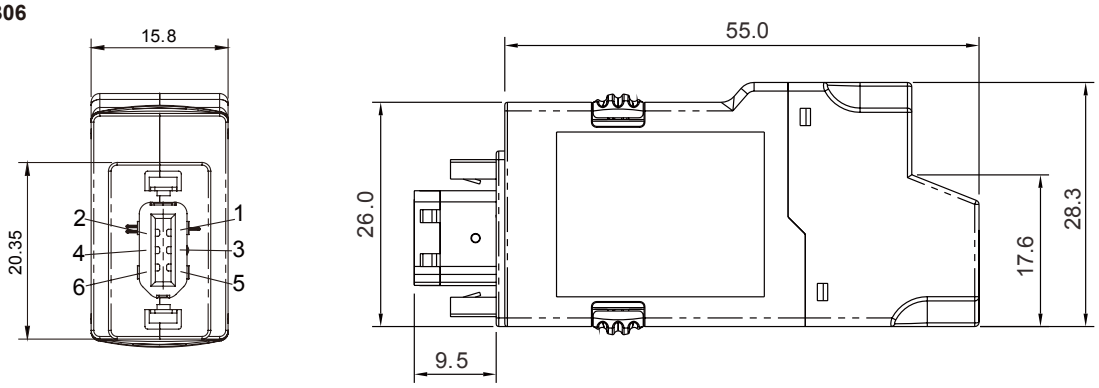


NOTE

1) Other accessories for ASDA-A2 series will be increased gradually.
2) Accessories images shown here may differ from actual product appearance. Please refer to the actual product appearance.

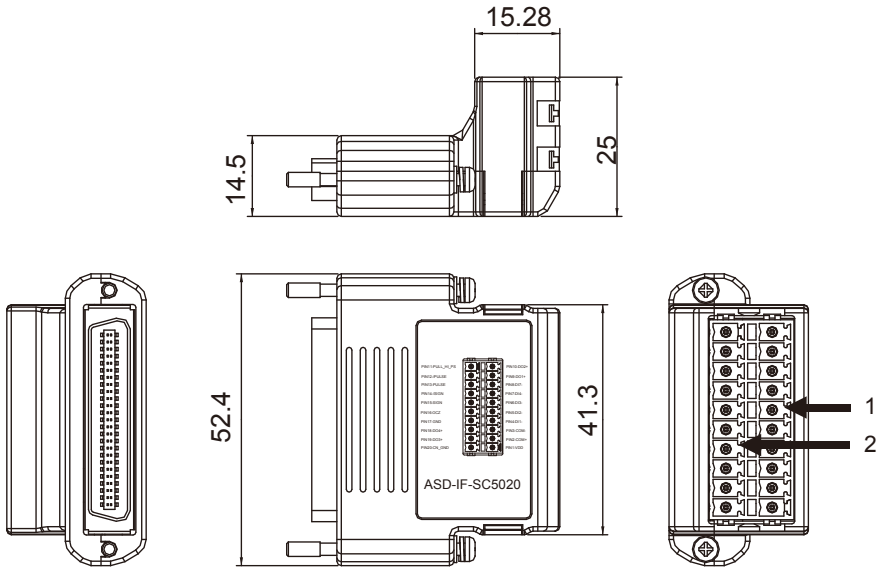
● RS-485 Connector Units: mm[inch]

ASD-CNIE0B06

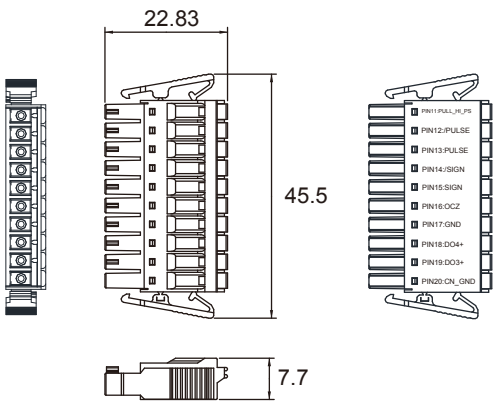


● CN1 I/O Connector Units: mm[inch]

ASD-IF-SC5020



1.



2.