Servo drive CMMT-ST

FESTO



Characteristics

At a glance Further information → cmmt-st

- Space-optimised servo drive for operating stepper motors and brushless DC motors
- For extremely economical positioning tasks and motion solutions with low power requirements up to 300 W and 800 W peak performance for 3 s
- Primary voltage from 24 ... 48 V DC
- Motor current 8 A (peak 20 A)
- 50% more compact than the smallest CMMT-AS
- Point-to-point and interpolating movements and precise positioning possible
- Direct fieldbus integration for controllers from the major manufacturers
- Auto-tuning supports easy commissioning of rotary and linear motion using mechanical systems from Festo and third-party suppliers

Product segmentation



Festo Core Range

Solves the majority of your automation tasks

With the Festo Core Range, we have selected the most important products and functions from our broad product catalogue, and added the quickest delivery. the Core Range offers you the best value with the expected high Festo quality.

- Quickest delivery, worldwide wherever, whenever
- · Expected high Festo quality
- · Easy and fast to select

Engineering tools

Further information → engineering tools



Save time with engineering tools Smart Engineering for the optimal solution. Our goal is to increase your productivity. Our engineering tools play an integral part in this. They help you size your system correctly, tap into unimagined productivity reserves and generate additional productivity along the entire value chain. In every phase of your project, from the initial contact to the modernisation of your machine, you will come across a number of different tools which will be of use to you.

Electric Motion Sizing

• Create the optimum drive package quickly and reliably. Electric Motion Sizing calculates suitable combinations of electric axis, electric motor and servo drive using just a few application details. It provides all the relevant data including the bill of materials and documentation for your selected combination. This avoids design errors and results in significantly improved energy efficiency for the system. A smooth connection to the Festo Automation Suite also makes commissioning easier for you.

Festo Automation Suite

- Parameterisation, programming and commissioning in a clear and user-friendly interface
- Optimal support for complex processes thanks to guided wizards (e.g. for initial commissioning, drive configuration, etc.)
- Quick access to the required documents and further information
- Easy integration of electric drives in the controller programming

EPLAN

• EPLAN macros for fast and reliable electrical project planning in combination with servo drives, motors and cables. This allows a high level of planning reliability, consistency of documentation, with no need to create your own symbols, graphics and master data.

Trademarks

The following are the registered trademarks of the respective trademark owner in certain countries:

- PROFINET®
- EtherCat[®]
- EtherNet/IP®
- Modbus[®]

Characteristics

Bus protocol/activation

- Supported bus protocols: EtherCAT®; EtherNet/IP; PROFINET
- Modbus TCP is available as an additional protocol with all Ethernet/IP devices

[MP] Multiprotocol



EtherNet/IP

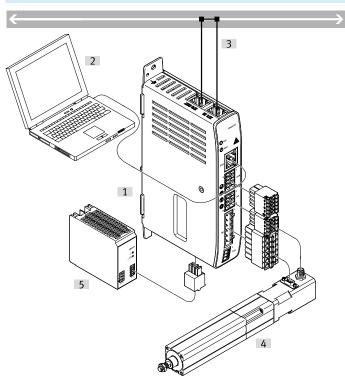




Safety function

- Safe torque off (STO) up to SIL3/Cat. 3 PL e
- Safe stop 1 (SS1) when using a suitable external safety relay unit and suitable circuitry for the servo drive

Overview



- [1] Servo drive
- [2] PC with Ethernet connection
- [3] Bus/network
- [4] Axis with motor
- [5] Power supply unit for logic and load supply

Servo drive CMMT-ST

Type code

001	Series	
CMMT	Motor controller	
002	Motor type	
ST	Stepper motor ST	
003	Nominal current	
C8	8 A	

004	Nominal input voltage	
1C	24 - 48 V DC	
005	Bus protocol/activation	
MP	Multiprotocol	
006	Safety function	
S0	Basic safety	

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Datasheet

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Mounting plate, attached with screws
With H-rail
Green/yellow/red LED
Cascade controller
P position controller
PI speed controller
PI current regulator for F or M
Profile operation with record and direct mode
Interpolated mode via fieldbus
Synchronised operating modes
Homing
Setting-up
Autotuning
Open-loop operation
Field-oriented closed-loop control
Position resolution 24 bit/rev
Real-time data acquisition
2x input capture (x, v, F)
2x output trigger (x, v, F)
1x position encoder input
Sampling rate 16 or 20 kHz
PWM with 16 or 20 KHz
Via software
I ² t monitoring
Temperature monitoring
Current monitoring
Voltage failure detection
Following error monitoring
Software end-position detection
Free convection, Vertical
350 g

Bus protocol					
Fieldbus link	EtherCAT, EtherNet/IP, Modbus/TCP, PROFINET				
Fieldbus interface, function	Bus connection incoming/outgoing, EtherCAT® slave, PROFINET slave, Fieldbus				
Process interfacing	I/O mode for 256 positioning records				
	Interpolated mode CSP				
	Interpolated mode CST				
	Interpolated mode CSV				
Communication profile	CiA402				
	CoE (CANopen over EtherCAT®)				
	EoE (Ethernet over EtherCAT®)				
	FoE (File over EtherCAT®)				
	PROFIdrive				
Field bus interface, transmis-	100 Mbit/s				
sion rate					
Field bus, connection type	2x socket				
Field bus, connection system	RJ45				

Datasheet

Electrical data

Output voltage class AC	0 V up to input voltage
Nominal output current	8 A
Nominal current per phase, ef-	8 A
fective	
Peak current per phase, effec-	20 A
tive	
Max. peak current duration	3 s
Controller nominal output	300 W
Maximum output	800 W
Output frequency	600 Hz
Max. length of motor cable	25 m
without external mains filter	
Load voltage range DC	24 V, 48 V
Max. intermediate circuit volt-	60 V
age DC	
Nominal voltage for logic pow-	24 V
er supply DC	
Current consumption of logic	1A
power supply without clamp-	
ing brake	
Current consumption for logic	2 A
supply with parking brake	
Max. output current of holding	1 A
brake	
Max. voltage drop from logic	1V
supply to brake output	

Interfaces

Ethernet interface, function	Parameterisation and commissioning
Ethernet interface, protocol	TCP/IP
Encoder interface, function	BiSS-C
	Incremental encoder
Number of digital logic inputs	6
Number of high-speed logic in-	2
puts	
Time resolution of high-speed	1 μs
logic inputs	
Features of digital logic out-	Not galvanically isolated
puts	
Switching logic for inputs	PNP (positive switching)
Specification logic input	Based on IEC 61131-2, type 3
Working range of logic input	-3 30 V
Number of high-speed switch-	2
ing outputs	
Time resolution of high-speed	1 μs
switching outputs	
Switching logic for outputs	PNP (positive switching)
Max. current digital logic out-	100 mA
puts	
Number of floating switching	1
outputs	
Max. current of the floating	100 mA
switching outputs	

Braking resistor

Brake resistor, external	6 0hm
Max. continuous output of the	490 W
external braking resistor (IEC)	

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Datasheet

Safety characteristics

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Safety function	Safe torque off (STO)
	Safe stop 1 time controlled (SS1-t)
Performance Level (PL)	STO/Cat. 3, PLd (EC motor without diagnostics)
	STO/Cat. 3, PLe (stepper motor/EC motor with diagnostics)
Safety Integrity Level (SIL)	STO/SIL 2/SILCL 2 (EC motor without diagnostics)
	STO/SIL 3/SILCL 3 (stepper motor/EC motor with diagnostics)
Certificate issuing authority	German Technical Control Board (TÜV) Rheinland 01/205/5696.00/19, German Technical Control Board (TÜV) Rheinland UK Ltd. 01/205U/5696.00/22, UL
	E331130
Proof test interval	STO/20 a (stepper motor/EC motor without diagnostics)
	STO: 0.25 a (EC motor with diagnostics)
Hardware fault tolerance	1

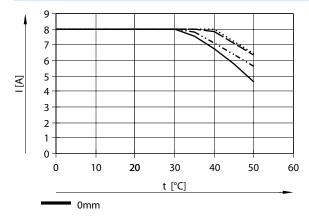
Operating and environmental conditions

operating and environmen					
Degree of protection	IP20				
Ambient temperature	50℃				
Storage temperature	-25 55℃				
Note on ambient temperature	Observe the derating regarding the mounting clearance and output current.				
Relative air humidity	5 - 90%, Non-condensing				
Protection class					
Overvoltage category	I				
Pollution degree	2				
Max. installation height	2,000 m				
Shock resistance	Shock test with severity level 1 to FN 942017-5 and EN 60068-2-27				
	As per EN 60068-2				
Vibration resistance	Transport application test with severity level 1 to FN 942017-4 and EN 60068-2-6				
To EN 61800-5-1: frequency 10-57 Hz, amplitude 0.075 mm, frequency 57-150 Hz, 1 g					
	As per EN 60068-2				
CE mark (see declaration of	EU EMC Directive				
conformity) 1)	To EC Machinery Directive				
	In accordance with EU RoHS Directive				
CE marking (see declaration of	To UK instructions for EMC				
conformity) ²⁾	To UK regulations for machines				
	To UK RoHS instructions				
Approval	RCM trademark				
	c UL us listed (OL)				
KC mark	KC-EMV				
LABS (PWIS) conformity	VDMA24364 zone III				
Note on materials	RoHS-compliant RoHS-compliant				

¹⁾ More information www.festo.com/catalogue/cmmt-st \rightarrow Support/Downloads.

Derating required

10mm 15mm

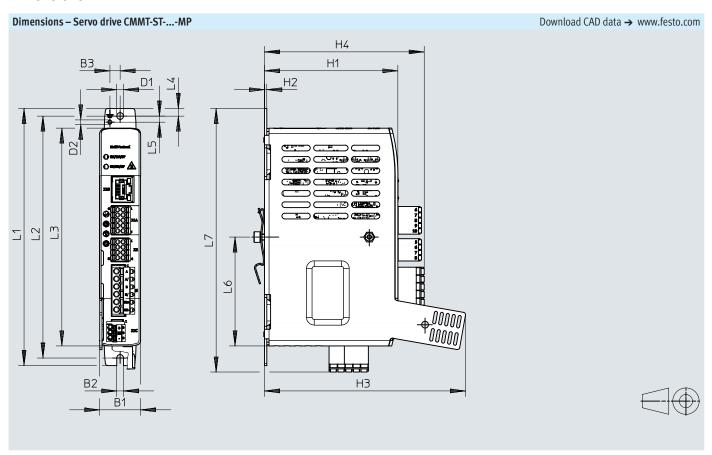


Mounting clearances may be required at output currents > 4.6 A to ensure the device reaches at least the specified service life. The mounting clearances required depend on the ambient temperature t and the output current I.

Mounting clearances from 0 mm are possible for a device combination consisting of several servo drives CMMT-ST. The following characteristic curves show the maximum permissible effective currents for the lateral mounting clearances 0 mm, 3 mm, 10 mm and 15 mm.

²⁾ More information www.festo.com/catalogue/cmmt-st \rightarrow Support/Downloads.

Dimensions



	B1	B2	В3	D1 Ø	D2	H1	H2	H3
CMMT-ST-C8-1C-MP	27	4, 5	6,8	4,5	M3x0,5	88,3	1,5	133
	H4	L1	L2	L3	L4	L5	L6	L7
CMMT-ST-C8-1C-MP	105,7	170	160	144	5	4	72	174,3

Ordering data

Ordering data								
	Type of mounting 1)	Field bus, protocol	Part no.	Туре				
	Mounting plate, attached with screws, With H-rail	EtherCAT [®] , EtherNet/IP, PROFINET IRT	★ 8163946	CMMT-ST-C8-1C-MP-S0				

¹⁾ The plug assortment NEKM is included in the scope of delivery of the servo drive.

Servo drive CMMT-ST

Accessories

Assortment of plugs NEKM						
	Description	Part no.	Туре			
	CMMT-STMP	8173466	NEKM-C-23			

Connecting cable NEBC							
	Description	Part no.	Туре				
	Patch line for the daisy chain connection of the bus interfaces X19A/B, Not included in the scope of delivery of the servo drive, Ethernet category Cat 5e	★ 8082383	NEBC-R3G8-KS-0.2-N-S-R3G8-ET				

Braking resistor CACR							
	Resistance value	Brake resistance rating	Product weight	Part no.	Туре		
	6 Ohm	60 W	150 g	8189339	CACR-LE2-6-W60-V		

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